

## Eta Matrices

In computer implementations of the Revised Simplex Method it is sometimes useful to give the updates to the matrix  $B$  in a concise way. In particular, the *eta* matrix  $E$  is the matrix that updates  $B$ :

$$(\text{new } B) = (\text{old } B)E$$

We explained in class, that this update can be added to an  $LU$  factorization of old  $B$  and we write  $\text{new } B = LUE$  and are still able to quickly solve for  $\mathbf{y}$  in  $\mathbf{t}^T = \mathbf{c}_{\text{new } B}^T \text{new } B^{-1}$  and for  $\mathbf{a}$  in  $\text{new } BA_k = \mathbf{a}$ . We note that the new  $B$  after a pivot differs in only one column from the old  $B$  in only one column and so the matrix  $E$  has a very simple form. Imagine that the  $j$ th column of  $B$  as been replaced while variable  $x_k$  enters and  $x_l$  leaves. Thus  $E$  is the identity matrix where the  $j$ th column has been replaced by  $(\text{old } B)^{-1}A_k$  where  $A_k$  is the column of  $[AI]$  indexed by  $x_k$ . Computer implementations of the Revised Simplex Method manage to avoid computing  $B^{-1}$  but do use the eta matrices. Read Chapter 7 in the text for more details if you wish.

Let me give some examples from the sample of the revised simple method that is posted on the web. There is one strange anomaly below that may confuse you; namely one of the matrices is its own inverse! This happens from time to time.

$$B_3^{-1} = \begin{bmatrix} x_4 & x_5 & x_3 \\ 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{bmatrix}^{-1} = \begin{bmatrix} x_4 & x_5 & x_3 \\ 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{bmatrix} = B_3.$$

$$B_1 = \begin{matrix} & x_4 & x_5 & x_6 \\ x_4 & \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix}$$

$x_0$  enters,  $x_6$  leaves

$$B_2 = \begin{matrix} & x_4 & x_5 & x_0 \\ x_4 & \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix} = B_1 E_1 = \begin{matrix} & x_4 & x_5 & x_6 \\ x_4 & \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix} \begin{matrix} & x_4 & x_5 & x_0 \\ x_4 & \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix}$$

$x_3$  enters,  $x_0$  leaves

$$B_3 = \begin{matrix} & x_4 & x_5 & x_3 \\ x_4 & \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix} = B_2 E_2 = \begin{matrix} & x_4 & x_5 & x_0 \\ x_4 & \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix} \begin{matrix} & x_4 & x_5 & x_3 \\ x_4 & \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix}$$

$x_1$  enters,  $x_5$  leaves

$$B_4 = \begin{matrix} & x_4 & x_1 & x_3 \\ x_4 & \begin{pmatrix} 1 & -4 & 2 \\ 0 & -1 & 2 \\ 0 & 1 & -1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix} = B_3 E_3 = \begin{matrix} & x_4 & x_5 & x_3 \\ x_4 & \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix} \begin{matrix} & x_4 & x_1 & x_3 \\ x_4 & \begin{pmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \\ x_5 & \\ x_6 & \end{matrix}$$

$x_2$  enters,  $x_4$  leaves

$$B_5 = \begin{matrix} & x_2 & x_1 & x_3 \\ x_4 & \left( \begin{array}{ccc} 1 & -4 & 2 \\ -3 & -1 & 2 \\ 1 & 1 & -1 \end{array} \right) \\ x_5 & \\ x_6 & \end{matrix} = B_4 E_4 = \begin{matrix} & x_4 & x_1 & x_3 \\ x_4 & \left( \begin{array}{ccc} 1 & -4 & 2 \\ 0 & -1 & 2 \\ 0 & 1 & -1 \end{array} \right) \\ x_5 & \\ x_6 & \end{matrix} \begin{matrix} & x_2 & x_1 & x_3 \\ x_4 & \left( \begin{array}{ccc} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -2 & 0 & 1 \end{array} \right) \\ x_1 & \\ x_3 & \end{matrix}$$