

Midterm Exam I

October 2, 20123

No books. No notes. No calculators. No electronic devices of any kind.

Name _____ Student Number _____

Problem 1. (6 points)

The hyperboloid of one sheet with equation $x^2 + 4y^2 - z^2 = 16$ and the plane with equation $x + z = 2$ intersect in a curve C .

- (a) Sketch the projection of C into the xy -plane.
- (b) Find a parametric vector equation for the tangent line to C at the point $\langle 4, 1, -2 \rangle$.

Hint: use $y = t$ to parametrize C .

Parametrize C : substitute $y = t$ into $x^2 + 4y^2 - z^2 = 16$ to get

$x^2 + 4t^2 - z^2 = 16$. To solve for x in terms of t , use

the second equation $x + z = 2$ to eliminate z . Solve for z :

$z = 2 - x$, substitute into $x^2 + 4t^2 - z^2 = 16$ to get

$$x^2 + 4t^2 - (2 - x)^2 = 16$$

$$x^2 + 4t^2 - 4 + 4x - x^2 = 16$$

$$4t^2 + 4x = 20$$

$$x = 5 - t^2$$

Substitute into $z = 2 - x$ to get $z = 2 - (5 - t^2) = t^2 - 3$.

So $\boxed{\vec{r}(t) = \langle 5 - t^2, t, t^2 - 3 \rangle}$ is a parametrization of C .

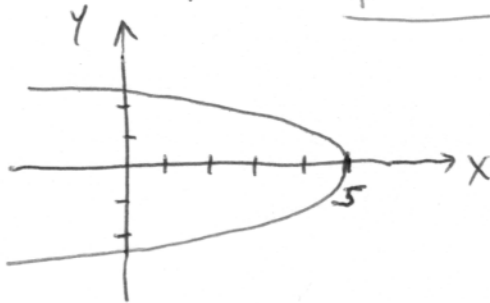
(continued)

1	2	3	4	5	total/21

Overflow space

(a) The xy -projection is parametrized by $\begin{cases} x = 5 - t^2 \\ y = t \end{cases}$

and has equation $\boxed{x = 5 - y^2}$. This is a parabola:



(b) $\vec{r}(t) = \langle 5 - t^2, t, t^2 - 3 \rangle$

$\vec{r}'(t) = \langle -2t, 1, 2t \rangle$

$\vec{r}(1) = \langle 4, 1, -2 \rangle$ this is the point we want, $t = 1$.

$\vec{r}'(1) = \langle -2, 1, 2 \rangle$

parametric vector equation for the tangent line:

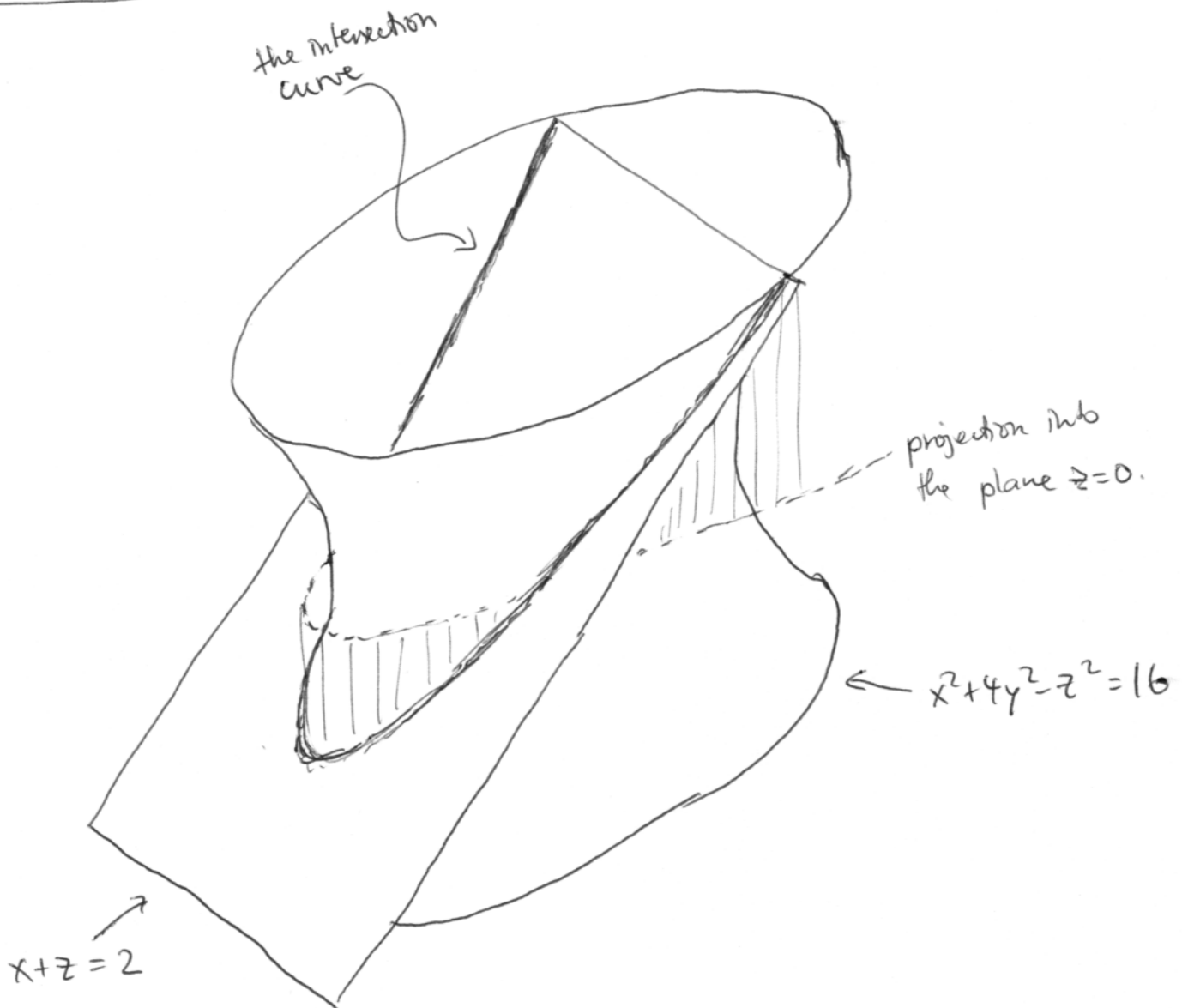
$\boxed{\langle 4, 1, -2 \rangle + t \langle -2, 1, 2 \rangle}$

Remark.

Finding the projection into the xy -plane does not mean setting $z=0$.

Setting $z=0$ gives the intersection with the xy -plane.

Eliminating z from the equations will give the projection.



Problem 2. (4 points)The curve C is parametrized by the vector function

$$\vec{r}(t) = \langle t^3, 2, t^2 \rangle$$

Find the arc length of the part of C which is between the points $\langle 0, 2, 0 \rangle$ and $\langle 27, 2, 9 \rangle$.

Hint: the integral can be solved with a simple substitution.

$$\vec{r} = \langle t^3, 2, t^2 \rangle \quad \text{on the interval } t \in [0, 3]$$

b/c $\vec{r}(0) = \langle 0, 2, 0 \rangle$ and $\vec{r}(3) = \langle 27, 2, 9 \rangle$.

$$\vec{r}' = \langle 3t^2, 0, 2t \rangle$$

$$\|\vec{r}'\| = \sqrt{9t^4 + 4t^2} = \sqrt{9t^2 + 4} \sqrt{t^2} = \sqrt{9t^2 + 4} t \quad \text{b/c } t \geq 0 \text{ on the interval.}$$

$$ds = \|\vec{r}'\| dt = \sqrt{9t^2 + 4} t dt$$

The arc-length is

~~$$\int_C ds = \int_0^3 \sqrt{9t^2 + 4} t dt$$~~

$$\begin{aligned}
 \int_C ds &= \int_0^3 \sqrt{9t^2 + 4} t dt && u = 9t^2 + 4 \\
 &&& du = 18t dt \\
 &= \frac{1}{18} \int_4^{85} \sqrt{u} du && = \frac{1}{18} \left. \frac{2}{3} u^{3/2} \right|_4^{85} = \frac{1}{27} (85^{3/2} - 4^{3/2}) \\
 &= \frac{1}{27} (85^{3/2} - 8) \\
 &= \frac{85\sqrt{85} - 8}{27}
 \end{aligned}$$

Problem 3. (3 points)

True or false? (Assume that a curve C is parametrized by a twice continuously differentiable vector function $\vec{r}(t)$, with velocity $\vec{v}(t)$, and acceleration $\vec{a}(t)$.)

- (a) at a time t where $\kappa(t)$ reaches a maximum, we necessarily have $\vec{a}(t) \perp \vec{v}(t)$.
 (b) at a time t where $\kappa(t)$ is zero, we must have that $\vec{a}(t) \parallel \vec{v}(t)$.
 (c) Suppose that $\vec{r}(t) \parallel \vec{a}(t)$, for all t . Then the vector function $\vec{r}(t) \times \vec{v}(t)$ is constant, i.e., does not change in time.

(a) FALSE. (This is only true at constant speed. If the speed changes at the point of maximal curvature, \vec{a} will have a non-zero tangential component, and will not be orthogonal to \vec{v} .)

(b) TRUE. (If $\kappa=0$ the normal component of \vec{a} is 0, so \vec{a} is parallel to \vec{v} .)

(c) TRUE.
$$(\vec{r} \times \vec{v})' = \vec{r}' \times \vec{v} + \vec{r} \times \vec{v}'$$

$$= \underbrace{\vec{v} \times \vec{v}}_{=0} + \underbrace{\vec{r} \times \vec{a}}_{=0} = \vec{0}$$

b/c $\vec{v} \parallel \vec{v}$ b/c $\vec{r} \parallel \vec{a}$

so $\vec{r} \times \vec{v}$ is constant.

Problem 4. (4 points)The curve C is parametrized by the vector function

$$\vec{r}(t) = \langle t^2, e^t, \cos t \rangle$$

Find equations for the osculating plane and the normal plane to C at the point corresponding to the parameter value $t = 0$.

$$\begin{aligned}\vec{r} &= \langle t^2, e^t, \cos t \rangle \\ \vec{r}' &= \langle 2t, e^t, -\sin t \rangle \\ \vec{r}'' &= \langle 2, e^t, -\cos t \rangle\end{aligned}$$

~~$$\vec{r}(0) = \langle 0, 1, 1 \rangle$$~~

$$\begin{aligned}\vec{r}'(0) &= \langle 0, 1, 0 \rangle \\ \vec{r}''(0) &= \langle 2, 1, -1 \rangle\end{aligned}$$

Normal plane: normal vector is $\vec{r}'(0) = \langle 0, 1, 0 \rangle$
 point on plane is $\vec{r}(0) = \langle 0, 1, 1 \rangle$
 eqn is $\langle 0, 1, 0 \rangle \cdot (\langle x, y, z \rangle - \langle 0, 1, 1 \rangle) = 0$
 or $0(x-0) + 1(y-1) + 0(z-1) = 0$
 or $\boxed{y = 1}$

Osculating plane: normal vector is $\vec{r}'(0) \times \vec{r}''(0) = \langle 0, 1, 0 \rangle \times \langle 2, 1, -1 \rangle$
 point is $\vec{r}(0) = \langle 0, 1, 1 \rangle$
 $= \begin{vmatrix} i & j & k \\ 0 & 1 & 0 \\ 2 & 1 & -1 \end{vmatrix} = \langle -1, 0, -2 \rangle$

Eqn is $\langle -1, 0, -2 \rangle \cdot (\langle x, y, z \rangle - \langle 0, 1, 1 \rangle) = 0$
 or $-1(x-0) + 0(y-1) - 2(z-1) = 0$
 or $-x - 2z + 2 = 0$
 or $\boxed{x + 2z = 2}$

Overflow space I.

Remark: At the point $\langle 0, 1, 1 \rangle$ corresponding to $t=0$ we have:

$$\vec{T} = \langle 0, 1, 0 \rangle$$

$$\vec{N} = \frac{\sqrt{5}}{5} \langle 2, 0, -1 \rangle$$

$$\vec{B} = \frac{\sqrt{5}}{5} \langle -1, 0, -2 \rangle$$

The quickest way to calculate these is:

- ① normalize $\vec{r}'(0)$ to get \vec{T}
- ② normalize $\vec{r}'(0) \times \vec{r}''(0)$ to get \vec{B}
- ③ $\vec{N} = \vec{B} \times \vec{T}$.

This method avoids having to differentiate $\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$ to obtain \vec{N} .

But you do not need $\vec{T}, \vec{N}, \vec{B}$ for this problem.

Problem 5. (4 points)

The derivative $\frac{d}{dt}(\vec{r}(t) \cdot \vec{r}'(t))$ is equal to

- (a) $\vec{r}'(t) \cdot \vec{r}'(t)$,
 (b) $\vec{r}(t) \cdot \vec{r}''(t)$,
 (c) $\vec{r}'(t) \cdot \vec{r}''(t)$
 (d) $\|\vec{r}'(t)\|^2 + \vec{r}(t) \cdot \vec{r}''(t)$
 (e) none of the above.

$$(\vec{r} \cdot \vec{r}')' = \vec{r}' \cdot \vec{r}' + \vec{r} \cdot \vec{r}''$$

$$= \|\vec{r}'\|^2 + \vec{r} \cdot \vec{r}''$$

(d) is correct.

We have a smooth vector function $\vec{r}(t)$, with associated unit tangent vector $\vec{T}(t)$, principal normal vector $\vec{N}(t)$, and binormal vector $\vec{B}(t)$. The derivative $\frac{d}{dt}\vec{T}(t)$ is given by

- (a) $\frac{\vec{r}'(t) \times \vec{r}''(t)}{\|\vec{r}'(t)\|^2}$,
 (b) $\frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^2} \vec{N}(t)$
 (c) $\frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^2} \vec{B}(t)$
 (d) $\frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} \vec{N}(t)$
 (e) none of the above.

Start with the definition of curvature: $\frac{d\vec{T}}{ds} = \kappa \vec{N}$ ($\kappa = \text{curvature}$)

Multiply by $\frac{ds}{dt}$ to get $\frac{d\vec{T}}{dt}$: $\frac{d\vec{T}}{dt} = \frac{d\vec{T}}{ds} \frac{ds}{dt} = \kappa \frac{ds}{dt} \vec{N}$.

Recall the formulas $\kappa = \frac{\|\vec{r}' \times \vec{r}''\|}{\|\vec{r}'\|^3}$ and $\frac{ds}{dt} = \|\vec{r}'\|$:

$$\frac{d\vec{T}}{dt} = \frac{\|\vec{r}' \times \vec{r}''\|}{\|\vec{r}'\|^3} \|\vec{r}'\| \vec{N} = \frac{\|\vec{r}' \times \vec{r}''\|}{\|\vec{r}'\|^2} \vec{N}$$

(b) is correct.