

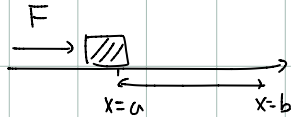
Lec 2x

• Work § 7.6.

• Probability § 7.8.

Work § 7.6.

• single body



• When F is constant.

"work = force x distance"

units
Force \rightarrow N.
Newton
distance \rightarrow m
meter.
work \rightarrow N·m.

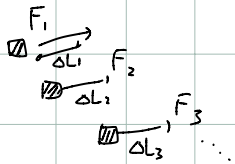
$$W = F \cdot (b-a)$$

• When F is not constant in general.

$$dW = F(x) dx$$

$$W = \int_{x=a}^{x=b} dW = \int_a^b F(x) dx$$

• Many bodies



$$W = \sum_{i=1}^N W_i$$
$$= \sum_{i=1}^N F_i \Delta L_i$$

• fluid.

$$dW = F dL$$

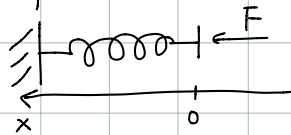


continuous family of "particles"

need multi variable calculus.

(but, special cases can be handled using single variable calculus.

EX. Spring.



$$F(x) = kx$$

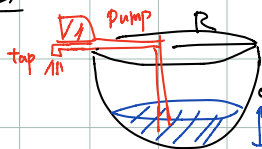
Hooke's law. $k = \text{constant}$.

Suppose $k = 2000$

To stretch the spring by 3 cm.

$$W = \int_0^3 2000x \, dx = 1000x^2 \Big|_0^3 = 9000 \text{ N}\cdot\text{cm}$$
$$= \underline{90 \text{ N}\cdot\text{m}} \quad \leftarrow 1 \text{ cm} = \frac{1}{100} \text{ m}$$

EX



Water tank

hemisphere, radius R (m)

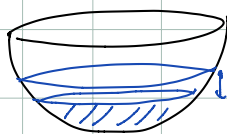
gravitational constant g

mass density per volume ρ ($\rho = 1000 \text{ kg/m}^3$)

To empty the tank, how much work has to be done by the pump?
at least.

<sol>

• Consider the infinitesimal moment

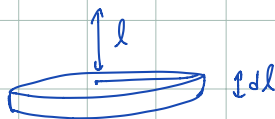


for the distance from the top of the container

to the water surface,

to be from l to $l+dl$.

Then the amount of water
corresponding the thin slice



has to be moved.

at least distance l .

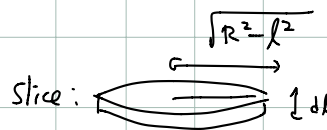
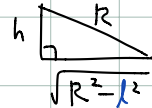
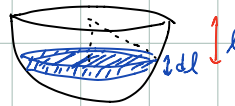
• Work corresponding to the slice at distance l from the top of the container.

$$dW = F \cdot l$$

• Force corresponding to the thin slice.

gravitational force = $g \cdot \text{mass}$.

$$F = \overbrace{g \cdot \rho}^{\text{gravitational constant}} \cdot \underbrace{dV}_{\text{mass density}}$$



• volume $dV = \text{area} \cdot \text{width}$

$$= \pi (\sqrt{R^2 - l^2})^2 dl$$

$$= \pi (R^2 - l^2) dl$$

• So $dW = g \cdot \rho \cdot \pi (R^2 - l^2) dl \cdot l$

$$= g \cdot \rho \cdot \pi (R^2 - l^2) l dl$$

• Total work



$$W = \int_{l=R/2}^{l=R} dW = \int_{l=R/2}^{l=R} g \rho \pi (R^2 - l^2) l dl$$

$$= g \rho \pi \int_{R/2}^R (R^2 - l^2) l dl = g \rho \pi \left[R^2 \frac{l^2}{2} - \frac{l^4}{4} \right]_{R/2}^R$$

constants.

$$= g \rho \pi \left[\frac{R^4}{2} - \frac{R^4}{4} - \left(R^2 \cdot \frac{R^2}{8} - \frac{R^4}{2^4 \cdot 4} \right) \right]$$

$$= g \rho \pi R^4 \cdot \left(\frac{1}{4} - \frac{1}{8} - \frac{1}{64} \right) = g \rho \pi R^4 \cdot \frac{16-8-1}{64}$$

$$= \underline{\underline{\frac{7}{64} g \rho \pi R^4}}$$

Probability § 2.8. 3 lectures

Exercises in § 2.8 : 12, 15, 16, 18, 20, plus Ch. review challenging problem #7.

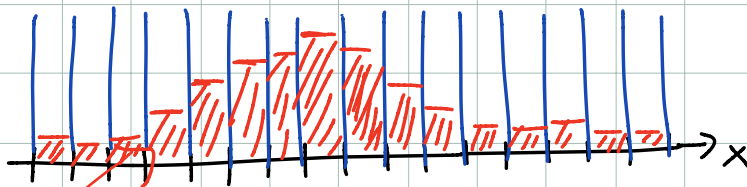
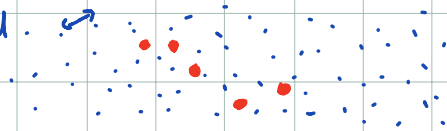
Continuous Probability Distributions

- From discrete probability to continuous probability.
- Probability density
- § From discrete probability to continuous probability.

Example for motivation

- Watch YouTube "Galton Board" (the one with 2:24 min).

The grid size is comparable to the ball.



• Suppose each ball has small area A .

• Suppose the total area = 1.

(i.e. Total # of balls = $\frac{1}{A}$).

• In each bin,



• The area = (# of balls in the bin) \times A
$$= \frac{\text{\# of balls in the bin}}{\text{total \# of balls}}$$

$$A = \frac{1}{\text{Total \# of balls}}$$

So, this area represents
the probability for a ball to be in the bin.

• The height $h = \frac{\text{the area}}{\text{width}}$

$$= \frac{\frac{\text{\# of balls in the bin}}{\text{total \# of balls}}}{\Delta x}$$

The height represents how much portion of balls
per the unit width.

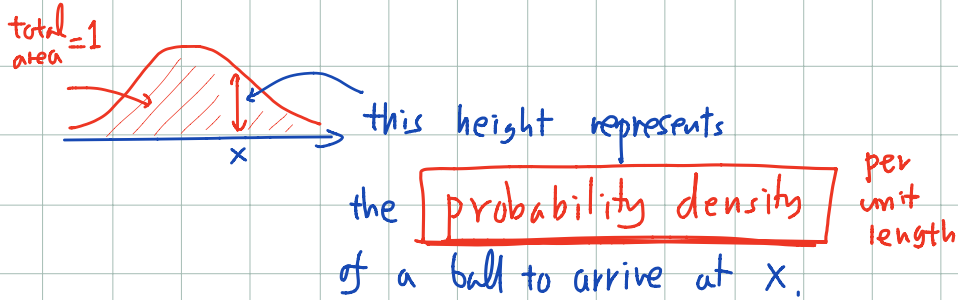
(i.e. the probability per unit width Δx).

* This is a probability density!

• Continuous Probability

If the size of each ball and the width of each bin
get smaller & smaller
(i.e. $A \rightarrow 0$ & $\Delta x \rightarrow 0$).

Then, the resulting shape will be a curve.



* probability density is similar to mass density.
(except the total probability is always 1.)

RMK In the Galton board,
the curve is the bell curve. "Normal distribution"
(Gaussian)

$$y = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$$

μ = constant. = mean of the distribution

σ = constant. = variance of the "

σ = constant = standard deviation

We will learn
these concepts
in the next
two lectures.

§ Probability density function:

Def. A function $P(x)$ defined on $[a, b]$

is said to be a
probability density

(here, a can be $-\infty$
 b can be ∞)

if 1. $P(x) \geq 0$ for all x

2. $\int_a^b P(x) dx = 1.$

$[a, b]$
is the possible
values of x

* probability density is similar to mass density.
except that total probability = 1, ALWAYS!

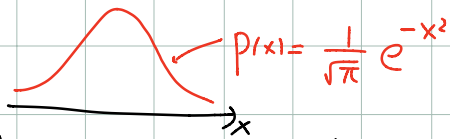
Def A variable x with probability density $p(x)$ is called a random variable

e.g. $p(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$ is a probability density function because

- $p(x) \geq 0$ for all x .
- Fact $\int_{-\infty}^{\infty} \frac{1}{\sqrt{\pi}} e^{-x^2} dx = 1$.

e.g. (Probability VS Probability density)

Let, in the Galton board example,



What is the probability for a small ball to arrive at $x=1$?

~~e.g. At $x=1$, $p(1) = \frac{1}{\sqrt{\pi}} e^{-1}$~~

~~So, the probability is $\frac{1}{\sqrt{\pi}} e^{-1}$.~~

~~WRONG!~~

NOTE Probability density \neq probability

(similarly to mass density \neq mass)

At the point $x=1$, the width of the interval = 0.

So, the probability for a ball to arrive there

is zero. \square

More systematic way

to get probability from probability density:

Integrate the probability density!

(Just like how you get mass from mass density.)

- Probability from probability density function.

The probability for a random variable takes on values in the interval $\alpha \leq x \leq \beta$:

$$\mathbb{P}(\alpha \leq x \leq \beta) = \int_{\alpha}^{\beta} p(x) dx.$$

just a notation to denote the probability

e.g. $p(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$

$$\mathbb{P}(x=1) = \int_1^1 p(x) dx = \int_1^1 \frac{1}{\sqrt{\pi}} e^{-x^2} dx = 0$$

Ex. Let $p(x) = Cx^2$, $0 \leq x \leq 1$. $C = \text{const.}$

be a probability density. possible values of x .

① Determine C .

② Find probability for x to be in $\frac{1}{2} \leq x \leq 1$.

<sol>

$$\textcircled{1} 1 = \int_0^1 p(x) dx = C \int_0^1 x^2 dx = C \left[\frac{x^3}{3} \right]_0^1 = C \cdot \frac{1}{3} \therefore \underline{C=3}$$

$$\textcircled{2} \mathbb{P}\left(\frac{1}{2} \leq x \leq 1\right) = \int_{\frac{1}{2}}^1 p(x) dx = \int_{\frac{1}{2}}^1 3 \cdot x^2 dx = \left[x^3 \right]_{\frac{1}{2}}^1 = 1 - \left(\frac{1}{2}\right)^3 = \underline{\underline{\frac{7}{8}}}$$

$C=3$ from ①.

Next lecture:

- Cumulative function

- Mean (expectation)

- Some applications