

Last time Finished self-adjoint linear operators. (over \mathbb{R}).
 (recall: eigenvalues are real, there is an orthonormal basis of eigenvectors, so the matrix is diagonalizable)
 ↗ symmetric matrix.

Today: applications: - discrete dynamical systems
 (quick sketch) - stochastic matrices, probability Markov chains

Idea: many situations where you have "state" and apply linear operator, get a new "state".
 ↑ a bunch of numbers

Then do it many times.

Example: "state" could be - populations of rabbits and foxes.

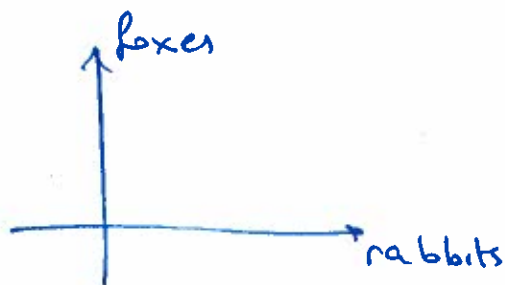
linear operator could be encoding how these populations influence each other:

- number of rabbits eaten by foxes is proportional to the number of foxes.

$$\begin{matrix} r & f \\ r & \begin{pmatrix} a_{11} & * \\ a_{21} & * \end{pmatrix} \\ f & \end{matrix}$$

born: proportional to how many you have

initial state: $\begin{pmatrix} R_0 \\ F_0 \end{pmatrix}$ ← # rabbits
 ← # foxes



$$\begin{pmatrix} R_1 \\ F_1 \end{pmatrix} = A \cdot \begin{pmatrix} R_0 \\ F_0 \end{pmatrix}$$

↑ populations after 1 year

↑ 2x2 matrix based on your predictions

$$R_1 = a_{11} R_0 + a_{12} F_0$$

↑ neg. number accounting for fox food.

↑ positive number "percentage of births" and death of rabbits.

After one year: $\begin{pmatrix} R_1 \\ F_1 \end{pmatrix} = A \begin{pmatrix} R_0 \\ F_0 \end{pmatrix}$

After n years: $\begin{pmatrix} R_n \\ F_n \end{pmatrix} = A^n \begin{pmatrix} R_0 \\ F_0 \end{pmatrix}$

(Note: you could have seen predator-prey model in terms of differential equations:

~~$f(t), r(t)$~~ $f(t), r(t)$ - # foxes/rabbits at time t .

$f'(t) = a_{11} f(t) + a_{12} r(t)$

Our model is a discrete version of this.

(no individual states, not continuous time).



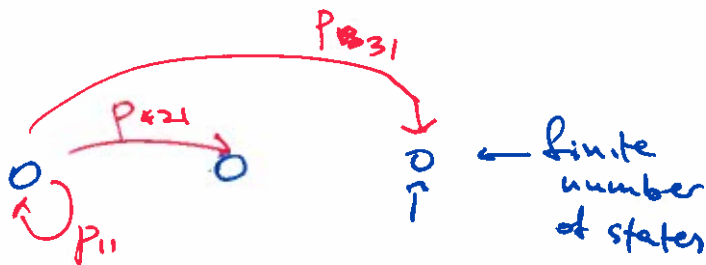
(Note: look at linear recurrences).

In many situations, such a system will approach a steady state: from any initial state, it will approach some fixed state as n gets large. ("equilibrium").

Finite automaton

Markov chain

"vending machine"



Your imaginary machine is a list of probabilities P_{ji} of going from state i to state j

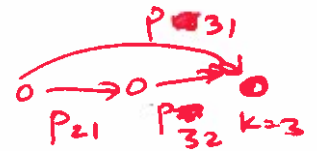
$P_{ij} \geq 0$. $\sum_{j=1}^n P_{ij} = 1$ ← we have to go somewhere from state i

Let $\bar{s} = (s_1, \dots, s_n)$ ← probabilities of our states.
(initially)

Let $P = (p_{ij})$

The new probabilities are $P\bar{s}$

$$\begin{pmatrix} p_{11} & p_{12} & \dots & p_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ p_{k1} & \dots & \dots & p_{kn} \end{pmatrix} \begin{pmatrix} s_1 \\ \vdots \\ s_n \end{pmatrix}$$



The ~~kth~~ coordinate of this vector is the probability that we ended up in state k :
we could have ~~to~~ come to it from:
state 1 with prob. $p_{k1} \cdot s_1$

+
state 2 with prob. $p_{k2} \cdot s_2$



$$\sum_{j=1}^n p_{kj} s_j = \text{the } k^{\text{th}} \text{ entry of } P\bar{s}$$

The properties of P :

- $p_{ij} \geq 0$
 - columns sum to 1.
- } positive
stochastic
matrix

(Note: predator-prey model doesn't satisfy these conditions).

Perron - Frobenius Theorem

- 1) A stochastic matrix has eigenvalue 1 and unique (up to scaling) eigenvector corr. to this eigenvalue
- 2) All other eigenvalues satisfy $|\lambda| < 1$.
(if $a_{ij} > 0$).

Pf: Let A be a stochastic matrix.
Consider A^T - the transpose of A .

Then the rows of A^T sum to 1.

$$A^T \cdot \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} = \begin{pmatrix} \text{sum of row 1} \\ - \\ \text{sum of row } n \end{pmatrix} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$$

← eigenvector of A^T with eigenvalue 1

But A and A^T have the same char. poly.

$$= \det(A - \lambda I) = \det(A^T - \lambda I^T) = \det(A - \lambda I)$$

↑
transpose doesn't affect det.

So 1 is an eigenvalue of A

So there must be an eigenvector of A .

$Aw = w$, Then $A^n w = w$. ← "steady state"

2) $Av = \lambda v$

$$\left(\sum_{j=1}^n a_{jk} v_j \right)_{k=1}^n$$

← easy to check.

$$|\sum a_{jk} v_j| \leq \sum |a_{jk}| |v_j| \leq v_j \underbrace{(\sum |a_{jk}|)}_1 \Rightarrow |\lambda| < 1.$$

When A is diagonalizable, this means:

$$A^m = C^{-1} \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_m \end{pmatrix}^m C$$

$$\lambda_1 = 1.$$

$\rightarrow 0$ as $m \rightarrow \infty$
b/c $|\lambda_i| < 1$ for $i \neq 1$.

So: $A^m \rightarrow$ projector onto the
1-dim subspace spanned
by the steady state w .

Ex: Google page rank is the steady state of the
"google matrix".
(see the link on the webpage)