

Math 405/607E: Numerical Solution of Differential Equations  
Final Exam, December 2016

Family Name: \_\_\_\_\_ Given Name: \_\_\_\_\_

Signature: \_\_\_\_\_ Student Number: \_\_\_\_\_

Course: 405 or 607E: \_\_\_\_\_

Question:	1	2	3	4	5	6	7	8	9	Total
Points:	16	8	6	6	6	6	8	6	8	70
Score:										

## Instructions

- You have 150 minutes to write this exam.
- This exam contains 5 pages including this cover page. Ensure you have all the pages.
- Some parts of this exam are multiple choice: for these you do not need to show any calculations unless specifically asked.
- For other problems, please write your answers on an exam booklet.
- For short answer questions, write solutions to the questions in the space provided below each question. If you require more space, label clearly where you have written your solution.
- No aids are allowed. No notes, books, programmable calculators etc. Simple calculators are acceptable, but should not be needed.

16 marks

1. (a) True False A singular matrix has a zero condition number.
- True False A *composite quadrature method* is a method that adaptively chooses the best grid to approximate an integral.
- True False The Barycentric Lagrange formula is one possible technique for evaluating an interpolating polynomial.
- True False Radial basis function methods approximate a function  $u(\vec{x})$  as a weighted sum of radial functions:  $u(\vec{x}) = \sum_i^N w_i \phi(\|\vec{x} - \vec{x}_i\|_2)$ .
- True False Even if the grid points  $x_0, x_1, \dots, x_n$  are not distinct, the interpolating polynomial of degree  $n$  is still unique.
- True False When doing spectral methods, the second derivative can be computed in the “frequency domain” by  $\widehat{u_{xx}} = k^2 \hat{u}$ .
- (b) A numerical method for a differential equation is \_\_\_\_\_ if the global error approaches zero in the limit as  $h \rightarrow 0$ .
- (c) A numerical method is *consistent* with a differential equation if the \_\_\_\_\_ goes to zero as  $h \rightarrow 0$ .
- (d) A well- \_\_\_\_\_ *problem* is a problem where small perturbations do not have a large effect on the exact solution.
- (e) An \_\_\_\_\_ numerical method is one that is highly sensitive to perturbation.
- (f) State (or derive if you wish) the *variational problem* corresponding to the Poisson problem  $-u_{xx} = f(x)$  on the domain  $x \in [a, b]$ .
- (g) Sketch a “hat function” appropriate for use as one of the *basis functions* in a finite element method based on piecewise linear test functions. Label your diagram.
- (h) Give the cardinal polynomial  $L_{n,k}(x)$

8 marks

2. The following matrix problems approximate the differential equation  $u_{xx} = f$ . The first and last row of each matrix is missing; fill in to approximate the indicated boundary conditions. You may need to add values on the right-hand side as well.

Here  $\vec{u}$  is a vector of point-wise values of  $u$  sampled on the interval  $[a, b]$  (the grid is not specified and could be different in each part).

- (a) **Periodic** with  $u(a) = u(b)$ :

$$\frac{1}{h^2} \begin{bmatrix} \text{-----} \\ 1 & -2 & 1 & & & \\ & 1 & -2 & 1 & & \\ & & \ddots & \ddots & \ddots & \\ & & & 1 & -2 & 1 \\ \text{-----} & & & & 1 & -2 & 1 \\ \text{-----} \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ u_2 \\ \vdots \\ u_{N-2} \\ u_{N-1} \\ u_N \end{bmatrix} = \begin{bmatrix} \text{-----} \\ f_1 \\ f_2 \\ \vdots \\ f_{N-2} \\ f_{N-1} \\ \text{-----} \end{bmatrix}$$

- (b) **Dirichlet** with  $u(a) = 0$  and  $u(b) = 6$ :

$$\frac{1}{h^2} \begin{bmatrix} \text{-----} \\ 1 & -2 & 1 & & & \\ & 1 & -2 & 1 & & \\ & & \ddots & \ddots & \ddots & \\ & & & 1 & -2 & 1 \\ \text{-----} & & & & 1 & -2 & 1 \\ \text{-----} \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ u_2 \\ \vdots \\ u_{N-2} \\ u_{N-1} \\ u_N \end{bmatrix} = \begin{bmatrix} \text{-----} \\ f_1 \\ f_2 \\ \vdots \\ f_{N-2} \\ f_{N-1} \\ \text{-----} \end{bmatrix}$$

- (c) **Neumann and... an integral!** where  $u'(a) = 0$  and  $\int_a^b u(x) dx = 7$ :

$$\frac{1}{h^2} \begin{bmatrix} \text{-----} \\ 1 & -2 & 1 & & & \\ & 1 & -2 & 1 & & \\ & & \ddots & \ddots & \ddots & \\ & & & 1 & -2 & 1 \\ \text{-----} & & & & 1 & -2 & 1 \\ \text{-----} \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ u_2 \\ \vdots \\ u_{N-2} \\ u_{N-1} \\ u_N \end{bmatrix} = \begin{bmatrix} \text{-----} \\ f_1 \\ f_2 \\ \vdots \\ f_{N-2} \\ f_{N-1} \\ \text{-----} \end{bmatrix}$$

**Solutions for the following problems should be written in exam booklets.**

6 marks

3. Let  $P$  (a number) be the solution to some problem. Suppose we have a numerical method  $M(h)$  which approximates  $P$  using a small numerical parameter  $h$  (such as a grid spacing). Furthermore, we know an error analysis:  $M(h) = P + Ch^2 + O(h^3)$ , where  $C$  is an unknown fixed constant independent of  $h$ .

Using only the values of  $M(h)$  and  $M(h/3)$ , determine a new more-accurate method for find  $P$ . Give the error term (in Big Oh notation).

Suppose that  $M(1) = 2$  and  $M(1/3) = 3$ . What is your best guess for  $P$ ?

6 marks

4. Let  $A = \begin{bmatrix} 12 & 3 & 4 \\ 3 & 5 & 10 \\ 4 & 10 & 10 \end{bmatrix}$ . In this problem, “ $\times$ ” indicates values that we do not care about.

(a) Find an orthogonal matrix  $H$  such that  $HA = \begin{bmatrix} \alpha & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}$ . What is  $\alpha$ ?

(b) Find an orthogonal matrix  $Q$  such that  $QA = \begin{bmatrix} 12 & 3 & 4 \\ \beta & \times & \times \\ 0 & \times & \times \end{bmatrix}$ . What is  $\beta$ ?

(c) How can we get a matrix  $\begin{bmatrix} 12 & \times & \times \\ \beta & \times & \times \\ 0 & \times & \times \end{bmatrix}$  with the same eigenvalues as  $A$ ?

6 marks

5. Consider the factorization of a matrix into  $A = LL^T$ , where  $L$  is a lower-triangular matrix. This is the *Cholesky factorization*; every *positive definite* matrix has one.

(a) Assuming we already have the Cholesky factorization, describe how to solve  $Ax = b$  for  $x$ . Give the operation count (in “Big Oh” notation) for each step.

(b) *Colin’s Bad Theorem: every positive definite matrix has only unit eigenvalues.*

This theorem ain’t true; find the error in the following “proof”:

“Consider the Cholesky factorization  $A = LL^T$ . Now  $A = LIL^T = LIL^{-1}$  where  $I$  is the identity matrix. Thus  $A$  is similar to the identity matrix. Therefore  $A$  has one eigenvalue,  $\lambda = 1$  (of multiplicity  $n$ ).”

6 marks

6. Give a finite difference discretization of each of these differential equations. Assume there is a uniform grid in  $x$ , given by  $x_i$  with grid spacing  $h$  and a uniform grid in  $t$ , given by  $t_n$  with grid spacing  $k$ .

(a)  $u_{tt} + u_t = (u_{xx})^2$

(b)  $(a(x)u_x)_x = f(x)$

(c)  $u_{xt} = g(x)$ , using forward differences in  $t$  and centered in  $x$

8 marks

7. Consider the ODE  $u_t = f(t, u)$  with initial condition  $u(0) = u_0$ . Which of the following methods are *consistent* and which are *zero-stable*?

(a)  $u_{n+1} = u_n$  (“Colin’s Method”, three easy payments of \$39.99)

(b) 
$$\begin{cases} y = u_n + \frac{1}{2}kf(t_n, u_n) \\ u_{n+1} = y + \frac{1}{2}kf(t_n + \frac{1}{2}k, y) \end{cases}$$

(c)  $u_{n+1} = 3u_n + 4kf(t_n, u_n)$

(d)  $u_{n+1} = u_n + \frac{3}{2}kf(t_n, u_n) - \frac{1}{2}kf(t_{n-1}, u_{n-1})$

6 marks

8. For part (c) of the previous question, perform an absolute stability analysis. Assume that  $\lambda$  (in the test problem) is real (so that  $z = k\lambda$  is real). Determine any restrictions on  $z$  for absolute stability.

For part (d) of the previous question, begin an absolute stability analysis and give two equations which must be satisfied for absolute stability. Note you *do not need to* find the restrictions on  $z$ .

8 marks

9. (a) State Newton’s Method for solving the scalar algebraic equation  $F(y) = 0$ .  
 (b) Give the implicit Backward Euler method for numerically solving the scalar ODE  $u' = f(u)$  with solution  $u(t)$  with initial condition  $u(0) = u_0$  using a stepsize  $h$ .  
 (c) We want to solve  $u' = f(u)$  using the Backward Euler method. Suppose we (only) have two codes `myfcn(u)` and `myderiv(u)` which compute  $f(u)$  and its derivative  $f'(u)$  for a given input. We do not know anything else about  $f(u)$ .

Write an algorithm (e.g., in Matlab-esque or Pythonese “pseudocode”) for taking a single step of Backward Euler (to advance from  $u_n$  to  $u_{n+1}$ ).

Hint: your algorithm does not need *exactly* implement Backward Euler; it is enough to approximate  $u_{n+1}$  to within a tolerance of  $10^{-12}$  (after all,  $u_{n+1}$  is only an approximation of the exact solution  $u(t)$ ).