The mkpath package

Here are the routines defined in the file **mkpath.inc**. Roughly speaking, the entire package is concerned with building paths in 2*D*.

ROUTINE:	mkgraph
ARGUMENTS:	$a f x_0 x_f N$
RETURNS:	Adds a sequence of Bezier curves to the current path

The path added has N Bezier curves, along the graph of y = f(x) from x_0 to x_f . The initial array contains parameters passed to the routine f. It is the *name* of the routine f which is passed as an argument (flagged by / in PostScript). The routine f has a fixed interface: it has two arguments, an array of parameters and a single number x, and returns an array [f(x) f'(x)]. The array can be empty, but it must be used in the call to mkgraph, and it must be removed from the stack in the routine f even if it is not used.

To draw the graph of $y = 2x^4$ from x = -1 to x = 1 we might have (among other things)

```
/quartic {
3 dict begin
/x exch def
/pars exch def
/c pars 0 def
[
c x mul x mul x mul x mul
2 c mul x mul x mul x mul
]
end
} def
```

newpath
[2] /quartic -1 1 8 mkgraph
stroke

The number N is to be chosen by experience.

ROUTINE:**mkpath**ARGUMENTS: $a f t_0 t_f N$ RETURNS:Adds a sequence of Bezier curves to the current path

Here the routine *f* amounts to a parametrization of a path. It has arguments [...] t as for mkgraph, and it is to return data of the form

 $[[x(t) \ y(t)][x'(t) \ y'(t)]]$

This routine has a feature the graphing routine does not: it adds the path constructed to the current path by drawing a line from the current point if it exists to the start of the path being built. In this it acts like the command arc in PostScript.

```
/lissajous {
4 dict begin
/t exch 180 mul 3.1416 div def
/pars exch def
/m pars 0 get
/n pars 1 get
[
[t m mul cos t n mul cos]
[t m mul sin neg t n mul sin neg]
```

] end } def

newpath [2 3] /lissajous 0 6.28 8 mkpath stroke

ROUTINE:mkpolypathARGUMENTS: $a f t_0 t_f N$ RETURNS:Adds a sequence of line segments to the current path

This has exactly the same calling setup as mkpath, but ignores the derivative in order to build a sequence of straight segments from one position to the next. Its purpose is to help you debug your parametrization routine, to separate the derivative calculation from the position calculation.