

Today: • Equivalence of matrices
changes of basis

• State Jordan Normal form Theorem. (also rank them? - easy!)

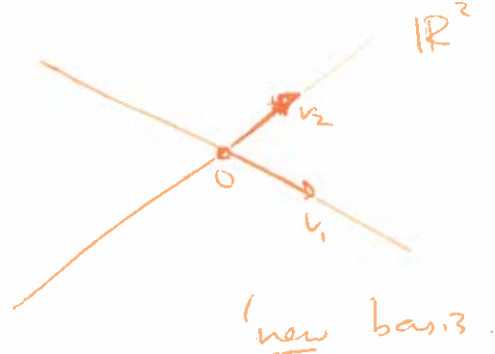
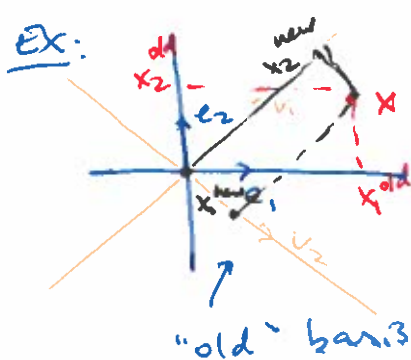
Changes of basis

V - vector space over F .

$\{v_1, \dots, v_n\}^{\text{old}}$ - a basis of V

$\{v_1, \dots, v_n\}^{\text{new}}$ - a new basis of V .

(Recall: they have the same number of elements, $n = \dim(V)$).



(often: old basis is $\{e_1, \dots, e_n\}$ - standard basis of F^n)

How do the old coords of x relate to the new coords of x ?

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{old}} = x_1^{\text{old}} v_1^{\text{old}} + \dots + x_n^{\text{old}} v_n^{\text{old}}$$

Also

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{new}} = x_1^{\text{new}} v_1^{\text{new}} + \dots + x_n^{\text{new}} v_n^{\text{new}}$$

Geometrically hard to relate $\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{new}}$ to $\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{old}}$.

We solve this question algebraically:

we make a transition matrix C :

Columns of C are the coordinates of the new basis vectors in the old basis.

Example: Old basis: $\{e_1, e_2\}$ in \mathbb{R}^2

New basis: $v_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ $v_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

$$X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^{\text{old}}$$

What are the new coordinates?

↑ usual standard coords.

We make C : $\begin{bmatrix} 2 & 2 \\ 1 & -1 \end{bmatrix}$ - our transition matrix

Aside: you could make a mean example:
 $\{v_1, \dots, v_n\}$ - not the standard basis; given in terms of e_1, \dots, e_n
 $\{w_1, \dots, w_n\}$ - another one. - given in terms of e_1, \dots, e_n .

Transition from $\{v_1, \dots, v_n\}$ to $\{w_1, \dots, w_n\}$?

Answer: C_1 = transition matrix from $\{e_1, \dots, e_n\}$ to $\{v_1, \dots, v_n\}$

C_2 - transition from $\{e_1, \dots, e_n\}$ to $\{w_1, \dots, w_n\}$

$$C_1 = \begin{bmatrix} \boxed{} \\ \vdots \\ \boxed{} \end{bmatrix}$$

↑ coords of v_i w.r.t. $\{e_1, \dots, e_n\}$

$$C_2 = \begin{bmatrix} \boxed{} \\ \vdots \\ \boxed{} \end{bmatrix}$$

↑ coords of w_i w.r.t. $\{e_1, \dots, e_n\}$

To go from the v 's to the w 's:

$$C^{-1} = C_2^{-1} C_1 \rightsquigarrow$$

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{new}, v} = C_1^{-1} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{standard}}$$

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^w = C_2^{-1} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{standard}}$$

We have:

$$X^{\text{old}} = C \cdot X^{\text{new}}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = C \cdot \begin{bmatrix} x_1^{\text{new}} \\ x_2^{\text{new}} \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1^{\text{new}} \\ x_2^{\text{new}} \end{bmatrix}$$

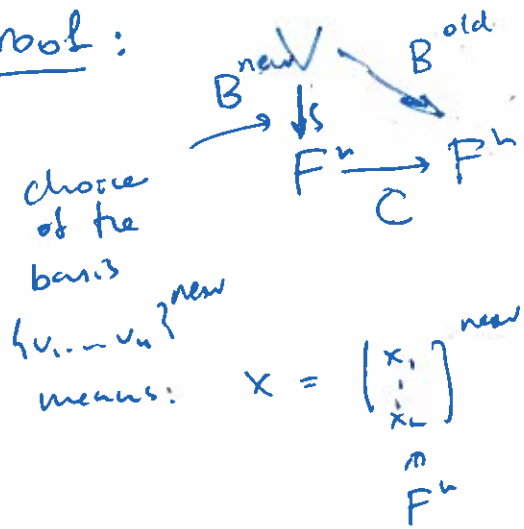
Then

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^{\text{new}} = C^{-1} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^{\text{old}}$$

why does C^{-1} exist?

We know: columns of C form a basis, so $\text{rk}(C) = n$
 then C^{-1} exists (b/c $\dim(\ker(C)) = n - \text{rk}(C) = 0$.)

Proof:



$$B: V \rightarrow F^n \quad (\text{old or new})$$

- the bijective linear operator that comes from a choice of a basis.

sends a vector to a tuple of its coords

C : columns are coords of the new basis w.r.t. the old basis:

it gives a map: $V \rightarrow V$ which takes old basis vectors to the new ones, but

what we are looking for is a map: $F^n \rightarrow F^n$ that agrees with it

(that would be the relation on the $\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}^{\text{old}}$ and

have: on the new basis vectors v_i^{new} $\xrightarrow{B^{\text{old}}}$ $\begin{bmatrix} v \\ \vdots \\ v \end{bmatrix}$ and $B^{\text{new}}(v_i^{\text{new}}) = e_i$

Then $C B^{\text{new}}(v_i^{\text{new}}) = B^{\text{old}}(v_i^{\text{new}})$

$$x^{\text{old}} = C x^{\text{new}}$$

" $B^{\text{old}}(x)$ " $B^{\text{new}}(x)$

Then $B^{\text{old}}(x) = C B^{\text{new}}(x)$

For linear operators

$A: V \rightarrow V$ - lin. op.

has matrix A^{old} w.r.t. the old basis $\{v_1, \dots, v_n\}^{old}$
 A^{new} ———— $\{v_1, \dots, v_n\}^{new}$.

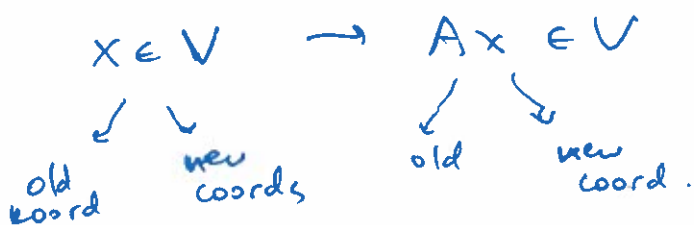
How are these matrices related?

$$X^{new} = C^{-1} X^{old}$$

$$\underbrace{\begin{pmatrix} A^{old} & X^{old} \end{pmatrix}}_{\vec{V}}^{old} = \underbrace{\begin{pmatrix} A^{new} & X^{new} \end{pmatrix}}_{\vec{V}}^{new}$$

both are expressions for Ax

lin. operator
 Ax
 $(Ax^{old})^{new}$ makes almost no sense



Then: $C^{-1} A^{old} X^{old} = A^{new} X^{new}$

$$C^{-1} A^{old} C X^{new} = A^{new} X^{new}$$

$$A^{new} = C^{-1} A^{old} C$$

Example: $C = \begin{bmatrix} 2 & 2 \\ 1 & -1 \end{bmatrix}$ $A = \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix}$

recall: $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 2 \\ -1 \end{bmatrix}$ were eigenvectors for A

compute $C^{-1} A C$: $C^{-1} = \begin{bmatrix} -1 & -2 \\ -1 & 2 \end{bmatrix} \cdot \frac{1}{-4}$ "det A"

using $\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{\det A} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \begin{bmatrix} 1/4 & 1/2 \\ 1/4 & -1/2 \end{bmatrix}$

$$C^{-1} \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix} C = \begin{bmatrix} 1/4 & 1/2 \\ 1/4 & -1/2 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 1 & -1 \end{bmatrix}$$

$\leftarrow A^{new}$

it does "it" \rightarrow expect $= \begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix}$ 4