

Equivalence Relations.

Recall: A relation on a set X , denoted \sim

($R \subset X \times X$, $x \sim y$ means $(x, y) \in R$.)

is an equivalence relation if

- reflexive $x \sim x \quad \forall x \in X$.

- symmetric, $x \sim y \Rightarrow y \sim x$

- transitive: $x \sim y, y \sim z \Rightarrow x \sim z$.

For $x \in X$ we have

$[x] = \{y \in X \mid x \sim y\}$.. equivalence class of $x \in X$.

If \sim is an equivalence relation then:

- Every $x \in X$ is contained in an equivalence class:
 $x \in [x]$ b/c \sim reflexive.

- $[x] \cap [y] = \emptyset$ } $[x], [y]$ equivalence classes
either $[x] \cap [y] = \emptyset$ } if $z \in [x]$ and $z \in [y]$
or $[x] = [y]$. } then $[x] = [y]$.

So X decomposes into equivalence classes.

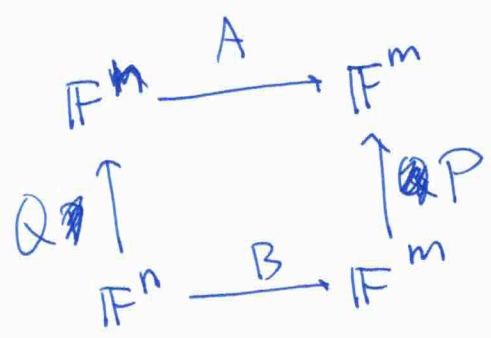
Example. $X = M(m \times n, \mathbb{F})$.
 relation: row equivalence.

$A \sim_R B$ if and only if there exists an invertible $P \in M(m \times m, \mathbb{F})$:
 $PA = B$.

- ① $A \sim_R B$ if and only if $RREF(A) = RREF(B)$.
 - ② Every equivalence class contains a unique matrix in RREF.
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Example: $X = M(m \times n, \mathbb{F})$.

$A \sim B$ equivalent \iff there exist $Q \in M(n \times n, \mathbb{F})$ and $P \in M(m \times m, \mathbb{F})$ both invertible, such that

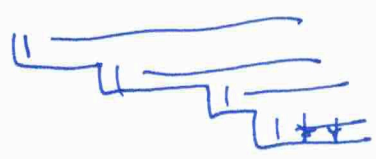


$$B = P^{-1} A Q$$

or $A = P B Q^{-1}$

$A \sim B$ if and only if A can be converted into B by a sequence of elementary row & column operations.

Every matrix $A \sim \left(\begin{array}{c|c} \overbrace{\begin{matrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{matrix}}^{\text{rk } A} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ \hline \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \end{array} \right).$



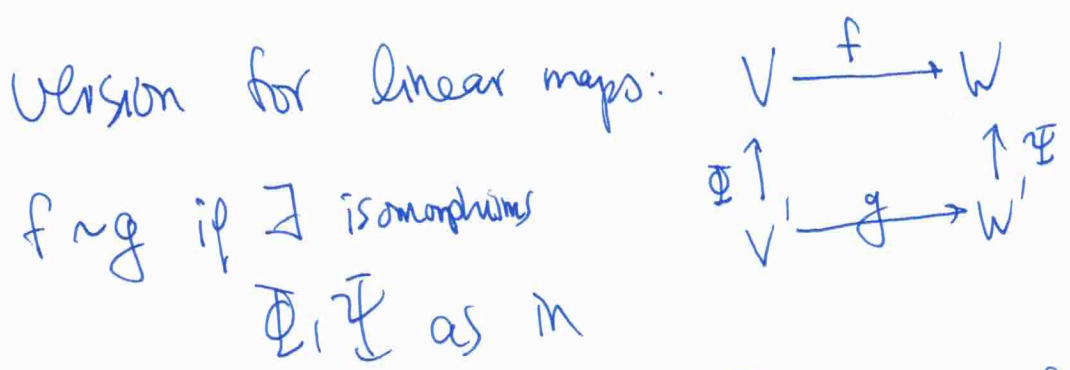
Theorem: (1) $A \sim B$ if and only if $\text{rk } A = \text{rk } B$.

(2) ~~Every equivalence class~~

there are

$$\left(\begin{array}{c|c} 0 & 0 \end{array} \right), \left(\begin{array}{c|c} 1 & 0 \\ \hline 0 & 0 \end{array} \right), \left(\begin{array}{c|c} \begin{matrix} 1 & 0 \\ 0 & 1 \end{matrix} & 0 \\ \hline 0 & 0 \end{array} \right), \dots, \left(\begin{array}{c|c} I_k & 0 \\ \hline 0 & 0 \end{array} \right)$$

complete list of equivalence classes
until $k = \min(m, n)$.



the diagram. Then $f \sim g \Leftrightarrow \text{rk } f = \text{rk } g$.

Moreover for every linear map $f: V \rightarrow W$

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$$\begin{array}{ccc} V & \xrightarrow{f} & W \\ \uparrow \Phi & & \uparrow \Psi \\ \mathbb{F}^n & \xrightarrow{A} & \mathbb{F}^m \end{array}$$

there exist bases of V and W such that

the matrix of f is

$$\left(\begin{array}{c|c} I_{r \times r} & 0 \\ \hline 0 & 0 \end{array} \right).$$

Proof. choose a basis of $\ker(f)$
 $w_1 \dots w_{n-r}$

$r = \text{rk.}$
 $\dim V = n.$

complete to a basis of V .

$v_1 \dots v_r$

$f(v_1) \dots f(v_r)$ are lin indep in W

complete to a basis $y_1 \dots y_m$.

| | $v_1 \dots v_r$ | $w_1 \dots w_{n-r}$ |
|----------|-----------------|---------------------|
| $f(v_1)$ | 1 0 0 | ○ |
| $f(v_r)$ | 0 0 1 | |
| y_1 | 0 0 0 | ○ |
| y_m | 0 0 0 | |

Specialize to endomorphisms

$$f: V \rightarrow V. \quad \begin{array}{ccc} V & \xrightarrow{f} & V \\ \cong \uparrow & & \uparrow \cong \\ \mathbb{F}^n & \xrightarrow{A} & \mathbb{F}^n \end{array}$$

Matrix version:

$B, A \in M(n \times n, \mathbb{F})$ are similar if

there exists
an invertible
matrix

$$\begin{array}{ccc} \mathbb{F}^n & \xrightarrow{A} & \mathbb{F}^n \\ \uparrow P & & \uparrow P \\ \mathbb{F}^n & \xrightarrow{B} & \mathbb{F}^n \end{array}$$

$P \in M(n \times n, \mathbb{F})$ such that $P B P^{-1} = A$

$A \text{ sim } B \Leftrightarrow A = P B P^{-1}$

quite hard to decide ~~if~~ when $A \sim B$
or to describe all similarity classes.

Remark: If $A \sim B$ then $\text{char poly}_A = \text{char poly}_B$.

(also $\det A = \det B$.) $A = P B P^{-1}$

$$\begin{aligned} \det(A - tI) &= \det(P B P^{-1} - tI) \\ &= \det(P B P^{-1} - P tI P^{-1}) = \det(P (B - tI) P^{-1}) \end{aligned}$$

$$= \cancel{\det(P)} \det(B-tI) \cancel{\det(P)^{-1}}$$

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$$= \det(B-tI).$$

Jordan canonical form

Answers the question how to describe all similarity classes over $\mathbb{F} = \mathbb{C}$.

Let $\lambda \in \mathbb{C}$. $J_{\lambda}^{(k)} = \begin{pmatrix} \lambda & 1 & & 0 \\ & \lambda & \ddots & \\ & & \ddots & 1 \\ 0 & & & \lambda \end{pmatrix}$ Jordan Block Matrix.

(1) 1×1 Jordan block

$$\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix} \quad 2 \times 2$$

3×3

$$\begin{pmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{pmatrix} \quad \dots$$

e_k .

char poly of Jordan block

$$\begin{vmatrix} \lambda-t & 1 & & \\ & \lambda-t & \ddots & \\ & & \ddots & 1 \\ 0 & & & \lambda-t \end{vmatrix} = \underline{\underline{(\lambda-t)^k}}$$

k = size of Jordan block

λ only eigenvalue.

algebraic multiplicity k .

Eigenspace: $\text{Nul} \begin{pmatrix} \lambda & 1 & & 0 \\ & \lambda & \ddots & \\ & & \ddots & 1 \\ 0 & & & \lambda \end{pmatrix} \begin{matrix} \downarrow \\ \text{RREF.} \\ \dim E_{\lambda} = 1 \end{matrix}$

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Theorem. Every ~~is~~ $A \in M(n \times n, \mathbb{C})$ is similar to exactly one matrix a matrix in Jordan canonical form, i.e.

Block diagonal, with Jordan blocks on diagonal.

$$\begin{pmatrix} \boxed{\begin{matrix} J_{k_1} \\ \lambda_1 \end{matrix}} & & & 0 \\ 0 & \boxed{\begin{matrix} J_{k_2} \\ \lambda_2 \end{matrix}} & & 0 \\ & & \ddots & \\ 0 & & & \boxed{\begin{matrix} J_{k_r} \\ \lambda_r \end{matrix}} \end{pmatrix}$$

The Jordan canonical form is unique up to reordering the Jordan blocks.

~~For~~ Let $f: V \rightarrow V$ be an endomorphism of a \mathbb{C} -VS V .
Then \exists basis B of V s.t.

$[f]_B$ is in JCF.