

# The Principle of Least Action

We have seen in class that Newton's law,  $\frac{1}{2}m\ddot{\vec{x}}(t) = -\vec{\nabla}U(\vec{x}(t))$  for the motion of a particle in a potential well is equivalent to the stationarity of the action

$$S_{[t_1, t_2]} \{ \vec{x}(t) \} = \int_{t_1}^{t_2} L(\vec{x}(t), \dot{\vec{x}}(t)) dt \quad \text{with Lagrangian} \quad L(\vec{x}, \vec{v}) = \frac{1}{2}m\vec{v}^2 - U(\vec{x})$$

This is known as the ‘‘Principle of Least Action’’ (or Hamilton's Principle). Here is the Theorem which provides the motivation for that name.

**Theorem.** *Let  $\vec{x}(t)$  be a stationary curve for the Lagrangian  $L(\vec{x}, \vec{v}) = \frac{1}{2}m\vec{v}^2 - U(\vec{x})$  on the interval  $a \leq t \leq b$ . Then there exists a  $\delta > 0$  (depending on  $m$ , the potential  $U(\vec{x})$  and the curve  $\vec{x}(t)$ ) such that whenever*

- $a \leq t_1 < t_2 \leq b$  with  $t_2 - t_1 \leq \delta$
  - $\vec{\zeta} : [t_1, t_2] \rightarrow \mathbb{R}^n$  is a  $C^\infty$  curve obeying  $\vec{\zeta}(t_1) = \vec{0}$ ,  $\dot{\vec{\zeta}}(t_2) = \vec{0}$  and  $|\dot{\vec{\zeta}}(t)| \leq 1$  for all  $t_1 \leq t \leq t_2$
- then

$$S_{[t_1, t_2]} \{ \vec{x}(t) + \vec{\zeta}(t) \} \geq S_{[t_1, t_2]} \{ \vec{x}(t) \}$$

Thus  $\vec{x}(t)$  is a local minimum of the action for short time intervals.

**Proof:** We wish to show that

$$\begin{aligned} \Delta &\equiv S_{[t_1, t_2]} \{ \vec{x}(t) + \vec{\zeta}(t) \} - S_{[t_1, t_2]} \{ \vec{x}(t) \} \\ &= \int_{t_1}^{t_2} dt \left[ \frac{1}{2}m\dot{\vec{\zeta}}(t)^2 + m\dot{\vec{x}}(t) \cdot \dot{\vec{\zeta}}(t) - U(\vec{x}(t) + \vec{\zeta}(t)) + U(\vec{x}(t)) \right] \end{aligned}$$

is positive. Taylor expanding  $f(\eta) = -U(\vec{x}(t) + \eta\vec{\zeta}(t)) + U(\vec{x}(t))$  to second order in  $\eta$ , including the remainder, and then setting  $\eta = 1$  gives

$$\begin{aligned} -U(\vec{x} + \vec{\zeta}) + U(\vec{x}) &= f(1) = f(0) + f'(0) + \frac{1}{2}f''(\bar{\eta}) \\ &= -\vec{\zeta} \cdot \frac{\partial U}{\partial \vec{x}}(\vec{x}) - \frac{1}{2} \sum_{i,j=1}^n \zeta_i \zeta_j \frac{\partial}{\partial x_i} \frac{\partial}{\partial x_j} U(\vec{x} + \bar{\eta}\vec{\zeta}) \end{aligned}$$

for some  $0 \leq \bar{\eta} \leq 1$  (depending on  $t$ ). For all  $0 \leq \bar{\eta} \leq 1$  and all  $t_1 \leq t \leq t_2$  and all  $\vec{\zeta}$  of magnitude at most one,  $\vec{x}(t) + \bar{\eta}\vec{\zeta}$  lies within distance one of the compact set  $\mathcal{X} = \{ \vec{x}(t) \mid t_1 \leq t \leq t_2 \}$ . The set of all points of distance at most one from  $\mathcal{X}$  is again compact. Hence there is a finite constant  $M$  such that

$$-U(\vec{x} + \vec{\zeta}) + U(\vec{x}) \geq -\vec{\zeta} \cdot \frac{\partial U}{\partial \vec{x}}(\vec{x}) - M|\vec{\zeta}|^2$$

Hence

$$\Delta \geq \int_{t_1}^{t_2} dt \left[ \frac{1}{2}m\dot{\vec{\zeta}}(t)^2 - M\vec{\zeta}(t)^2 \right] + \int_{t_1}^{t_2} dt \left[ m\dot{\vec{x}}(t) \cdot \dot{\vec{\zeta}}(t) - \vec{\zeta}(t) \cdot \frac{\partial U}{\partial \vec{x}}(\vec{x}(t)) \right] \quad (1)$$

Now the second integral is exactly  $\left. \frac{d}{d\varepsilon} S_{[t_1, t_2]} \{ \vec{x}(t) + \varepsilon\vec{\zeta}(t) \} \right|_{\varepsilon=0}$  and hence is zero by the stationarity of  $\vec{x}(t)$ . (Note that, since  $\vec{x}(t)$  is stationary on  $[a, b]$ , it obeys the Euler–Lagrange equation on  $[a, b]$ . So it also obeys

the Euler–Lagrange equation on  $[t_1, t_2] \subset [a, b]$  and so is stationary for  $[t_1, t_2]$  too.) For the first integral we use

$$\begin{aligned} |\zeta_i(t)| &= \left| \int_{t_1}^t \dot{\zeta}_i(s) ds \right| \quad (\text{Recall that } \vec{\zeta}(t_1) = 0.) \\ &\leq \left[ \int_{t_1}^t 1 ds \right]^{1/2} \left[ \int_{t_1}^t \dot{\zeta}_i(s)^2 ds \right]^{1/2} \quad (\text{by the Cauchy–Schwarz inequality}) \\ &= [t - t_1]^{1/2} \left[ \int_{t_1}^t \dot{\zeta}_i(s)^2 ds \right]^{1/2} \end{aligned}$$

which implies that

$$\vec{\zeta}(t)^2 \leq [t - t_1] \int_{t_1}^t \dot{\vec{\zeta}}(s)^2 ds \leq [t - t_1] \int_{t_1}^{t_2} \dot{\vec{\zeta}}(s)^2 ds$$

and

$$\int_{t_1}^{t_2} \vec{\zeta}(t)^2 dt \leq \int_{t_1}^{t_2} \dot{\vec{\zeta}}(s)^2 ds \int_{t_1}^{t_2} [t - t_1] dt = \frac{1}{2} [t_2 - t_1]^2 \int_{t_1}^{t_2} \dot{\vec{\zeta}}(s)^2 ds \quad (2)$$

Substituting (2) into (1) gives

$$\Delta \geq \int_{t_1}^{t_2} dt \frac{1}{2} (m - M[t_2 - t_1]^2) \dot{\vec{\zeta}}(t)^2 \geq 0$$

provided  $m - M[t_2 - t_1]^2 \geq 0$ , or equivalently,

$$t_2 - t_1 \leq \sqrt{\frac{m}{M}} \equiv \delta$$

■

**Example.** We illustrate this result using dimension  $n = 1$ , the harmonic oscillator Lagrangian  $L(x, v) = \frac{1}{2}[v^2 - x^2]$ , interval  $[a, b] = [t_1, t_2] = [0, \mu\pi]$  for noninteger positive  $\mu$  and boundary conditions  $x(0) = x(\mu\pi) = 0$ . The Euler–Lagrange equation is  $\ddot{x} + x = 0$ . The general solution to this equation is  $x(t) = A \sin t + B \cos t$ . The condition  $x(0) = 0$  forces  $B = 0$  and the condition  $x(\mu\pi) = A \sin(\mu\pi) = 0$  forces  $A = 0$ , so the only stationary curve is  $x(t) = 0$  and the corresponding action  $S\{x(t)\} = 0$ . Denote

$$\zeta_{\varepsilon, k} = \varepsilon \sin\left(\frac{k}{\mu}t\right)$$

Then

$$\begin{aligned} S\{\zeta_{\varepsilon, k}\} &= \int_0^{\mu\pi} \frac{1}{2} \left[ \varepsilon^2 \left(\frac{k}{\mu}\right)^2 \cos^2\left(\frac{k}{\mu}t\right) - \varepsilon^2 \sin^2\left(\frac{k}{\mu}t\right) \right] dt \\ &= \frac{1}{2} \mu \varepsilon^2 \int_0^{\pi} \left[ \left(\frac{k}{\mu}\right)^2 \cos^2(ks) - \sin^2(ks) \right] ds \quad \text{with } t = \mu s \\ &= \frac{\pi}{4} \mu \varepsilon^2 \left[ \left(\frac{k}{\mu}\right)^2 - 1 \right] \end{aligned}$$

If  $\mu > 1$  (i.e. the time interval is longer than  $\pi$ ), this is negative for  $k < \mu$  and positive for  $k > \mu$ . So we have a saddle point. If  $\mu < 1$ , this is positive for all  $k \in \mathbb{N}$ , which is consistent with having a local minimum.