

Five print on Lagrange mult.

- For the method to work:
 - need to assume
 - $f(x,y,z)$ is ^{cont.} differentiable
 - $G(x,y,z)$ cont. diff.
 - $\nabla f = \lambda \nabla G$ - really works only when $\nabla G \neq 0$.

$f(x,y,z)$ - the function whose extrema we are looking for

$G(x,y,z) = 0$ - the constraint.

So, when looking for ~~the~~ candidate points for the extremum, make a list:



$G(x,y,z) = 0$.

- critical points of f inside the domain ← if you have a solid in \mathbb{R}^3 or domain in \mathbb{R}^2
- On the boundary;

- (1) • use Lagrange mult.
 $F = f - \lambda G$

critical points of F

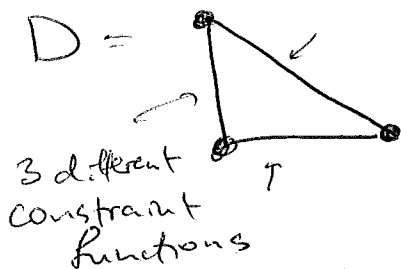
- (2) All points where ∇f does not exist (inside the domain or on the boundary)

- (3) All points where ∇G does not exist

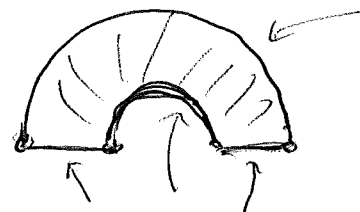
- (4) All points where $\nabla G = 0$.

- If the boundary has "end points", these end points.

ex: \mathbb{R}^2 ,



or



4 different Lagrange problems

Example: Find $\max f(x,y,z)$

on a cube

$$0 \leq x \leq 1$$

$$0 \leq y \leq 1$$

$$0 \leq z \leq 1$$

Algorithm:

• find critical pts of f inside (or on the boundary) of the cube.

• Find the candidate points on each face of the cube.

(2 methods: Lagrange or

plug in, say, $x=1$ ~~if~~

if on the face $x=1$,

work with a function of y, z).

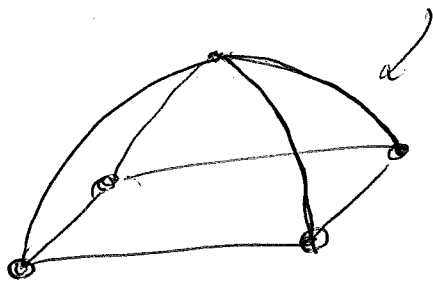
• Look for max on the edges

(plug in $x=1, y=0$, for example --)

(or for more complicated solids,

use Lagrange

with 2 constraints)



$$f(x,y,z) - \lambda G(x,y,z) -$$

$$\mu H(x,y,z)$$

equations
of surfaces

whose intersection is
our edge.

• Vertices

• points where f is not diff.

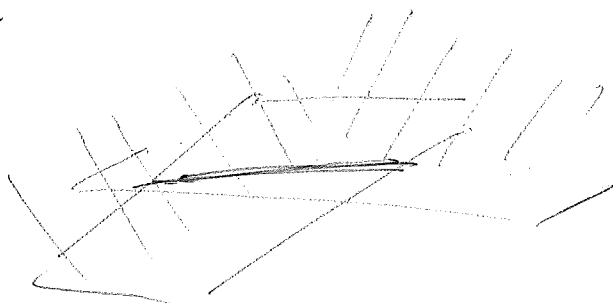
~~points~~ • points where $\bar{D}_G, \bar{D}_H, \dots$ are 0.

• Linear programming : shortens this process

in the situation where $f(x_1, \dots, x_n)$

is linear and the solid ~~set~~ is defined by linear inequalities in (x_1, \dots, x_n) :

$$\left\{ \begin{array}{l} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots \geq 0 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n \geq 0 \\ \dots \\ a_{m1}x_1 + \dots + a_{mn}x_n \geq 0 \end{array} \right. \quad (\text{convex polyhedron})$$



in fact, only need to check the vertices.

(Optional reading.)

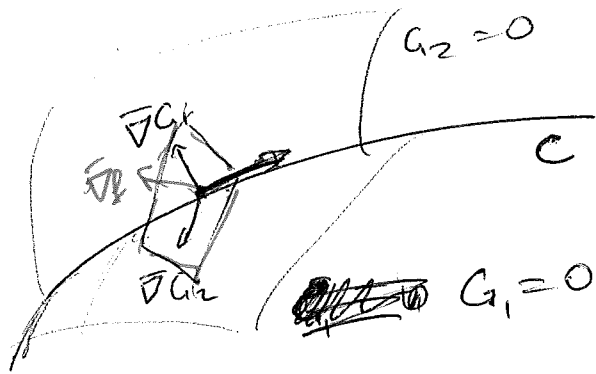
When more than one constraint:

the condition for an extremal point of $f(x_1, \dots, x_n)$
subject to constraints $C_1(x_1, \dots, x_n) = 0$
 \vdots
 $C_m(x_1, \dots, x_n) = 0$

is: ∇f has to lie in the subspace of \mathbb{R}^n
spanned by $\nabla C_1, \dots, \nabla C_m$ at that point.

$$\left(\nabla f = \lambda_1 \nabla C_1 + \dots + \lambda_m \nabla C_m \right)$$

↑ Lagrange multipliers



$\text{span}(\nabla G_1, \nabla G_2) = \text{plane perpendicular to the tangent vector to the curve of intersection.}$

↑
want to min/max of $f(x, y, z)$ when $(x, y, z) \in C$.

$$\nabla f = \lambda \nabla G_1 + \mu \nabla G_2$$

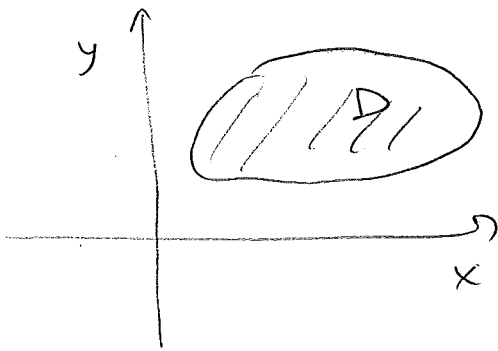
Meaning of λ : it tells you how much
max f will change if you replace

$G(x, y, z) = 0$ with $G(x, y, z) = h$
for small h .

max f will change by $\lambda \cdot |\nabla G|$
(see p. 773 - 774)

Integrals over rectangles in \mathbb{R}^2

Read 14.1-14.3



want to define: $\iint_D f(x,y) dA$ all one symbol.

double integral

(number of integrals = dimension of the domain)

Note: there will be no 'indefinite integral'.

(it is a single symbol).

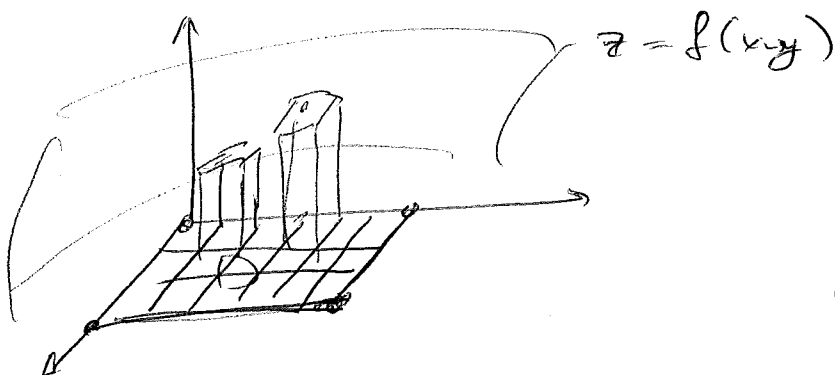
(!) $\iint f(x,y) dA$
 $\iint_D f(x,y)$
 $\int_D f(x,y) dA$

don't make sense.

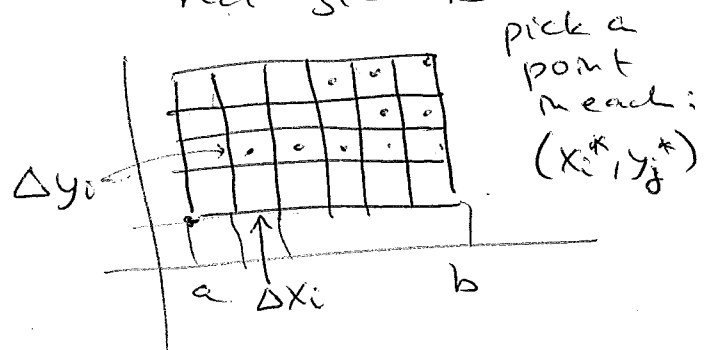
The correct usage:

$$\iint_D f(x,y) dA.$$

1. Let D be a rectangle.



Riemann sum: subdivide our rectangle D



pick a point in each: (x_i^*, y_j^*)

Riemann sum for the double integral is

$$\sum_{\substack{i=1 \dots n \\ j=1 \dots m}} f(x_i^*, y_j^*) \underbrace{\Delta x_i \Delta y_j}_{\text{area of the small rectangle}} = R_P$$

↑
partition

approximates the volume under the graph of $f(x, y)$ over our rectangle D . assume $f(x, y) > 0$

"Theorem:" If $\Delta x_i^2 + \Delta y_j^2 \rightarrow 0$ then all subdivisions will give Riemann sums that are very close to the volume under the graph.

$(\forall \epsilon, \exists \delta$ s.t. if for every i, j diameter of each small rectangle $< \delta$
then $|R_P - R_{P'}| < \epsilon$ for any P, P' satisfies this

and any choice (x_i^*, y_j^*) .)

Then their limit exists, and is called $\iint_D f(x, y) dA$.

(Assume f is cont. on D)