

20 points) 1. For the following system of ordinary differential equations, (a) find the general solutions; (b) classify the types (saddle, node (source or sink), spirals) and the stability; (c) draw a few trajectories

$$(1) \quad x' = \begin{pmatrix} -1 & 4 \\ 1 & -1 \end{pmatrix} x,$$

$$(2) \quad x' = \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix} x$$

(1)  $A = \begin{pmatrix} -1 & 4 \\ 1 & -1 \end{pmatrix}$

$$\det(A - \lambda I) = (\lambda + 1)^2 - 4 = 0$$

$$\lambda_1 = 1, \quad \lambda_2 = -3$$

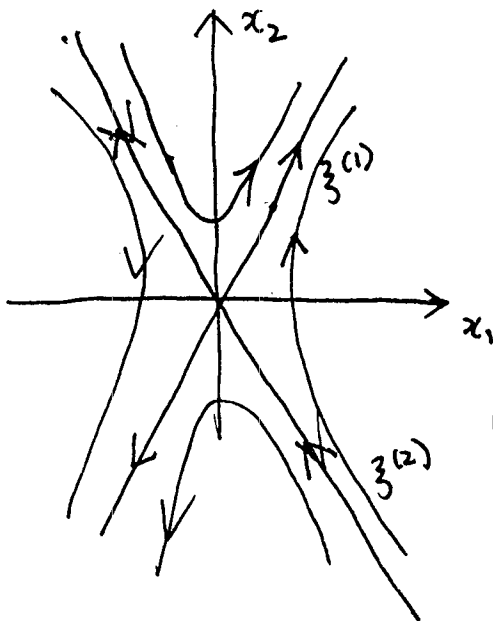
For  $\lambda_1 = 1$ ,  $\zeta^{(1)} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

(+6)

For  $\lambda_2 = -3$ ,  $\zeta^{(2)} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$

$$x = c_1 e^t \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

$\lambda_1 > 0 > \lambda_2$  : saddle unstable } (+2)



(+2)

(2)  $A = \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}$

$$\det(A - \lambda I) = (\lambda + 2)^2 - 1 = 0$$

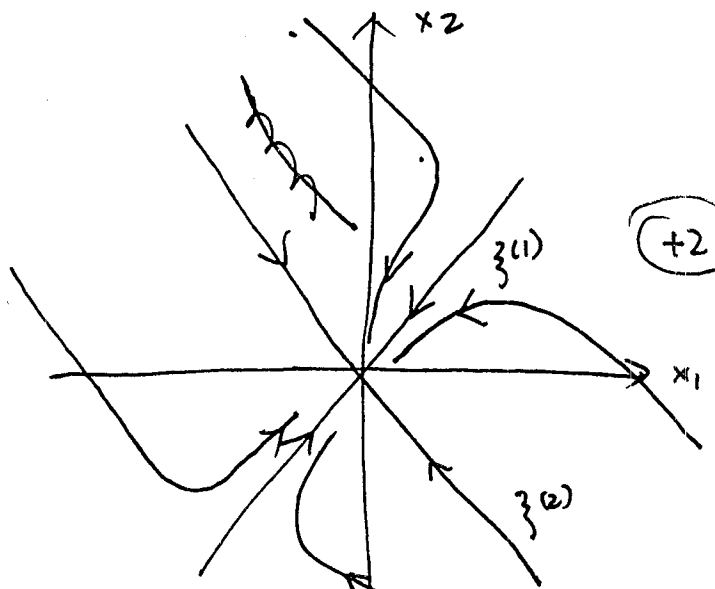
$$\lambda_1 = -1, \quad \lambda_2 = -3$$

(+6)

$$\zeta^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \zeta^{(2)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$x = c_1 e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$\lambda_1 < 0, \lambda_2 < 0$  : sink, stable } (+2)



(+2)

$$t \rightarrow +\infty, \quad x \approx e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$t \rightarrow -\infty, \quad x \approx e^{-3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

(10 points) 2. Find the general solutions to the following system of ordinary differential equations

$$x' = \begin{pmatrix} 3 & 1 \\ -5 & -1 \end{pmatrix} x$$

(+5)  $A = \begin{pmatrix} 3 & 1 \\ -5 & -1 \end{pmatrix}$   $\det(A - \lambda I) = \det \begin{pmatrix} 3-\lambda & 1 \\ -5 & -1-\lambda \end{pmatrix}$   
 $= (\lambda+1)(\lambda-3) + 5 = \lambda^2 - 2\lambda + 2 = 0$   
 $\lambda = 1 \pm i$   
 $\lambda_1 = 1 + i,$   $\begin{pmatrix} 3-(1+i) & 1 \\ -5 & -1-(1+i) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0,$   $\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{pmatrix} 1 \\ -2+i \end{pmatrix}$

$e^{(1+i)t} \begin{pmatrix} 1 \\ -2+i \end{pmatrix} = \begin{pmatrix} e^t \cos t + i e^t \sin t \\ (-2+i)(e^t \cos t + i e^t \sin t) \end{pmatrix}$

$= \begin{pmatrix} e^t \cos t \\ -2e^t \cos t - e^t \sin t \end{pmatrix} + i \begin{pmatrix} e^t \sin t \\ e^t \cos t - 2e^t \sin t \end{pmatrix}$

(+5)  $x = c_1 \begin{pmatrix} e^t \cos t \\ -2e^t \cos t - e^t \sin t \end{pmatrix} + c_2 \begin{pmatrix} e^t \sin t \\ e^t \cos t - 2e^t \sin t \end{pmatrix}$

(5 points) 3. Use the method of undetermined coefficients to obtain the general solutions of

$$x' = \begin{pmatrix} -1 & -2 \\ 3 & 4 \end{pmatrix} x + e^t \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

1)  $A = \begin{pmatrix} -1 & -2 \\ 3 & 4 \end{pmatrix}$

$$\det(A - \lambda I) = (\lambda + 1)(\lambda - 4) + 6 = \lambda^2 - 3\lambda + 2 = 0$$

$$\lambda_1 = 1, \lambda_2 = 2$$

For  $\lambda = \lambda_1$ ,  $z^{(1)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

(+4)

For  $\lambda = \lambda_2$ ,  $z^{(2)} = \begin{pmatrix} 2 \\ -3 \end{pmatrix}$

2) So  $x_h = c_1 e^t \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 2 \\ -3 \end{pmatrix}$

2)  $x_p = \vec{a} t e^t + \vec{b} e^t$  — (3)

$$x_p' = \vec{a} t e^t + (\vec{a} + \vec{b}) e^t$$

$$= A \vec{a} t e^t + A \vec{b} e^t + e^t \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$A \vec{a} = \vec{a}$$

$$A \vec{b} = \vec{a} + \vec{b} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

(3)

(+8)

(4)  $\vec{a} = k \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$$A \vec{b} - \vec{b} = k \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} -2 & -2 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = k \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\left. \begin{aligned} -2b_1 - 2b_2 &= k - 1 \\ 3b_1 + 3b_2 &= -k \end{aligned} \right\} \Rightarrow 3(k - 1) = -2k \Rightarrow k = \frac{3}{5}$$

$$-2b_1 - 2b_2 = -\frac{2}{5} \Rightarrow b_1 + b_2 = \frac{1}{5}, b_1 = \frac{1}{5}, b_2 = 0$$

$$x_p = \frac{3}{5} \begin{pmatrix} 1 \\ -1 \end{pmatrix} t e^t + \begin{pmatrix} \frac{1}{5} \\ 0 \end{pmatrix} e^t$$

3)  $x = x_h + x_p$

(+1)

(15 points) 4. Use the method of variation of parameters to obtain the general solutions of

$$x' = \begin{pmatrix} 2 & -1 \\ 4 & -2 \end{pmatrix} x + \begin{pmatrix} 0 \\ t^{-2} \end{pmatrix}, t > 0.$$

▷  $A = \begin{pmatrix} 2 & -1 \\ 4 & -2 \end{pmatrix}$

$$\det(A - \lambda I) = \lambda^2 - 4 + 4 = 0, \lambda = 0$$

$$\lambda = 0 \Rightarrow z^{(1)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$x^{(1)} = e^{at} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$x^{(2)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t + \eta$$

$$A\eta = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad \begin{pmatrix} 2 & -1 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$2\eta_1 - \eta_2 = 1 \Rightarrow \eta = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$x^{(2)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} t \\ 2t-1 \end{pmatrix}$$

$$\Psi = \begin{pmatrix} 1 & t \\ 2 & 2t-1 \end{pmatrix}$$

2)  $x_p = \Psi \vec{c}(t) \Rightarrow \Psi \vec{c}' = \begin{pmatrix} 0 \\ t^{-2} \end{pmatrix}$

$$c_1' + t c_2' = 0$$

$$2c_1' + (2t-1)c_2' = t^{-2}$$

$$c_1' = -t c_2' = +t^{-1} \Rightarrow c_1 = \ln t$$

$$\Rightarrow -c_2' = t^{-2} \Rightarrow c_2 = t^{-1}$$

So  $x_p = \begin{pmatrix} 1 & t \\ 2 & 2t-1 \end{pmatrix} \begin{pmatrix} \ln t \\ t^{-1} \end{pmatrix}$

3)  $x = \begin{pmatrix} 1 & t \\ 2 & 2t-1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} + \begin{pmatrix} 1 & t \\ 2 & 2t-1 \end{pmatrix} \begin{pmatrix} \ln t \\ t^{-1} \end{pmatrix}$

(+7)

(+7)

(+1)

(10 points) 5. Compute the Laplace transform of

$$f(t) = \begin{cases} 1, & 0 \leq t < 2\pi \\ \cos t, & 2\pi \leq t < +\infty \end{cases}$$

Hint:  $\cos(t) = \cos(t - 2\pi)$ .

(List of Laplace transform formulas is attached at the last page)

$$\begin{aligned} f(t) &= 1 + (\cos t - 1) u_{2\pi}(t) \\ &= 1 + (\cos(t-2\pi) - 1) u_{2\pi}(t) \end{aligned} \quad \Bigg| \quad (+5)$$

$$\begin{aligned} \mathcal{L}[f](s) &= \frac{1}{s} + e^{-2\pi s} \left[ \frac{s}{s^2+1} - \frac{1}{s} \right] \\ &= \frac{1}{s} - \frac{1}{s(s^2+1)} e^{-2\pi s} \end{aligned} \quad \Bigg| \quad (+5)$$

5 points) 6. Use the method of Laplace transform to solve

$$y'' + y = g(t), \quad y(0) = 0, y'(0) = 0$$

where

$$g(t) = \begin{cases} -1, & 0 \leq t < 2 \\ t-3, & 2 \leq t < 3, \\ 0, & 3 \leq t < +\infty \end{cases}$$

(List of Laplace transform formulas is attached at the last page)

$$g(t) = -1 + (t-2)u_2 - (t-3)u_3$$

— (3)

$$L[g](s) = -\frac{1}{s} + e^{-2s} \frac{1}{s^2} - e^{-3s} \frac{1}{s^2}$$

— (3)

$$s^2 Y + Y = L[g](s)$$

$$Y(s) = -\frac{1}{s(s^2+1)} + \frac{1}{s^2(s^2+1)} (e^{-2s} - e^{-3s})$$

— (2)

$$\frac{1}{s(s^2+1)} = \frac{1}{s} - \frac{s}{s^2+1}, \quad L^{-1}\left[\frac{1}{s(s^2+1)}\right] = 1 - \cos t$$

— (2)

$$\frac{1}{s^2(s^2+1)} = \frac{1}{s^2} - \frac{1}{s^2+1}, \quad L^{-1}\left[\frac{1}{s^2(s^2+1)}\right] = t - \sin t$$

— (2)

$$y(t) = L^{-1}[Y(s)] = -1 + \cos t + (t-2 - \sin(t-2))u_2(t) - (t-3 - \sin(t-3))u_3(t)$$

(3)

(15 points) 7. Use the method of Laplace transform to solve

$$y'' - 3y' + 2y = \delta(t - 2), \quad y(0) = 0, \quad y'(0) = 1$$

(List of Laplace transform formulas is attached at the last page)

$$s^2 Y(s) - sy(0) - y'(0) - 3(sY(s) - y(0)) + 2Y(s) = e^{-2s}$$

$$(s^2 - 3s + 2)Y(s) = 1 + e^{-2s}$$

$$Y(s) = \frac{1}{s^2 - 3s + 2} + \frac{1}{s^2 - 3s + 2} e^{-2s}$$

$$\frac{1}{s^2 - 3s + 2} = \frac{1}{(s-1)(s-2)} = \frac{a}{s-1} + \frac{b}{s-2} = \frac{-1}{s-1} + \frac{+1}{s-2}$$

$$\mathcal{L}^{-1}\left[\frac{1}{s^2 - 3s + 2}\right] = -e^t + e^{2t}$$

$$\text{so } y(t) = \mathcal{L}^{-1}[Y(s)] = \underbrace{-e^t + e^{2t}}_{(2)} + \underbrace{(-e^{t-2} + e^{2(t-2)})}_{(+4)} u_2(t)$$