

# ON A PROPERTY OF REAL PLANE CURVES OF EVEN DEGREE

ZINOVY REICHSTEIN

ABSTRACT. F. Cukierman asked whether or not for every smooth real plane curve  $X \subset \mathbb{P}^2$  of even degree  $d \geq 2$  there exists a real line  $L \subset \mathbb{P}^2$  such  $X \cap L$  has no real points. We show that the answer is “yes” if  $d = 2$  or  $4$  and “no” if  $n \geq 6$ .

## 1. INTRODUCTION

F. Cukierman asked whether or not for every smooth real plane curve  $X \subset \mathbb{P}^2$  there exists a real line  $L \subset \mathbb{P}^2$  such that the intersections  $X \cap L$  has no real points. In other words, can we “see” all real points of  $X$  in some affine space of the form  $\mathbb{A}^2 = \mathbb{P}^2 \setminus L$ ?

Note that if  $d$  is odd, then the answer is “no” for trivial reasons:  $X \cap L$  is cut out by an odd degree polynomial on  $L$  and hence, always has a real point. On the other hand, in the case where  $d = 2$ , the answer is readily seen to be “yes”. Indeed, given a real conic  $X$  in  $\mathbb{P}^2$ , choose a complex point  $z \in X(\mathbb{C}) \setminus X(\mathbb{R})$  which is not real, and let  $L$  be the (real) line passing through  $z$  and its complex conjugate  $\bar{z}$ . If  $X$  is smooth, then  $L$  is not contained in  $X$ . Hence, the intersection  $(X \cap L)(\mathbb{C}) = \{z, \bar{z}\}$  contains no real points.

The main result of this note, Theorem 1 below, asserts that the answer to Cukierman’s question is “yes” if  $d = 2$  or  $4$  and “no” if  $n \geq 6$ .

**Theorem 1.** (a) *Suppose  $d = 2$  or  $4$ . Then for every smooth plane curve  $X \subset \mathbb{P}^2$  of degree  $d$  defined over the reals, there exists a real line  $L \subset \mathbb{P}^2$  such that  $(X \cap L)(\mathbb{R}) = \emptyset$ .*

(b) *Suppose  $d \geq 6$  is an even integer. Then there exists a smooth plane curve  $X \subset \mathbb{P}^2$  of degree  $d$  defined over the reals, such that  $(X \cap L)(\mathbb{R}) \neq \emptyset$  for every real line  $L \subset \mathbb{P}^2$ .*

The proof of Theorem 1 presented in in Sections 3 and 4 uses deformation arguments. These arguments, in turn, rely on the preliminary material in Section 2.

## 2. CONTINUITY OF MINIMIZER AND MAXIMIZER FUNCTIONS

**Lemma 2.** *Let  $V, W$  and  $F$  be topological manifolds. Assume that  $F$  be compact,  $\pi: V \rightarrow W$  is an  $F$ -fibration, and  $f: V \rightarrow \mathbb{R}$  is a continuous function. Then the minimizer  $\mu(w) := \min\{f(v) \mid \pi(v) = w\}$  and the maximizer  $\nu(w) := \max\{f(v) \mid \pi(v) = w\}$  are continuous functions  $W \rightarrow \mathbb{R}$ .*

*Proof.* Since  $F$  is compact,  $f$  assumes its minimal and maximal values on every fiber  $\pi^{-1}(w)$ . Hence, the functions  $\mu$  and  $\nu$  are well defined. Note also that if we replace  $f$  by  $-f$ , we will change  $\mu(w)$  to  $-\nu(w)$ . Thus it suffices to show that  $\mu$  is continuous. Finally, to show that  $\mu$  is continuous at  $w \in W$ , we may replace  $W$  by a small neighborhood of

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$w$  and thus assume that  $V = W \times F$  and  $\pi: V \rightarrow W$  is projection to the first factor. In this special case, the continuity of  $\mu$  is well known; see, e.g., [Wo] (cf. also [Da]).  $\square$

**Corollary 3.** *Let  $d \geq 2$  be an even integer,  $\text{Pol}_d$  be the affine space of homogeneous polynomials of even degree  $d$  in 3 variables, and  $\check{\mathbb{P}}^2$  be the dual projective plane parametrizing the lines in  $\mathbb{P}^2$ . Then the functions*

$$m_p(L) \text{ and } M_p(L): \text{Pol}_d(\mathbb{R}) \times \check{\mathbb{P}}^2(\mathbb{R}) \rightarrow \mathbb{R}$$

given by  $m_p(L) = \min\{p(x) \mid x \in L(\mathbb{R})\}$  and  $M_p(L) = \max\{p(x) \mid x \in L(\mathbb{R})\}$  are well defined and continuous.

Note that a polynomial  $p(x, y, z)$  of even degree  $d$  gives rise to a continuous function  $\mathbb{P}^2(\mathbb{R}) \rightarrow \mathbb{R}$  given by

$$(2.1) \quad (x : y : z) \rightarrow \frac{p(x, y, z)}{(x^2 + y^2 + z^2)^{d/2}}.$$

By a slight abuse of notation, we will continue to denote this function by  $p$ .

*Proof of Corollary 3.* We will apply Lemma 2 in the following setting. Let  $W := \text{Pol}_d \times \check{\mathbb{P}}^2$  and

$$V := \{(p, L, a) \mid a \in L\} \subset \text{Pol}_d \times \check{\mathbb{P}}^2 \times \mathbb{P}^2.$$

In other words,  $V = \text{Pol}_d \times \text{Flag}(1, 2)$ , where  $\text{Flag}(1, 2)$  is the flag variety of  $(1, 2)$ -flags in a 3-dimensional vector space. Clearly  $V$  and  $W$  are smooth algebraic varieties defined over  $\mathbb{R}$ . Their sets of real points,  $V(\mathbb{R})$  and  $W(\mathbb{R})$ , are topological manifolds and the projection  $\pi: V(\mathbb{R}) \rightarrow W(\mathbb{R})$  to the first two components is a topological fibration with compact fiber  $F = \mathbb{P}^1(\mathbb{R})$ .

Applying Lemma 2 to the continuous function  $f: V(\mathbb{R}) \rightarrow \mathbb{R}$  given by  $f(p, L, a) := p(a)$ , where  $p(a)$  is evaluated as in (2.1), we deduce the continuity of the real-valued functions  $m_p(L) = \mu(p, L)$  and  $M_p(L) = \nu(p, L)$  on  $\text{Pol}_d(\mathbb{R}) \times \check{\mathbb{P}}^2(\mathbb{R})$ .  $\square$

**Proposition 4.** *Let  $p \in \mathbb{R}[x, y, z]$  be a homogeneous polynomial of even degree and  $X \subset \mathbb{P}^2$  be the zero locus of  $p$ . Set  $m(p) := \max_{L \in \check{\mathbb{P}}^2} m_p(L)$  and  $M(p) := \min_{L \in \check{\mathbb{P}}^2} M_p(L)$ , where  $L$  ranges over the real lines in  $\mathbb{P}^2$ . Then*

- (a)  $m(p)$  and  $M(p)$  are well-defined continuous functions  $\text{Pol}_d(\mathbb{R}) \rightarrow \mathbb{R}$ .
- (b)  $m(p) \leq M(p)$ .
- (c)  $(X \cap L)(\mathbb{R}) \neq \emptyset$  for every real line  $L \subset \mathbb{P}^2$  if and only if  $m(p) \leq 0 \leq M(p)$ .
- (d)  $p$  assumes both positive and negative values on each real line  $L \subset \mathbb{P}^2$  if and only if  $m(p) < 0 < M(p)$ .
- (e) If  $m(p) = M(p) = 0$ , then  $X$  is not a smooth curve.

*Proof.* By Corollary 3,  $M_p(L)$  and  $m_p(L)$  are continuous functions  $\text{Pol}_d(\mathbb{R}) \times \check{\mathbb{P}}^2(\mathbb{R}) \rightarrow \mathbb{R}$ . Since  $\check{\mathbb{P}}^2(\mathbb{R})$  is compact, Lemma 2 tells us that the functions  $m(p)$  and  $M(p): \text{Pol}_d(\mathbb{R}) \rightarrow \mathbb{R}$  are well-defined and continuous. This proves (a).

(c) and (d) are immediate consequences of the definition of  $m(p)$  and  $M(p)$ .

To prove (b) and (e), choose lines  $L_1, L_2 \subset \mathbb{P}^2$  such that  $m_p(L)$  attains its maximal value  $m(p)$  at  $L = L_1$  and  $M_p(L)$  attains its minimal value  $M(p)$  at  $L = L_2$ . If  $L_1$  and  $L_2$  intersect at a point  $a \in \mathbb{P}^2(\mathbb{R})$ , then

$$(2.2) \quad m(p) = m_p(L_1) \leq p(a) \leq M_p(L_2) = M(p).$$

This proves (b).

In part (e), where we further assume that  $m(p) = M(p) = 0$ , the inequalities (2.2) tell us that  $p(a) = 0$  is the maximal value of  $p$  on  $L_1(\mathbb{R})$  and the minimal value of  $p$  on  $L_2(\mathbb{R})$ . Hence,  $a$  lies on  $X$ , and both  $L_1$  and  $L_2$  are tangent to  $X$  at  $a$ . We want to show that  $X$  cannot be a smooth curve. Assume the contrary. Then  $X$  has a unique tangent line at  $a$ . Thus  $L_1 = L_2$ , and  $0 = m_p(L_1) = M_p(L_2) = M_p(L_1)$ . We conclude that  $p$  is identically zero on  $L_1(\mathbb{R}) = L_2(\mathbb{R})$ . Consequently,  $L_1 = L_2 \subset X$ , contradicting our assumption that  $X$  is a smooth curve.  $\square$

### 3. PROOF OF THEOREM 1(A)

The case where  $d = 2$  was handled in the Introduction; we will thus assume that  $d = 4$ .

**Lemma 5.** *Let  $p \in \mathbb{R}[x, y, z]$  be a homogeneous polynomial of degree 4 cutting out a smooth quartic curve  $X$  in  $\mathbb{P}^2$ . Then either  $m(p) \geq 0$  or  $M(p) \leq 0$ .*

*Proof.* By a theorem of H. G. Zeuthen [Zeu],  $X$  has a real bitangent line  $L \subset \mathbb{P}^2$ . (For a modern proof of Zeuthen's theorem, we refer the reader to [Ru, Corollary 4.11]; cf. also [PSV].) The restriction of  $p(x, y, z)$  to  $L$  is a real quartic polynomial with two double roots, i.e., a polynomial of the form  $\pm q(s, t)^2$ , where  $s$  and  $t$  are linear coordinates on  $L$ , and  $q \in \mathbb{R}[s, t]$  is a binary form of degree 2. In particular,  $p$  does not change sign on  $L$ , i.e., either (i)  $p(a) \geq 0$  for every  $a \in L(\mathbb{R})$  or (ii)  $p(a) \leq 0$  for every  $a \in L(\mathbb{R})$ . In case (i),  $m(p) \geq m_p(L) \geq 0$  and in case (ii),  $M(p) \leq M_p(L) \leq 0$ .  $\square$

We are now ready to finish the proof of Theorem 1(a) for  $d = 4$ . Assume the contrary: there exists a smooth real quartic curve  $X \subset \mathbb{P}^2$  such that  $(X \cap L)(\mathbb{R}) \neq \emptyset$  for every real line  $L \subset \mathbb{P}^2$ . Let  $p \in \mathbb{R}[x, y, z]$  be a defining polynomial for  $X$ . By Proposition 4(c),  $m(p) \leq 0 \leq M(p)$ . In view of Lemma 5, after possibly replacing  $p$  by  $-p$ , we may assume that  $m(p) = 0$ . Proposition 4(e) now tell us that  $m(p) = 0 < M(p)$ . Let  $p_t(x, y, z) = p(x, y, z) - t(x^2 + y^2 + z^2)^2$ , where  $t$  is a real parameter, and let  $X_t \subset \mathbb{P}^2$  be the quartic curve cut out by  $p_t$ . Note that  $X_t$  can be singular for only finitely many values of  $t \in \mathbb{R}$ . Thus we can choose  $t \in (0, M(p))$  so that  $X_t$  is smooth. Since  $x^2 + y^2 + z^2$  is identically 1 on  $\mathbb{P}^2(\mathbb{R})$  (cf. (2.1)), we have

$$m(p_t) = m(p) - t < 0 < M(p) - t = M(p_t).$$

This contradicts Lemma 5, which asserts that  $m(p_t) \geq 0$  or  $M(p_t) \leq 0$ .  $\square$

### 4. PROOF OF THEOREM 1(B)

Given an even integer  $d \geq 6$ , set  $p(x, y, z) := (x^3 + y^3 + z^3)^2(x^2 + y^2 + z^2)^{(d-6)/2}$  and

$$p_t(x, y, z) = p(x, y, z) - t(x^d + y^d + z^d),$$

where  $t$  is a real parameter. In view of Proposition 4(c), it suffices to show that if  $t > 0$  is sufficiently small, then (i)  $X_t$  is smooth and (ii)  $m(p_t) < 0 < M(p_t)$ .

Since the Fermat curve,  $x^d + y^d + z^d = 0$ , is smooth,  $X_t$  is singular for only finitely many values of  $t$ , and (i) follows.

To prove (ii), note that  $p$  is non-negative but is not identically 0 on any real line  $L \subset \mathbb{P}^2$ . Thus  $M_p(L) > 0$  and consequently,  $M(p) > 0$ . By Proposition 4(a),  $M(p_t) > 0$  for small  $t$ . On the other hand, for every real line  $L \subset \mathbb{P}^2$ , the cubic polynomial  $x^3 + y^3 + z^3$  vanishes at some real point  $a$  of  $L$ . Hence for every  $t > 0$ , we have  $p_t(a) < 0$  and thus  $m_{p_t}(L) < 0$ . We conclude that  $m(p_t) < 0$ , as desired.  $\square$

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF BRITISH COLUMBIA, VANCOUVER, B.C., CANADA V6T 1Z2

*E-mail address:* reichst@math.ubc.ca