

Counting invariants for Calabi-Yau threefolds

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Definition

A *Calabi-Yau threefold* is a complex projective manifold Y of dimension 3, endowed with a nowhere vanishing holomorphic volume form $\omega_Y \in \Gamma(Y, \Omega_Y^3)$.

Example. $Y = Z(x_0^5 + \dots + x_4^5) \subset \mathbb{P}^4$ the *Fermat quintic*.

Example. More generally, $g(x_0, \dots, x_4)$ a generic polynomial of degree 5 in 5 variables. $Y = Z(g) \subset \mathbb{P}^4$ the *quintic threefold*.

Example. Algebraic torus $\mathbb{C}^3/\mathbb{Z}^6$ (sometimes excluded, because it is not simply connected).

CY3: the compact part of 10-dimensional space-time according to superstring theory.

Moduli spaces of sheaves

Y : Calabi-Yau threefold.

Fix numerical invariants, and a stability condition.

X : associated moduli space of stable sheaves (derived category objects) on Y .

Example: Fix integer $n > 0$. $X = \text{Hilb}^n(Y)$, Hilbert scheme of n points on Y . $E \in X \iff E$ is a (degenerate) set of n points in Y .

degenerate: $n = 2$: $E = (\text{point } P, \text{tangent vector to } Y \text{ at } P)$

$n = 3$: $E = (\text{point } P, \text{two tangent vectors at } P)$, or
 $E = (2\text{-jet of a curve in } Y)$

Example: Fix integers $n \in \mathbb{Z}$, $d > 0$. $X = I_{n,d}(Y)$, moduli space of (degenerate) curves of genus $1 - n$, degree d in Y .

$E \in X \iff E$ ideal sheaf of a 1-dimensional subscheme $Z \subset Y$.

Degenerate curves: singular curves, curve with several components, curves with clusters of points as in $\text{Hilb}^n(Y)$.

Example: Fix $r > 0$, and $c_i \in H^{2i}(Y, \mathbb{Z})$. X : moduli space of stable sheaves (degenerate vector bundles) of rank r , with Chern classes c_i on Y .

X : can be a finite set of points.

Example. Y : quintic 3-fold in \mathbb{P}^4 .

$X = I_{1,1}(Y)$ moduli space of lines on Y . X : 2875 discrete points.

Example. Y : quintic 3-fold in \mathbb{P}^4 .

$X = I_{1,2}(Y)$ moduli space of conics in Y . X : 609250 discrete points.

(First success of *mirror symmetry*: continue this sequence.)

Slogan. If the world were *without obstructions*, all instances of X would be finite sets of points.

X : almost always very singular.

X : quite often compact: always for examples $\text{Hilb}^n(Y)$ and $I_{n,d}(Y)$, sometimes in the last example (depending on the c_i).

Gauge Theory: why X 'looks like' $\text{Crit } f$

X is trying to look like the critical set of a holomorphic function:

$X =$ complex structures on a fixed bundle E .

$L^1 = A^{0,1}(Y, \text{End } E)$ almost complex structures on E .

$L^2 = A^{0,2}(Y, \text{End } E)$.

Curvature: $F : L^1 \rightarrow L^2$, $F(\alpha) = \bar{\partial}\alpha + \alpha \wedge \alpha$.

α is a complex structure $\iff F(\alpha) = 0$. $X = \{F = 0\} \subset L^1$.

Serre duality pairing $\kappa(\alpha, \beta) = \int_Y \text{tr}(\alpha \wedge \beta) \wedge \omega_Y$ makes L^2 dual to L^1 . So F is a 1-form on L^1 .

$f : L^1 \rightarrow \mathbb{C}$, $f(\alpha) = \frac{1}{2}\kappa(\alpha, \bar{\partial}\alpha) + \frac{1}{3}\kappa(\alpha, \alpha \wedge \alpha)$ holomorphic Chern-Simons. $df = F$. $X = \{F = 0\} = \text{Crit } f \subset L^1$.

Warning: this is most definitely not rigorous.

The main theorem

Y : is a complex projective Calabi-Yau threefold.

X : a moduli space of sheaves on Y .

Theorem (B.)

Suppose that X is compact. Then

$$\int_{[X]^{\text{virt}}} 1 = \chi(X, \nu_X).$$

$[X]^{\text{virt}} \in H_0(X, \mathbb{Z})$. The *virtual fundamental class* of X . From deformation theory and intersection theory.

$\int_{[X]^{\text{virt}}} 1 \in \mathbb{Z}$ *virtual number* of points of X , *Donaldson-Thomas counting invariant*. Needs X compact to be defined.

$\nu_X : X \rightarrow \mathbb{Z}$ a constructible function

$\nu_X(P) \in \mathbb{Z}$ an invariant of the singularity of X at $P \in X$.

$\chi(X, \nu_X)$ topological Euler characteristic of X , with respect to weight function ν_X .

Example: X smooth

Y : CY3 X : moduli space Theorem: $\int_{[X]^{\text{virt}}} 1 = \chi(X, \nu_X)$.

Suppose X is smooth. Then

$$[X]^{\text{virt}} = c_{\text{top}} \Omega_X \cap [X].$$

Hence,

$$\begin{aligned} \int_{[X]^{\text{virt}}} 1 &= \int_{[X]} c_{\text{top}} \Omega_X \\ &= (-1)^{\dim X} \int_{[X]} c_{\text{top}} T_X \\ &= (-1)^{\dim X} \chi(X), && \text{by Gau\ss-Bonnet} \\ &= \chi(X, \nu_X), && \text{with } \nu_X = (-1)^{\dim X}. \end{aligned}$$

Remark: Moduli spaces X are almost never smooth.

Example: $X = \text{Crit } f$

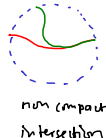
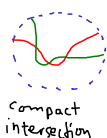
M smooth complex manifold (not compact),

$f : M \rightarrow \mathbb{C}$ holomorphic function,

$X = \text{Crit } f \subset M$. X compact.

Then X is the intersection of two submanifolds in Ω_M :

$$\begin{array}{ccc} X & \longrightarrow & M \\ \downarrow & & \downarrow \Gamma_{df} \\ M & \xrightarrow{0} & \Omega_M \end{array}$$



As X is compact, the intersection number $\int_{[X]_{\text{virt}}} 1 = \mathcal{I}_{\Omega_M}(M, \Gamma_{df})$ is well-defined.

Theorem (Singular Gauß-Bonnet. From microlocal geometry)

$$\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = \chi(X, \mu)$$

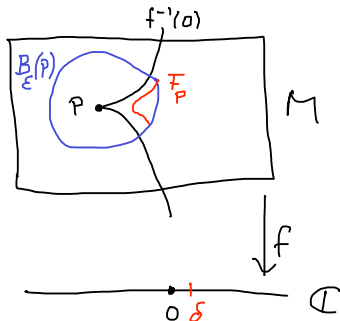
$$\mu(P) = \text{Milnor number of } f \text{ at } P = (-1)^{\dim M} (1 - \chi(F_P))$$

$$F_P = \text{Milnor fibre of } f \text{ at } P$$

Milnor fibre

$X = \text{Crit } f \subset M$ $f : M \rightarrow \mathbb{C}$ holomorphic Theorem: $\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = \chi(X, \mu)$

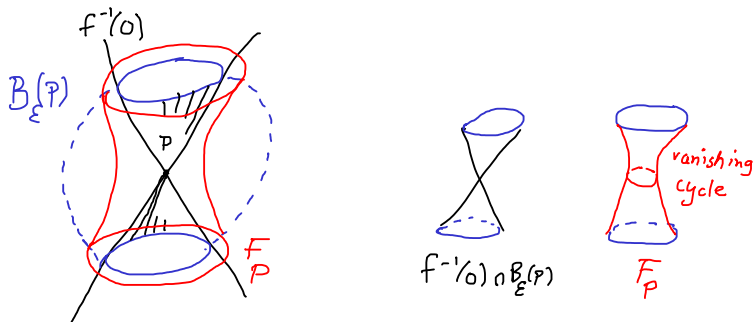
F_P : Milnor fibre of f at P : intersection of a nearby fibre of f with a small ball around P .



$$\mu(P) = (-1)^{\dim M} (1 - \chi(F_P))$$

$$\mu : X \rightarrow \mathbb{Z}$$

Milnor fibre example. $f(x, y) = x^2 + y^2$



$X = \text{Crit}(f) = \{P\}$. Isolated singularity.

Near P , the surface $f^{-1}(0)$ is a cone over the link of the singularity. The cone is contractible.

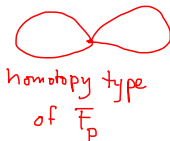
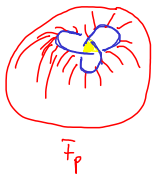
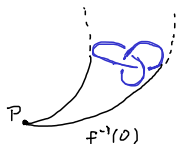
The Milnor fibre is a manifold with boundary. The boundary is the link.

The Milnor fibre supports the *vanishing cycles*. The Milnor number

$\mu(P) = (-1)^{\dim M} (1 - \chi(F_P))$ is the number of vanishing cycles.

In this example, $\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = 1 = \chi(X, \mu)$.

Milnor fibre example $f(x, y) = x^2 + y^3$



$X = \text{Crit}(f) = \{(x, y) \mid 2x = 0, 3y^2 = 0\} = \text{Spec } \mathbb{C}[y]/y^2$. Isolated singularity of multiplicity 2. $\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = 2$.

Link: $(2, 3)$ torus knot (trefoil). The singularity is a cone over the knot. The link bounds the Milnor fibre. Homotopy type (Milnor fibre) = bouquet of 2 circles. $\chi(F_P) = 1 - 2 = -1$.

The Milnor number is $\mu(P) = (-1)^2(1 - (-1)) = 2$. There are 2 vanishing cycles.

In this example, $\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = 2 = \chi(X, \mu)$.

For the case $\dim X = 0$ (isolated singularities) it is a theorem of Milnor that $\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = \text{Milnor number} = \chi(X, \mu)$.

Special case: $X = \text{Crit } f$ concluded

$X = \text{Crit } f \subset M$ $f : M \rightarrow \mathbb{C}$ holomorphic Theorem: $\mathcal{I}_{\Omega_M}(M, \Gamma_{df}) = \chi(X, \mu)$

Remark: The case X smooth is the special case $M = X$, and $f = 0$.

The intersection diagram is $X \longrightarrow X$ (self-intersection)

$$\begin{array}{ccc} X & \longrightarrow & X \\ \downarrow & & \downarrow 0 \\ X & \xrightarrow{0} & \Omega_X \end{array}$$

Hence we have $\mathcal{I}_{\Omega_X}(X, X) = \int_{[X]} c_{\text{top}}(\Omega_X)$.

This explains why we took $[X]^{\text{vir}} = c_{\text{top}}(\Omega_X) \cap [X]$.

The Milnor fibre is empty. So $\mu(P) = (-1)^{\dim X}$

So in the case where $f = 0$, the theorem is Gauß-Bonnet.

The general case follows from the micro-local index theorem of Kashiwara-MacPherson, and the identification of the characteristic variety of a hypersurface in terms of the Jacobian ideal.

Lagrangian Intersections

Theorem

Suppose that X is compact. Then $\int_{[X]^{\text{virt}}} 1 = \chi(X, \nu_X)$.

$[X]^{\text{virt}} \in H_0(X\mathbb{Z})$. X can locally be written as the critical set of a holomorphic function. Locally defined intersection classes glue. [B.-Fantechi], [Li-Tian], [Thomas]

$\int_{[X]^{\text{virt}}} 1$ counting invariant. Is invariant under deformations of Y .

$\chi(X, \nu_X)$ can be computed by cutting up X into pieces.

In fact, $\nu_X(P)$ should be thought of as the contribution of $P \in X$ to the counting invariant. $\chi(X, \nu)$ makes sense, even when X is not

compact. Unusual: in general, intersection points move away to infinity, when the intersection is not compact. This works because

$$\begin{array}{ccc} X & \longrightarrow & M \\ \downarrow & & \downarrow \Gamma_{df} \\ M & \xrightarrow{0} & \Omega_M \end{array}$$

is a *Lagrangian* intersection inside a *symplectic* manifold.

Application: Hilbert scheme of n points

Theorem (B.-Fantechi, Levine-Pandharipande, Li)

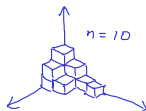
$$\sum_{n=0}^{\infty} \left(\int_{[\mathrm{Hilb}^n Y]^{\mathrm{virt}}} 1 \right) t^n = \left(\prod_{n=1}^{\infty} \left(\frac{1}{1 - (-t)^n} \right)^n \right)^{\chi(Y)}$$

This theorem makes sense even when Y is not compact, for example $Y = \mathbb{C}^3$. Then $\chi(Y) = 1$, and

$$\sum_{n=0}^{\infty} \chi(\mathrm{Hilb}^n \mathbb{C}^3, \nu) t^n = \prod_{n=1}^{\infty} \left(\frac{1}{1 - (-t)^n} \right)^n.$$

This is (up to signs) the generating function for 3-dimensional partitions [MacMahon]

$$\sum_{n=0}^{\infty} \#\{3\mathrm{D} \text{ partitions of } n\} t^n = \prod_{n=1}^{\infty} \left(\frac{1}{1 - t^n} \right)^n$$



Application: wall crossing

We can define a number $\nu(E) \in \mathbb{Z}$, for every coherent sheaf E on Y . More generally, for any derived category object $E \in D(Y)$. Because the singularity at E is always the same, for every moduli space $E \in X$, independent of the stability condition.

Joyce, Kontsevich-Soibelman: Define invariants for every stability condition on a derived category $D(Y)$, where Y is a CY3. (No need even for moduli spaces.) Also, study how invariants change, under change of stability condition (wall crossing).

For example, if Y' is a CY3, birational to Y ,

moduli of sheaves on $Y' =$ moduli of certain objects of $D(Y)$.

Compare counting invariants for Y and Y' via wall crossing in $D(Y)$.

For example [Toda], for every flop,
$$\frac{\sum_{(n,\beta)} \left(\int_{[I_{n,\beta}(Y)]^{\text{virt}}} 1 \right) x^\beta q^n}{\sum_{(n,\beta), f_*\beta=0} \left(\int_{[I_{n,\beta}(Y)]^{\text{virt}}} 1 \right) x^\beta q^n}$$
 does not change.

Applications: motivic Donaldson-Thomas invariants

Motivated by our theorem: use more general kind of counting: not just numbers, but motivic counting: Instead of using Euler characteristic of the Milnor fibre of local Chern-Simons map $f : \text{Ext}^1(E, E) \rightarrow \mathbb{C}$ to define $\nu(E)$, use its Poincaré polynomial $\in \mathbb{Q}[t]$, Hodge polynomial $\in \mathbb{Q}[u, v]$, or even its motive $\in K_0(\text{Var})$. This is being done by [Kontsevich-Soibelman].

Theorem (B.-Bryan-Szendrői)

$$\sum_{n=0}^{\infty} [\text{Hilb}^n Y]^{\text{virt}} t^n = \left(\prod_{m=1}^{\infty} \prod_{k=1}^m \frac{1}{1 - q^{k-2-\frac{m}{2}} t^m} \right)^{[Y]}$$

$[\text{Hilb}^n Y]^{\text{virt}}$ virtual motive of $\text{Hilb}^n Y$, defined using motivic vanishing cycles of a suitable local Chern-Simons, which is a homogeneous polynomial of degree 3, in this simple case,

$q = [\mathbb{C}]$ the motive of the affine line,

$[Y]$ the motive of Y . The formula uses the *power structure* on $K_0(\text{Var})$.