

10/15/2019

Lecture 12

Last time: • Span, basis, dimension of vector subspaces.

• we started talking about the four fundamental subspaces of a matrix.

$$N(A), R(A), N(A^T), R(A^T).$$

①. $N(A) = \{x: Ax = \vec{0}\}$.

To find a basis for $N(A)$:

→ solve system $Ax = \vec{0}$

↔ solve $\text{ref}(A)x = \vec{0}$

Example: $C = \begin{bmatrix} 1 & 3 & 3 & 10 & 0 \\ 2 & 6 & -1 & -1 & 0 \\ 2 & 3 & 1 & 4 & 1 \end{bmatrix} \rightsquigarrow \text{ref}(C) = \begin{bmatrix} 1 & 3 & 0 & 1 & 0 \\ 0 & 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 3 & 0 & 1 & 0 \\ 0 & 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \vec{0}$$

→ $x_2 = s, x_4 = t$ free variables

$$\begin{aligned} x_1 &= -3s - t \\ x_3 &= -3t \\ x_5 &= 0 \end{aligned}$$

$$x = s \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ -3 \\ 1 \\ 0 \end{bmatrix}$$

$$N(C) = \left\{ s \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ -3 \\ 1 \\ 0 \end{bmatrix} : s, t \in \mathbb{R} \right\}$$

Then, $\left\{ \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ -3 \\ 1 \\ 0 \end{bmatrix} \right\}$ is a basis for $N(C)$!

Fact: This is always the case.

②. $R(A) := \{Ax: x \in \mathbb{R}^n\}$ the range of A / column space of A.

let $A = [a_1 | a_2 | \dots | a_n]$, $a_j \in \mathbb{R}^m$

Then, recall that $Ax = x_1 a_1 + x_2 a_2 + \dots + x_n a_n$, a linear combination

Thus, $R(A) = \text{span}\{a_1, a_2, \dots, a_n\}$.

How do we find a basis for $R(A)$?

Equivalently, we need to find a basis for $\text{span}\{a_1, \dots, a_n\}$

Equivalently, we need to find the largest number of linearly independent columns of A .

\Leftrightarrow We need to find the pivot columns of A . Why?

Recall: • Pivot columns of A are linearly independent

$$Ax = \vec{0} \Leftrightarrow \text{rref}(A)x = \vec{0}$$

e.g. ~~$\begin{bmatrix} a_1 & a_2 & a_3 & a_4 & a_5 \\ x_1 & x_2 & x_3 & x_4 & x_5 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{cases} x_1 = 0 \\ x_3 = 0 \\ x_5 = 0 \end{cases}$~~

~~$x_1 a_1 + x_3 a_3 + x_5 a_5 = \vec{0} \Leftrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \\ x_5 \end{bmatrix} = \vec{0}$~~

$$\begin{bmatrix} 1 & 3 & 3 & 10 & 0 \\ 2 & 8 & -1 & -1 & 0 \\ 1 & 3 & 1 & 4 & 1 \end{bmatrix} x = \vec{0} \Leftrightarrow \begin{bmatrix} 1 & 0 & 0 & 4 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} x = \vec{0}$$

$x_1 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \vec{0} \Leftrightarrow x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \vec{0}$

$\Rightarrow x_1 = x_2 = x_3 = 0$

• All other columns can be expressed as linear combinations \rightarrow l.i.

combinations of the pivot columns:

~~$\begin{bmatrix} 3 \\ 8 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$~~

$$\begin{bmatrix} 3 \\ 8 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$c_2 = 3c_1$$

$$c_4 = c_1 + 3c_3$$

Definition: $\dim(R(A))$ is called the rank of A and is denoted by $\text{rank}(A)$.

Facts: (1) $\text{rank}(A) = \# \text{ pivots in rref}(A)$.
 (2) $\text{rank}(A) \leq \min(m, n)$.
 (3) $\dim(N(A)) = n - \# \text{ pivots in rref}(A)$.

$R(A) \subseteq \mathbb{R}^m$
 $\# \text{ pivots} \leq \# \text{ cols.} = \# \text{ rows.}$

$\Rightarrow \boxed{\dim(N(A)) = n - \text{rank}(A)}$ = # free variables
 The "rank-nullity theorem".

Bases for $N(A^T)$, $R(A^T)$:

Facts: Let A be $m \times n$. Then,

- (1) A^T is $n \times m$.
- (2) Columns of A^T are rows of A .

(3) ~~Let $rref(A) = R$~~ There exists an invertible matrix

Q s.t. ~~$rref(A) = Q^{-1}A$~~
 $rref(A) = Q^{-1}A$
 $\Rightarrow \underbrace{Q^{-1}}_{=:L} rref(A) = A$

$\Leftrightarrow A = L rref(A)$ and L is invertible.

$A^T = (rref(A))^T L^T$

Claim: If L is invertible so is L^T

Exercise: Prove this claim

Theorem: $R(A^T) = R((rref(A))^T)$

Remark: $(rref(A))^T \neq rref(A^T)$!!

Proof of the Theorem:

$$R(A^T) = \{A^T x : x \in \mathbb{R}^m\} = \{(rref(A))^T \underbrace{L^T x}_{y \in \mathbb{R}^m} : x \in \mathbb{R}^m\}$$

$$= \{(rref(A))^T y : y \in \mathbb{R}^m\}$$

Q : Is it true that $\{L^T x : x \in \mathbb{R}^m\} = \mathbb{R}^m$? I.e., can we find

A: yes. In fact given $y \in \mathbb{R}^m$, $x = (L^T)^{-1}y$ and

$$y = L^T x.$$

Therefore, $\mathcal{R}(A^T) = \{(\text{rref}(A))^T y : y \in \mathbb{R}^m\} = \mathcal{R}((\text{rref}(A))^T)$.

Example: let C be as before. Find $\mathcal{R}(C^T)$.

Solution: $\mathcal{R}(C^T) = \mathcal{R}((\text{rref}(C))^T)$

$$\text{rref}(C) = \begin{bmatrix} 1 & 3 & 0 & 1 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

$$\Rightarrow \mathcal{R}(C^T) = \text{span} \left\{ \begin{bmatrix} 1 \\ 3 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

a basis for C^T .

~~Example~~: let $A = \begin{bmatrix} 1 & 3 & 4 & 5 & 1 \\ 2 & 2 & 2 & 2 & 2 \\ 1 & 2 & 2 & 4 & 7 \end{bmatrix}$.

~~(a). What is $\text{rank}(A)$?~~

~~(b). $\dim(\mathcal{N}(A))$? $\dim(\mathcal{R}(A))$?~~

~~$\dim(\mathcal{N}(A^T))$? $\dim(\mathcal{R}(A^T))$?~~

4. $\mathcal{N}(A^T)$. A^T is $n \times m$

First, note that $\dim(\mathcal{N}(A^T)) = m - \dim(\mathcal{R}(A^T))$

For finding a basis, it might be easiest to find $\text{rref}(A^T)$.

Recall that $A = L \text{rref}(A)$ and $A^T = (\text{rref}(A))^T L^T$.

$$\text{rref}(A) = QA$$

$$(\text{rref}(A))^T = A^T Q^T$$

Note: Last $m - \text{rank}(A)$ columns of $(\text{rref}(A))^T$ are 0

the last $m - \text{rank}(A)$ columns of Q^T are in $\mathcal{N}(A^T)$.

They are also independent \rightarrow they are a basis for $N(A^T)$.

Example: let $A = \begin{bmatrix} 1 & 3 & 4 & 5 & 1 \\ 2 & 2 & 2 & 2 & 2 \\ 1 & 2 & 2 & 4 & 7 \end{bmatrix}$

- (a) Find $\text{rank}(A)$.
- (b) $\dim(N(A)) = ?$ $\dim(R(A)) = ?$
 $\dim(N(A^T)) = ?$ $\dim(R(A^T)) = ?$
- (c) Find a basis for $N(A)$.
- (d) " " " $R(A)$
- (e) " " " $R(A^T)$.

Solution: First, calculate $\text{rref}(A)$:

$$A \rightsquigarrow \text{rref}(A) = \begin{bmatrix} 1 & 0 & 0 & -2 & -5 \\ 0 & 1 & 0 & 5 & 18 \\ 0 & 0 & 1 & -2 & 12 \end{bmatrix}$$

(a) $\text{rank}(A) = 3$

(b) $\dim(N(A)) = n - \text{rank}(A) = 5 - 3 = 2$.

$\dim(R(A)) = 3$ $\dim(R(A^T)) = 3$

$\dim(N(A^T)) = 3 - \dim(R(A^T)) = 0$.

(c).

$$\begin{bmatrix} \textcircled{1} & 0 & 0 & -2 & -5 \\ 0 & \textcircled{1} & 0 & 5 & 18 \\ 0 & 0 & \textcircled{1} & -2 & 12 \end{bmatrix}$$

$x_4 = s$

$x_5 = t$

$x_1 = 2s + 5t$

$x_2 = -5s - 18t$

$x_3 = 2s - 12t$

$$\Rightarrow N(A) = \left\{ s \begin{bmatrix} 2 \\ -5 \\ 2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 5 \\ -18 \\ -12 \\ 0 \\ 1 \end{bmatrix} \right\}$$

↙ ↘
basis

(d). $\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} \right\}$

(e). $R(A^T) = R((\text{rref}(A))^T)$

$= \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$