

## Midterm Exam I

October 3, 2008

No books. No notes. No calculators. No electronic devices of any kind.

Name \_\_\_\_\_ Student Number \_\_\_\_\_

**Problem 1.** (5 points)

The cone with equation  $y^2 + z^2 = x^2$  and the plane with equation  $x + z = 4$  intersect in a curve  $C$ . Find the curvature of  $C$  at the point  $\langle 2, 0, 2 \rangle$ .

use  $t = y$ . Then  $t^2 + z^2 = x^2$  and  $x + z = 4$ , which we solve for  $x$  and  $z$  to get  $x = 2 + \frac{1}{8}t^2$   $y = t$   $z = 2 - \frac{1}{8}t^2$ .

$$\text{So } \vec{r}(t) = \langle 2 + \frac{1}{8}t^2, t, 2 - \frac{1}{8}t^2 \rangle$$

$$\vec{r}'(t) = \langle \frac{1}{4}t, 1, -\frac{1}{4}t \rangle$$

$$\vec{r}''(t) = \langle \frac{1}{4}, 0, -\frac{1}{4} \rangle.$$

The point  $\langle 2, 0, 2 \rangle$  corresponds to  $t = 0$ :

$$\vec{r}'(0) = \langle 0, 1, 0 \rangle$$

$$\vec{r}''(0) = \langle \frac{1}{4}, 0, -\frac{1}{4} \rangle.$$

$$\text{So } k(0) = \frac{|\vec{r}'(0) \times \vec{r}''(0)|}{|\vec{r}'(0)|^3} = \frac{|\langle 0, 1, 0 \rangle \times \langle \frac{1}{4}, 0, -\frac{1}{4} \rangle|}{|\langle 0, 1, 0 \rangle|^3} = \frac{|\langle -\frac{1}{4}, 0, -\frac{1}{4} \rangle|}{1^3} = \frac{\sqrt{2}}{4}.$$

Problem 1. continued.

Remark 1. If you use the formula  $k(0) = \frac{|\vec{T}'(0)|}{|\vec{r}'(0)|}$

you have to be very careful:

$\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$  At this point you cannot substitute  $|\vec{r}'(0)|$  in the denominator, because the formula for  $k(0)$  still requires you to differentiate  $\vec{T}(t)$ .

So you cannot use  $\vec{T}(t) = \langle \frac{1}{4}t, 1, -\frac{1}{4}t \rangle$  instead you have to use:

$$\vec{T}(t) = \frac{1}{\sqrt{t^2/8 + 1}} \langle \frac{1}{4}t, 1, -\frac{1}{4}t \rangle.$$

(Only because, by coincidence, the derivative of  $\frac{1}{\sqrt{t^2/8 + 1}}$  vanishes at  $t=0$  do you still get the correct answer.)

Remark 2. If you use  $x=t$ , you get  $\vec{r}(t) = \langle t, \sqrt{8t-16}, 4-t \rangle$ , which requires  $8t-16 \geq 0$  or  $t \geq 2$ . If you want to differentiate, it requires  $t > 2$ . (The domain of  $\vec{r}'(t) = \langle 1, \frac{8}{\sqrt{8t-16}}, -1 \rangle$  is  $t > 2$ .)

So this parametrization is not suitable for computing  $k(2)$ .

(It corresponds to speeding up to infinite speed as  $t \downarrow 2$ .)

1	2	3	4	5	6	total/22

**Problem 2.** (6 points)

The spiral  $C$  in the plane is parametrized by the vector function

$$\vec{r}(t) = e^t \langle \cos t, \sin t \rangle$$

- (a) Find the arclength of the part of  $C$  which is parametrized by the interval  $(-\infty, 0]$ .
- (b) Reparametrize  $C$  using arc-length measured from  $t = -\infty$ .

$$\vec{r}'(t) = e^t \langle \cos t, \sin t \rangle + e^t \langle -\sin t, \cos t \rangle \quad \text{by product rule.}$$

$$= e^t \langle \cos t - \sin t, \cos t + \sin t \rangle$$

$$|\vec{r}'(t)| = e^t \sqrt{(\cos t - \sin t)^2 + (\cos t + \sin t)^2}$$

$$= \sqrt{2} e^t.$$

$$(a) \quad L = \int_{-\infty}^0 |\vec{r}'(u)| du = \int_{-\infty}^0 \sqrt{2} e^u du = \sqrt{2} e^u \Big|_{-\infty}^0 = \sqrt{2} - 0 = \sqrt{2}.$$

This calculation is justified, because  $\lim_{u \rightarrow -\infty} \sqrt{2} e^u = 0$ .

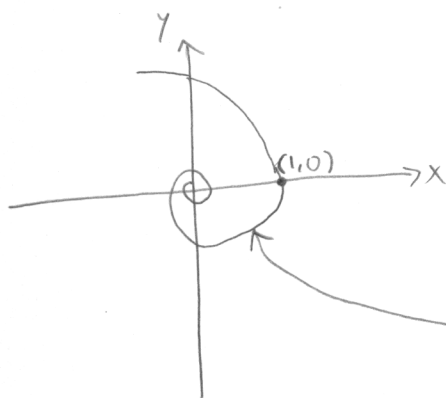
$$(b) \quad s = \int_{-\infty}^t |\vec{r}'(u)| du = \int_{-\infty}^t \sqrt{2} e^u du = \sqrt{2} e^u \Big|_{-\infty}^t = \sqrt{2} e^t - 0 = \sqrt{2} e^t.$$

Solve  $s = \sqrt{2} e^t$  for  $t$ :  $e^t = \frac{\sqrt{2}}{2} s$   $t = \ln\left(\frac{\sqrt{2}}{2} s\right)$

So

$$\vec{r}(s) = \frac{\sqrt{2}}{2} s \langle \cos \ln \frac{\sqrt{2}}{2} s, \sin \ln \frac{\sqrt{2}}{2} s \rangle \quad \text{with domain } s > 0.$$

## Problem 2 cont'd.



Note that the spiral spirals towards the origin so quickly that the total arclength of this part is finite ( $=\sqrt{2}$ ), even though the spiral spirals around the origin infinitely many times.

Note that the original parametrization had domain  $t \in (-\infty, \infty) = \mathbb{R}$   
the new parametrization has domain  $s \in (0, \infty)$  or  $s > 0$ .

For (b): We know that speed  $= |\vec{r}'(t)| = \frac{ds}{dt} = \sqrt{2}e^t$ ,

so  $s = \sqrt{2}e^t + C$  (indefinite instead of definite  
(improper) integral.)

You still need to justify why the constant of integration is  $C = 0$ .

For example, set  $t=0$ :  $s(0) = \sqrt{2} + C$ , but  $s(0) = \sqrt{2}$  from (a),

so  $C = 0$ .

**Problem 3.** (3 points)

True or false? (Assume that a curve  $C$  is parametrized by a twice continuously differentiable vector function  $\vec{r}(t)$ .)

- (a) at a time  $t$  where  $|\vec{v}(t)|$  reaches a maximum, we necessarily have  $\vec{a}(t) \perp \vec{v}(t)$ .  
 (b) at a time  $t$  where  $|\vec{v}(t)|$  is not zero and  $\vec{a}(t) \parallel \vec{v}(t)$ , the curvature  $\kappa(t)$  vanishes.  
 (c) at a time  $t$  where  $|\vec{v}(t)|$  vanishes, we must have that  $\vec{a}(t)$  is tangent to the curve.

All of these can be solved with the formula

$$\vec{a} = v' \vec{T} + \kappa v^2 \vec{N}.$$

- (a) if  $v$  reaches a maximum, then  $v' = 0$ , so  $\vec{a} \parallel \vec{N}$ , so  $\vec{a} \perp \vec{T}$ ,  
 so  $\vec{a} \perp \vec{v}$ . TRUE.

note that this remains true, even if  $\vec{N}$  is not defined, because  $\kappa = 0$ .

(in this case we still have  $\vec{a} = v' \vec{T}$ , so  $v' = 0$  implies  $\vec{a} = \vec{0}$ , and so  $\vec{a} \perp \vec{v}$  because  $\vec{0}$  is  $\perp$  to every vector)

(note also, that if  $\vec{T}$  is not defined because  $v = 0$ , then  $v = 0$  being a maximum means that  $v = 0$  everywhere, so that no movement is taking place,  $\vec{a} = \vec{0}$  and  $\vec{v} = \vec{0}$  in this case, still we have  $\vec{a} \perp \vec{v}$ .)

- (b)  $\vec{a} \parallel \vec{v}$  means  $\vec{a} \parallel \vec{T}$  so  $a_N = 0$ , so  $\kappa v^2 = 0$ . But then  $v^2 = 0$   
 implies  $\kappa = 0$ . TRUE.

[You may object that  $\kappa = 0$  means that  $\vec{N}$  is not defined, but that objection is not relevant. If both  $v$  and  $\kappa$  are not zero, then  $\vec{T}$  and  $\vec{N}$  and the above formula are defined, and the argument (b) shows that we get a contradiction, which (as  $v \neq 0$ ) can only be resolved by  $\kappa = 0$ .]

(c) if  $v=0$ , then  $a_N=0$  and so  $\vec{a} \parallel \vec{T}$ .

TRUE.

(If  $\vec{a} \nparallel \vec{T}$  then  $a_N \neq 0$  and so  $k \neq 0$  and  $v \neq 0$ .)

If you object, because  $v=0$  means the formulas for  $a_T$  and  $a_N$  don't work, here is a more detailed argument.

There has to be some parameter  $u$ , such that  $\frac{d\vec{r}}{du} \neq \vec{0}$

We have

$$\vec{a} = \frac{d^2\vec{r}}{dt^2} = \frac{d}{dt} \left( \frac{d\vec{r}}{du} \frac{du}{dt} \right) = \frac{d^2\vec{r}}{du^2} \left( \frac{du}{dt} \right)^2 + \frac{d\vec{r}}{du} \frac{d^2u}{dt^2}$$

and  $\frac{d\vec{r}}{dt} = \frac{d\vec{r}}{du} \frac{du}{dt}$  so  $v=0$  implies  $\vec{v} = \frac{d\vec{r}}{dt} = \vec{0}$ , implies  $\frac{du}{dt} = 0$

(as  $\frac{d\vec{r}}{du} \neq \vec{0}$ ).

so  $\vec{a} = \frac{d\vec{r}}{du} \frac{d^2u}{dt^2} \parallel \frac{d\vec{r}}{du}$  which is a tangent vector to  $C$ .

Important Remark: in (a) (b) (c) we are referring to one point in time, not all pts in time.

For example (b): if  $\vec{a} \parallel \vec{v}$  always then  $k=0$  always  $\rightarrow$  line

but if we just have  $\vec{a}(0) \parallel \vec{v}(0)$  we have  $k(0)=0$ , but  $C$  does not have to be a line.

(c): if  $\vec{v}(0) = \vec{0}$  it does not follow that  $\vec{a}(0) = \vec{0}$ .

**Problem 4.** (4 points)

The curve  $C$  is parametrized by the vector function

$$\vec{r}(t) = \langle t, e^{-t}, \cos t \rangle$$

Find an equation for the normal plane to  $C$  at the point corresponding to the parameter value  $t = 0$ .

$$\vec{r}'(t) = \langle 1, -e^{-t}, -\sin t \rangle$$

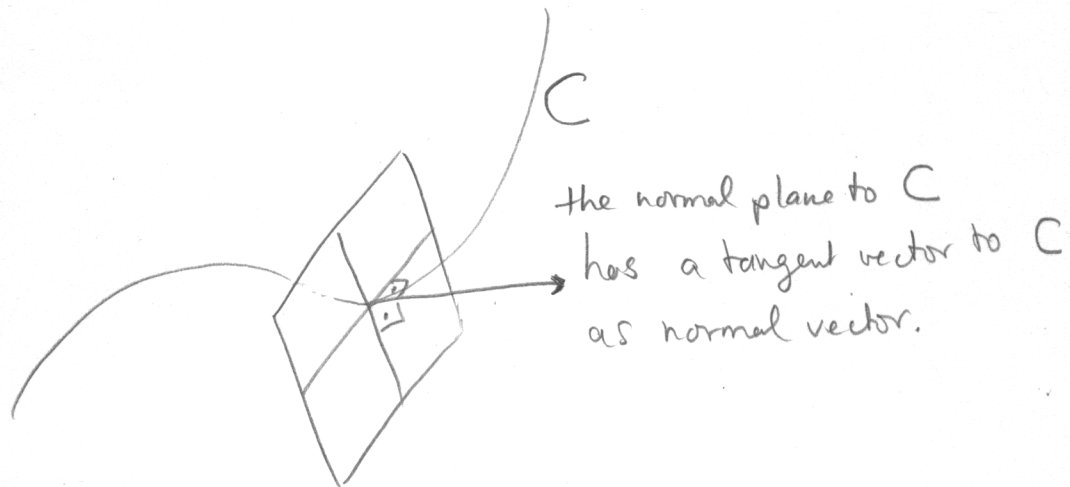
$$\vec{r}'(0) = \langle 1, -1, 0 \rangle \text{ tangent to } C, \text{ normal to normal plane,}$$

So equation is

$$\langle 1, -1, 0 \rangle \cdot (\langle x, y, z \rangle - \langle 0, 1, 1 \rangle) = 0$$

$$\langle 1, -1, 0 \rangle \cdot \langle x, y-1, z-1 \rangle = 0$$

$$\boxed{x - y + 1 = 0}$$



**Problem 5.** (4 points)

The derivative  $\frac{d}{dt}|\vec{r}'(t)|$  is given by

- (a)  $|\vec{r}''(t)|$ ,  
 (b)  $2\vec{r}'(t) \cdot \vec{r}''(t)$ ,  
 → (c)  $\frac{\vec{r}'(t) \cdot \vec{r}''(t)}{|\vec{r}'(t)|}$ ,  
 (d) 0  
 (e) non of the above.

The derivative  $\frac{d}{dt}(\vec{r}(t) \times \vec{r}'(t))$  is equal to

- (a)  $\vec{r}'(t) \times \vec{r}'(t)$ ,  
 → (b)  $\vec{r}(t) \times \vec{r}''(t)$ ,  
 (c)  $\vec{r}'(t) \times \vec{r}''(t) + \vec{r}(t) \times \vec{r}''(t)$   
 (d)  $\vec{r}(t) \times \vec{r}'(t) + \vec{r}(t) \times \vec{r}''(t)$   
 (e) none of the above.

$$\begin{aligned} \frac{d}{dt}|\vec{r}'| &= \frac{d}{dt} \sqrt{\vec{r}' \cdot \vec{r}'} = \frac{1}{2\sqrt{\vec{r}' \cdot \vec{r}'}} \frac{d}{dt}(\vec{r}' \cdot \vec{r}') \\ &= \frac{1}{2|\vec{r}'|} (\vec{r}'' \cdot \vec{r}' + \vec{r}' \cdot \vec{r}'') = \frac{2\vec{r}' \cdot \vec{r}''}{2|\vec{r}'|} = \frac{\vec{r}' \cdot \vec{r}''}{|\vec{r}'|} \quad (c). \end{aligned}$$

$$\frac{d}{dt}(\vec{r} \times \vec{r}') = \underbrace{\vec{r}' \times \vec{r}'}_{\vec{0}} + \vec{r} \times \vec{r}'' = \vec{r} \times \vec{r}'' \quad (b).$$

b/c  $\vec{r}' \parallel \vec{r}'$