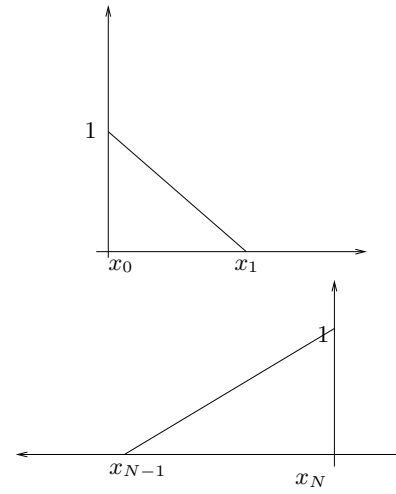


$$N_0^1(x) = \begin{cases} \left(\frac{x_1-x}{x_1-x_0}\right) & x \in [x_0, x_1] \\ 0 & x \notin [x_0, x_1] \end{cases}$$



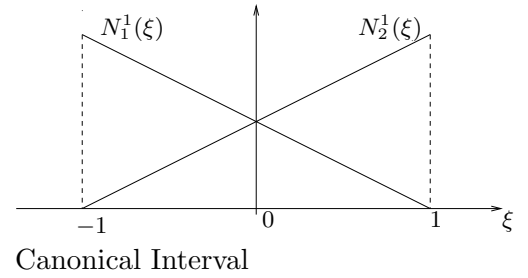
$$N_n^1(x) = \begin{cases} 0 & x \notin [x_{N-1}, x_N] \\ \left(\frac{x-x_{N-1}}{x_N-x_{N-1}}\right) & x \in [x_{N-1}, x_N] \end{cases}$$

Then  $p_{i,N}(x) = \sum_{i=0}^N f_i N_i^1(x) \approx f(x)$ . We notice that  $N_i^1(x_j) = \delta_{ij}$  so that the basis functions are zero outside the interval  $(x_{i-1}, x_{i+1})$  – we say that such *basis functions have local support*.

**Representation on a canonical interval:**

Sometimes it is more convenient to perform calculations by representing the piecewise linear basis functions on a canonical interval:  $[-1, 1]$ . On the canonical interval the basis functions assume the form.:

$$\begin{aligned} N_1^1(\xi) &= \frac{1}{2}(1 - \xi) & N_2^1(\xi) &= \frac{1}{2}(1 + \xi) \\ \text{or } N_a^1(\xi) &= \frac{1}{2}(1 + \xi_a \xi) & \xi_1 &= -1 & \xi_2 &= +1 \end{aligned}$$



**Note:**  $N_a^1(\xi_b) = \delta_{ab}$  and  $x(\xi) = \sum_{a=1}^2 x_a N_a^1(\xi)$

**Error involved:** Recall  $e_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} \prod_{j=0}^n (x - x_j)$  for polynomial interpolants.

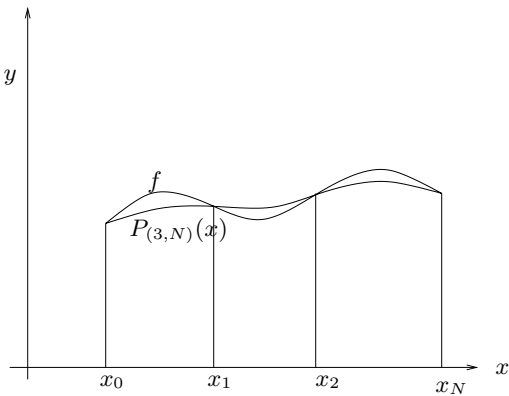
$$\begin{aligned} & \max_{x \in [x_i, x_{i+1}]} |e_1(x)| \\ &= \max_{x \in [x_i, x_{i+1}]} \left| \frac{f''(s)}{2} (x - x_i)(x - x_{i+1}) \right| \leq \frac{1}{2} \|f''\|_\infty \max_{x \in [x_i, x_{i+1}]} |(x - x_i)(x - x_{i+1})| \leq \frac{h^2}{8} \|f''\|_\infty. \end{aligned}$$

Using:

$$w(x) = (x - x_i)(x - x_{i+1}) = x^2 - (x_i + x_{i+1})x + x_i x_{i+1}$$

$$w'(x) = 2x - (x_i + x_{i+1}) = 0 \Rightarrow x = \frac{(x_i + x_{i+1})}{2} \quad \& \quad w\left(\frac{x_i + x_{i+1}}{2}\right) = \left(\frac{x_{i+1} - x_i}{2}\right) \left(\frac{x_i - x_{i+1}}{2}\right)$$

## 2. Piecewise quadratic interpolation:



**Degree of freedom analysis:**

$$\begin{array}{ll} N \text{ Subintervals} & 3 \text{ coefficients for quadratic} \\ 3N \text{ DOF} & \end{array}$$

Constraints

$$(1) \left. \begin{array}{l} \text{Continuity at interior points} \\ \text{Continuity of derivative at interior points} \end{array} \right\} \Rightarrow 2(N-1) \text{ constraints}$$

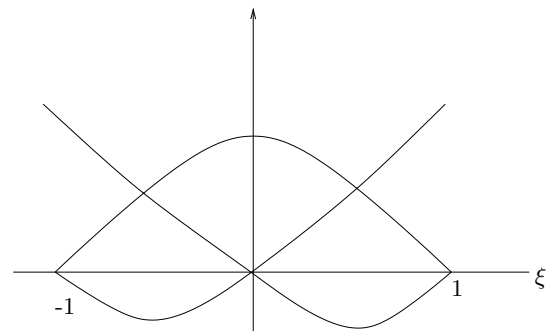
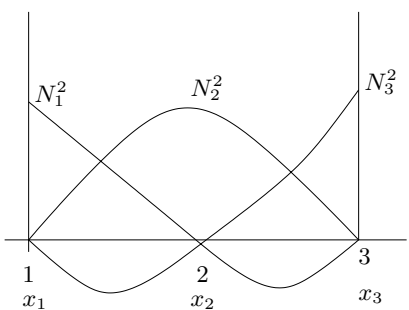
$$\begin{aligned} \text{Remaining DOF} &= 3N - 2(N-1) = N+2 = (N+1) + 1 \\ &= \text{function values at } N+1 \text{ nodes} \\ &\quad \text{and 1 extra condition (?)} \end{aligned}$$

$$(2) \text{ Continuity at interior nodes} \Rightarrow N-1$$

$$\begin{aligned} \text{Remaining DOF} &= 3N - (N-1) = 2N+1 = (N+1) + N \\ &= \text{function values at } (N+1) \text{ nodes} \\ &\quad +1 \text{ function value within each interval} \end{aligned}$$

These are called *quadratic Lagrange interpolants*.

### Basis functions representation for quadratic Lagrange



On Canonical Interval

$$\begin{aligned}
N_1^2(x) &= \frac{(x-x_2)(x-x_3)}{(x_1-x_2)(x_1-x_3)} & N_1(\xi) &= \frac{1}{2}\xi(\xi-1) \\
N_2^2(x) &= \frac{(x-x_1)(x-x_3)}{(x_2-x_1)(x_2-x_3)} & N_2(\xi) &= 1-\xi^2 \\
N_3^2(x) &= \frac{(x-x_1)(x-x_2)}{(x_3-x_1)(x_3-x_2)} & N_3(\xi) &= \frac{1}{2}\xi(\xi+1)
\end{aligned}$$

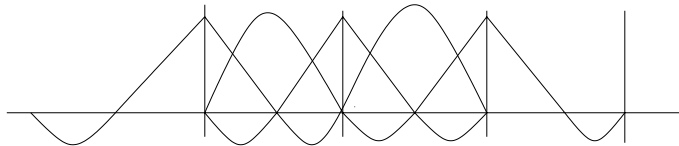
**Note:**

(1)  $N_i^2(x_j) = \delta_{ij}$       • On a canonical interval  $[-1, 1]$ .

(2)  $\sum_{i=1}^N N_i(x) = 1$        $N_1 + N_2 + N_3 = \frac{1}{2}\xi^2 - \frac{1}{2}\xi + 1 - \xi^2 + \frac{1}{2}\xi^2 + \frac{1}{2}\xi = 1$

Must be true as we must be able to represent a constant function exactly. We can now obtain a global representation of the interpolants by numbering all the basis functions:

$$f(x) \sim \sum_{i=0}^n f_i N_i^2(x)$$



### 3. Piecewise cubic interpolants: $p_{3,N}(x)$

**DOF Analysis:**      *FIGURE*

$N$  intervals       $N + 1$  nodes       $N - 1$  internal nodes

4 unknown coefficients for interval

**Schemes of constraint:**

(1)  $p_{3,N}(x)$  and  $p'_{3,N}(x)$  are continuous at interior nodes.

$$\begin{aligned}
\Rightarrow \text{DOF} : 4N - 2(N - 1) &= 2(N + 1) \\
&\Rightarrow \text{specify function value and} \\
&\quad \text{its derivative at all } N + 1 \text{ nodes}
\end{aligned}$$

$\Rightarrow$  **Piecewise Cubic Hermite polynomials**

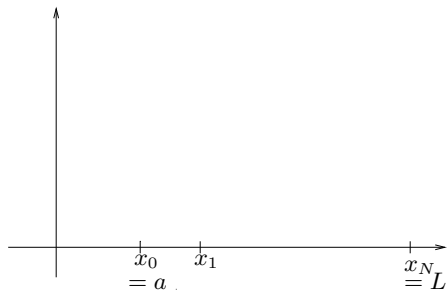
• Have to specify  $f$  &  $f'$  at all  $N + 1$  nodes!

(2)  $p_{3,N}(x)$ ,  $p'_{3,N}(x)$ ,  $p''_{3,N}(x)$  are all continuous at interior.

$$\begin{aligned}
\Rightarrow \text{DOF} : 4N - 3(N - 1) = N + 3 &= \underbrace{N + 1}_{\text{specify } f \text{ at all } N + 1 \text{ nodes}} + 2 \\
&\Rightarrow \text{and impose 2 EXTRA CONDITIONS}
\end{aligned}$$

This is a *cubic spline*. The extra conditions are up to the user to prescribe depending on the application, e.g.  $p''_3(x_0) = 0 = p''_3(x_N)$  which is called the natural spline.

## Piecewise cubic interpolation:



## Piecewise cubic Hermite polynomials:

DOF:  $4N - 2(N - 1) = 2(N + 1) \Rightarrow$  prescribe  $f(x_i)$  and  $f'(x_i)$  at  $i = 0, \dots, N$ .

Presentation of  $f$  in terms of Hermite basis functions  $h_i^{(0)}(x)$  and  $h_i^{(1)}(x)$ :

$$f(x) \approx h(x) = \sum_{i=0}^N f(x_i)h_i^{(0)}(x) + \sum_{i=0}^N f'(x_i)h_i^{(1)}(x)$$

where

$$\left. \begin{array}{l} h_i^{(0)}(x_j) = \delta_{ij} \quad \text{and} \quad \frac{d}{dx}h_i^{(1)}(x_j) = \delta_{ij} \\ \frac{d}{dx}h_i^{(0)}(x_j) = 0 \quad \quad \quad h_i^{(1)}(x_j) = 0 \end{array} \right\} \quad (1)$$

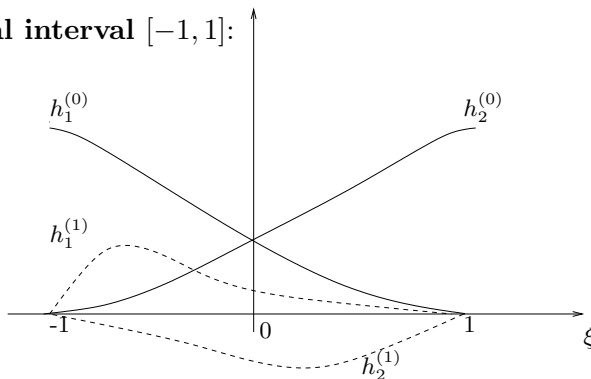
## Constructing basis functions on the canonical interval $[-1, 1]$ :

We use the linear Lagrange basis functions

$$N_a^1(\xi) = \frac{1}{2}(1 + \xi_a \xi) : N_a^1(\xi_b) = \delta_{ab}, \quad \xi_{a,b} = \pm 1$$

Let

$$\begin{aligned} h_1^{(0)}(\xi) &= (\alpha_1 \xi + \beta_1)[N_1^1(\xi)]^2; & h_2^{(0)}(\xi) &= (\alpha_2 \xi + \beta)[N_2^1(\xi)]^2 \\ h_1^{(1)}(\xi) &= (\gamma_1 \xi + \delta_1)[N_1^1(\xi)]^2; & h_2^{(1)}(\xi) &= (\gamma_2 \xi + \delta_2)[N_2^1(\xi)]^2 \end{aligned}$$



To find  $\alpha_i$ ,  $\beta_i$ ,  $\gamma_i$  and  $\delta_i$  we impose the conditions (1):

$$1 = h_1^{(0)}(-1) = \beta_1 - \alpha_1 \quad 0 = h_1^{(0)' }(-1) = \alpha_1 + (\beta_1 - \alpha_1) \frac{2}{2}(1 - (-1)) \frac{(-1)}{2} = 2\alpha_1 - \beta_1$$

$$\therefore \alpha_1 = 1 \text{ and } \beta_1 = 2$$

$$\Rightarrow \boxed{h_1^{(0)}(\xi) = \frac{1}{4}(2 + \xi)(1 - \xi)^2}$$

Similarly  $\boxed{h_2^{(0)}(\xi) = \frac{1}{4}(2 - \xi)(1 + \xi)^2}$

For the derivative basis functions

$$\left. \begin{aligned} 0 &= h_1^{(1)}(-1) = (\delta_1 - \gamma_1) \\ 1 &= h_1^{(1)}(-1) = 2\gamma_1 - \delta_1 \end{aligned} \right\} \Rightarrow \delta_1 = \gamma_1 = 1 \Rightarrow \boxed{h_1^{(1)}(\xi) = \frac{1}{4}(1 + \xi)(1 - \xi)^2}$$

Similarly  $\boxed{h_2^{(1)}(\xi) = \frac{1}{4}(\xi - 1)(1 + \xi)^2}$

**Expression of basis functions on an arbitrary interval  $[x_i, x_{i+1}]$ .**

$$\begin{aligned} \text{Use the linear transformation } x(\xi) &= x_i N_1^{(1)}(\xi) + x_{i+1} N_2^{(1)}(\xi) \\ &= x_i \frac{1}{2}(1 - \xi) + x_{i+1} \frac{1}{2}(1 + \xi) \\ &= \left( \frac{x_i + x_{i+1}}{2} \right) + \frac{(x_{i+1} - x_i)}{2} \xi \end{aligned}$$

$$\text{The inverse transformation is: } \xi(x) = \frac{2x - (x_i + x_{i+1})}{(x_{i+1} - x_i)} = \frac{2x - (x_i + x_{i+1})}{\Delta x_i}$$

$$\begin{aligned} 1 + \xi &= \frac{x_{i+1} - x_i + 2x - x_i - x_{i+1}}{x_{i+1} - x_i} = \frac{2(x - x_i)}{(x_{i+1} - x_i)} \Rightarrow 2 + \xi = \frac{\Delta x_i + 2(x - x_i)}{\Delta x_i} \\ 1 - \xi &= \frac{2(x_{i+1} - x)}{x_{i+1} - x_i} \Rightarrow (2 - \xi) = \frac{\Delta x_i + 2(x_{i+1} - x)}{\Delta x_i} \end{aligned}$$

$$\boxed{\begin{aligned} \therefore h_i^{(0)}(x) &= \frac{[\Delta x_i + 2(x - x_i)](x_{i+1} - x)^2}{(\Delta x_i)^3} \\ h_{i+1}^{(0)}(x) &= \frac{[\Delta x_i + 2(x_{i+1} - x)](x - x_i)^2}{(\Delta x_i)^3} \\ h_i^{(1)}(x) &= \frac{(x - x_i)(x_{i+1} - x)^2}{(\Delta x_i)^2} \\ h_{i+1}^{(1)}(x) &= -\frac{(x_{i+1} - x)(x - x_i)^2}{(\Delta x_i)^2} \end{aligned}}$$

Note:  $\Delta x_i = x_{i+1} - x_i$

$$\begin{aligned} \frac{dh_i}{d\xi}(\xi) &= \frac{dh_i}{dx}(\xi(x)) \cdot \frac{dx}{d\xi} \\ &= \frac{dh_i}{dx}(\xi(x)) \cdot \frac{\Delta x_i}{2} \end{aligned}$$

**Error involved:**

For function values the error is given by:

$$|f(x) - h(x)| \leq \|f^{(4)}\|_{\infty} \frac{\Delta x^4}{384}$$

while for derivatives the error is :

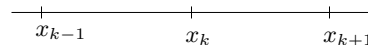
$$|f'(x) - h'(x)| \leq \|f^{(4)}\|_{\infty} \frac{\sqrt{3}\Delta x^3}{216}$$

## Piecewise cubic spline interpolation:

**NDOF:**  $4N - 3(N - 1) = N + 1 + 2 \Rightarrow$  specify  $f(x_i)$  at  $x_0, \dots, x_N$ .  
 + 2 extra conditions

Since we have similar piecewise cubic polynomials to the PWCH polynomials on each subinterval but with additional continuity required at the  $N - 1$  interior nodes, our starting point is the Hermite cubic basis expansion. We then impose additional conditions to make up for the derivatives  $f'(x_i)$  which are not known (or required) in the case of splines.

On  $[x_k, x_{k+1}]$



$$s(x) = f_k \frac{[\Delta x_k + 2(x - x_k)](x_{k+1} - x)^2}{(\Delta x_k)^3} + f_{k+1} \frac{[\Delta x_k + 2(x_{k+1} - x)](x - x_k)^2}{(\Delta x_k)^3} \\ + s'_k \frac{(x - x_k)(x_{k+1} - x)^2}{(\Delta x_k)^2} + s'_{k+1} \frac{(x - x_{k+1})(x - x_k)^2}{(\Delta x_k)^2}$$

where the  $f'_k$  and  $f'_{k+1}$  from the Hermite expansion have been replaced by the unknown quantities  $s'_k$  and  $s'_{k+1}$  which are to be determined by a system of equations which ensure that  $s''(x)$  is continuous at internal nodes.

The first and second derivatives of  $s(x)$  must be continuous at the points  $x_j$ . Continuity of the first derivative is already obtained by our choice of basis functions. So we apply continuity of  $s''(x)$  to get equations for the coefficients  $s'_k$ . That is, we calculate  $s''(x)$  on the two intervals  $[x_{k-1}, x_k]$  and  $[x_k, x_{k+1}]$  and require continuity at  $x_k$ . After some algebra.

$$\Delta x_k s'_{k-1} + 2(\Delta x_k + \Delta x_{k-1})s'_k + \Delta x_{k-1} s'_{k+1} = 3(f[x_k, x_{k+1}]\Delta x_{k-1} + f[x_{k-1}, x_k]\Delta x_k)$$

We have  $N - 1$  equations and  $(N + 1)$  unknowns  $s'_0, s'_1, \dots, s'_N$  so we need 2 more conditions. Say we specify

(I.)  $f'_0 = s'_0$  and  $s'_N = f'_N$  then on a uniform mesh  $\Delta x_k = \Delta x$ :

$$\begin{bmatrix} 4 & 1 & 0 & & \dots & & 0 \\ 1 & 4 & 1 & 0 & & \dots & 0 \\ 0 & 1 & 4 & 1 & & & \\ & 0 & & \ddots & & & \vdots \\ \vdots & & & \ddots & & & \vdots \\ & & & & 0 & & 1 \\ 0 & & \dots & & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} s'_1 \\ s'_2 \\ \vdots \\ \vdots \\ s'_{N-1} \end{bmatrix} = 3 \begin{bmatrix} f[x_1, x_2] + f[x_0, x_1] \\ f[x_2, x_3] + f[x_1, x_2] \\ \vdots \\ \vdots \\ f[x_{N-1}, x_N] + f[x_{N-2}, x_{N-1}] \end{bmatrix} - \begin{bmatrix} s'_0 \\ \vdots \\ \vdots \\ s'_N \end{bmatrix}$$

A tridiagonal system of equations – easy to solve!