## The three-dimensional mkpath package

Here are the routines defined in the file mkpath3d.inc. Roughly speaking, the entire package is concerned with building paths in 3D.

ROUTINE:	mkpath3d
ARGUMENTS:	$\ell \ a \ f \ t_0 \ t_f \ N$
RETURNS:	Adds a sequence of Bezier curves to the current path

Here  $\ell$  is the **location matrix**, of the form  $[M \ v]$  where M is a  $3 \times 3$  matrix and v a 3-vector. This is to be interpreted as a rigid affine transformation, describing the shifted position of the path to be drawn. The procedure f is called by name (with /). It has two arguments, an array of parameters and a value of t. Output from f is a three-dimensional parametrization in the format

 $[[x(t) \ y(t) \ z(t)][x'(t) \ y'(t) \ z(t)]]$ 

ROUTINE:	mkpolypath3d
ARGUMENTS:	$\ell \ a \ f \ t_0 \ t_f \ N$
<b>RETURNS</b> :	Adds a sequence of line segments to the current path

Is to mkpath3d as mkpolypath is to mkpath.

ROUTINE:	mkpolygon3d
ARGUMENTS:	A location matrix $\ell$ , an array of $3D$ points $p$
<b>RETURNS</b> :	Adds a sequence of line segments to the current path

The array looks like

 $[[x_0 \ y_0 \ z_0][x_1 \ y_1 \ z_1] \dots [x_n \ y_n \ z_n]]$ 

This can be used to draw a cube or faces of some other polyhedron, for example.

ROUTINE: ARGUMENTS: RETURNS:	<b>use-perspective</b> None Sets up use of perspective for rendering 3 <i>D</i> to 2 <i>D</i>
ROUTINE:	use-projection
ARGUMENTS:	None
RETURNS:	Sets up use of projection

Exactly one of these must be used before any three-dimensional drawing is done. If you don't do this, you will get an error message about **convert** being undefined.