

# Outline

## Week 10: Eigenvalues and eigenvectors

### Course Notes: 6.1

Goals: Understand how to find eigenvector/eigenvalue pairs, and use them to simplify calculations involving matrix powers.

## This Will Look Strange: A preview of Why We Bother

Eigenvectors: we'll use a **very specific** phenomenon to make hard calculations easier. Here is a preview of what we can do.

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$$\begin{bmatrix} 1/2 & 3/4 \\ 1/2 & 1/4 \end{bmatrix} \begin{bmatrix} x \\ -x \end{bmatrix} = -\frac{1}{4} \begin{bmatrix} x \\ -x \end{bmatrix} \qquad \begin{bmatrix} 1/2 & 3/4 \\ 1/2 & 1/4 \end{bmatrix} \begin{bmatrix} x \\ 2x/3 \end{bmatrix} = 1 \begin{bmatrix} x \\ 2x/3 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} =$$



$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 2 \begin{bmatrix} x \\ y \end{bmatrix}$$

# When Matrix Multiplication looks like Scalar Multiplication

$$\begin{bmatrix} 1/2 & 3/4 \\ 1/2 & 1/4 \end{bmatrix} \begin{bmatrix} x \\ -x \end{bmatrix} = -\frac{1}{4} \begin{bmatrix} x \\ -x \end{bmatrix} \qquad \begin{bmatrix} 1/2 & 3/4 \\ 1/2 & 1/4 \end{bmatrix} \begin{bmatrix} x \\ 2x/3 \end{bmatrix} = 1 \begin{bmatrix} x \\ 2x/3 \end{bmatrix}$$

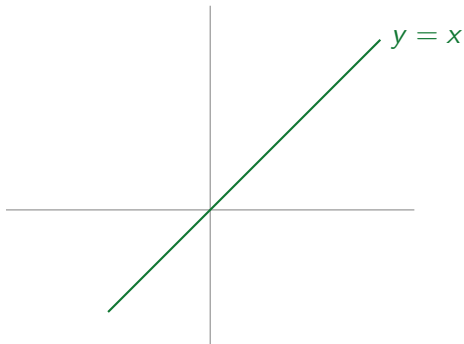
$$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 2 \begin{bmatrix} x \\ y \end{bmatrix}$$

Recall:

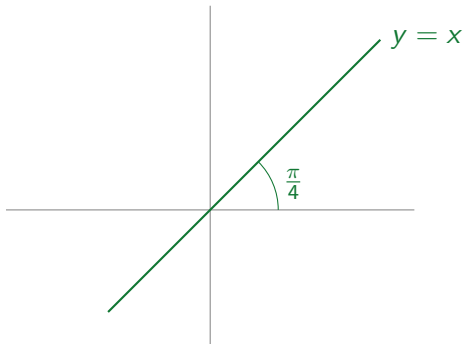
Two vectors that are scalar multiples of one another are parallel.

If we interpret matrix multiplication as a **linear transformation**, we're looking for **a vector whose image is parallel to itself**.

## Reflections, Revisited

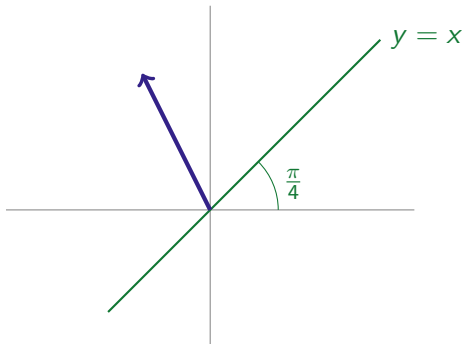


# Reflections, Revisited



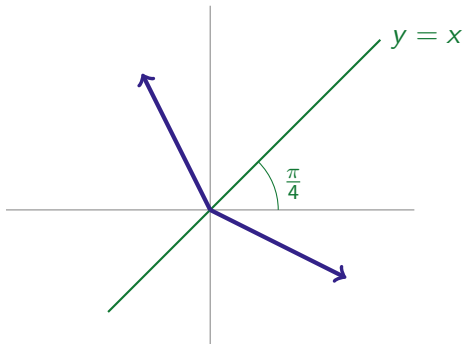
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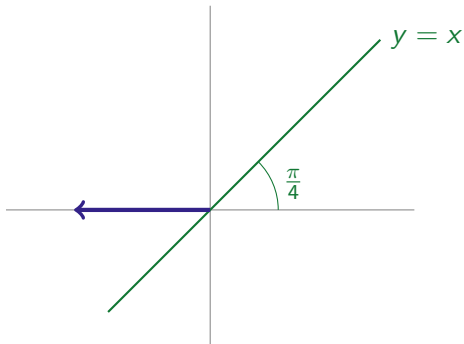
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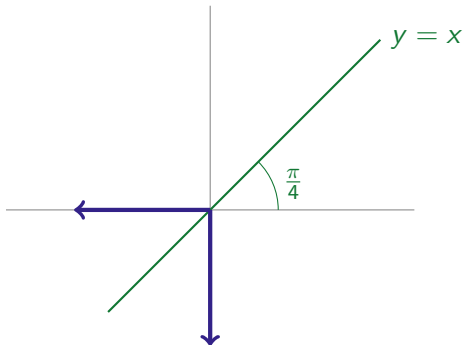
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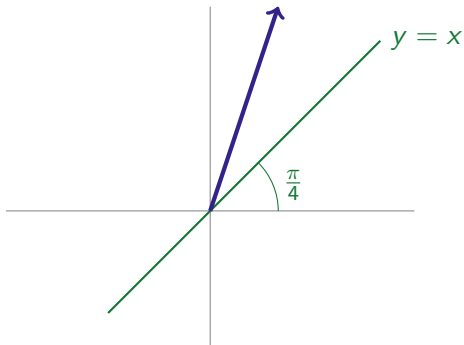
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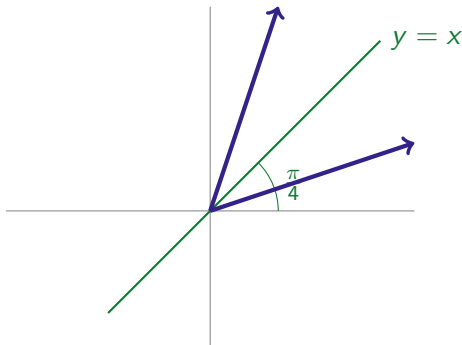


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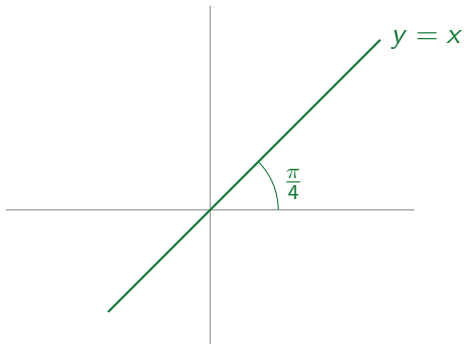
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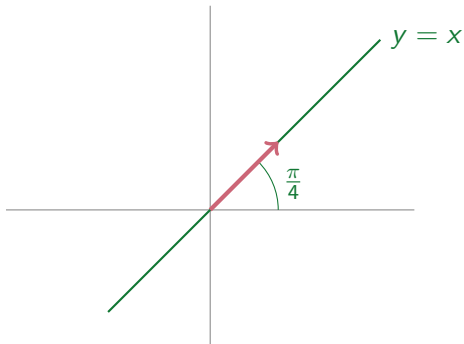
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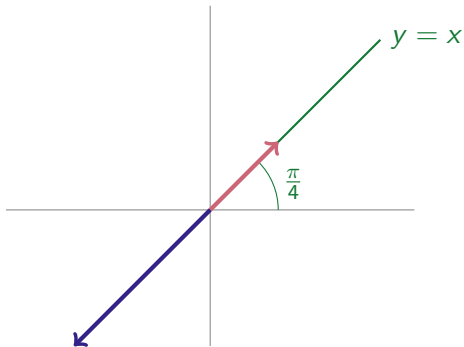
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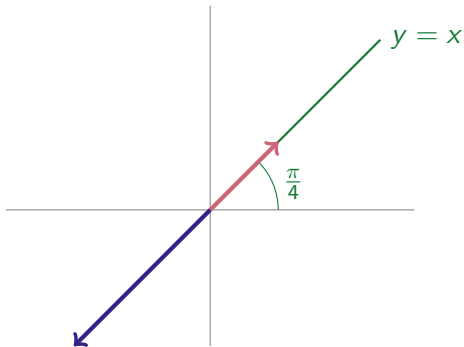
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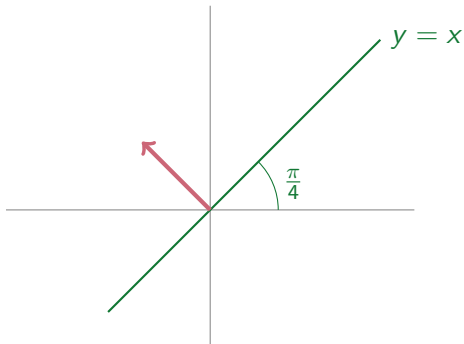
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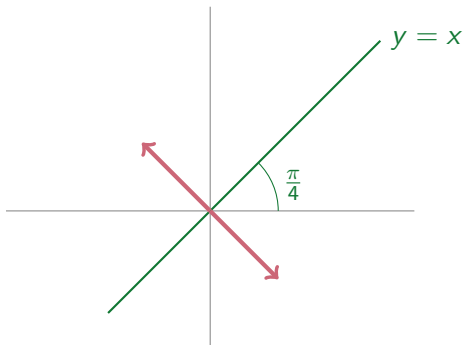
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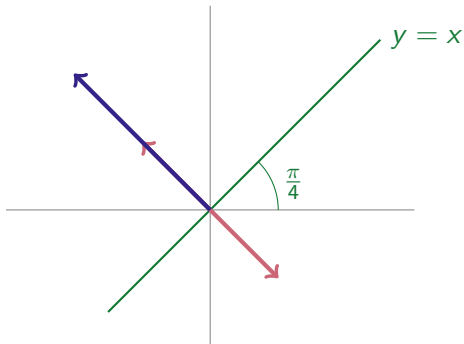


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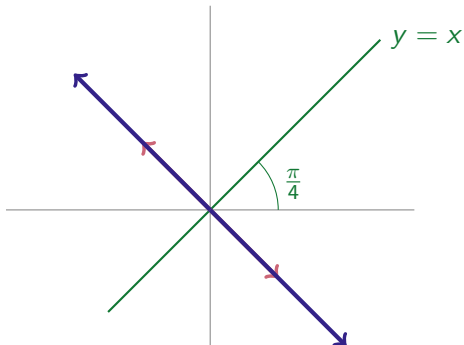
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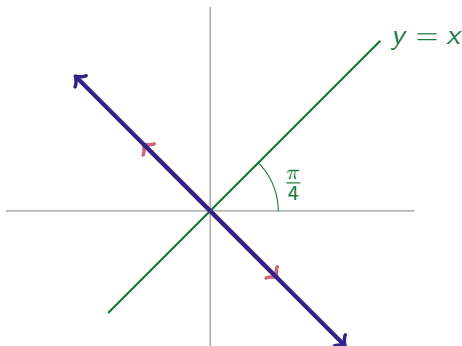
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## Eigenvectors and Eigenvalues

Given a matrix  $A$ , a scalar  $\lambda$ , and a NONZERO vector  $\mathbf{x}$  with

$$A\mathbf{x} = \lambda\mathbf{x}$$

we say  $\mathbf{x}$  is an *eigenvector* of  $A$  with *eigenvalue*  $\lambda$ .

Notice we omit zero vectors! These are not particularly useful, and they behave differently from nonzero vectors with this property.

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$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ x \end{bmatrix} = 1 \cdot \begin{bmatrix} x \\ x \end{bmatrix}$$

The matrix  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  has **eigenvector**  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  with **eigenvalue** 1.

By convention, we choose one representative eigenvector, with the understanding that all its nonzero scalar multiples are eigenvectors as well.

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The matrix  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  has **eigenvector**  $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$  with **eigenvalue**  $-1$ .

## Rotation Matrix Eigenvalues

$$Rot_{\theta} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$



# Rotation Matrix Eigenvalues

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Search for eigenvectors:

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \lambda \begin{bmatrix} x \\ y \end{bmatrix}$$

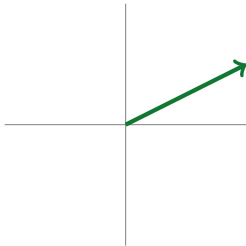
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e.g.  $\theta = 135^{\circ}$



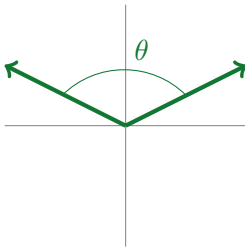
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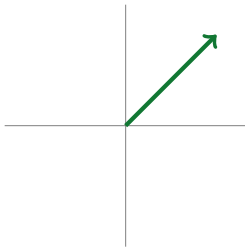
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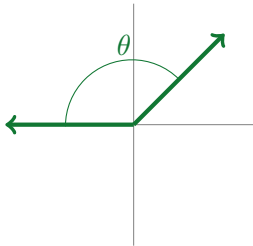
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$$Rot_{\theta} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

Search for eigenvectors:

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \lambda \begin{bmatrix} x \\ y \end{bmatrix}$$

e.g.  $\theta = 135^{\circ}$



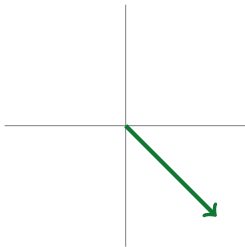
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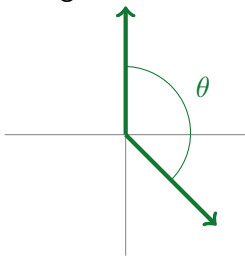
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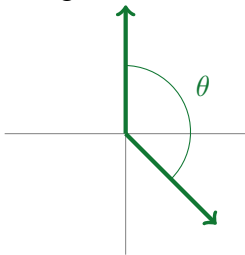
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For most values of  $\theta$ , the matrix  $Rot_{\theta}$  has no (real) eigenvalues.



## Finding Eigenvectors, Given Eigenvalues

Computation! We'll learn this in two stages.

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Given: 7 is an eigenvalue of the matrix  $\begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 1 \\ 4 & 1 & 2 \end{bmatrix}$ .

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In equation form:

$$\begin{array}{rclclcl} x & + & 2y & + & 4x & = & 7x \\ 2x & + & 4y & + & z & = & 7y \\ 4x & + & y & + & 2z & = & 7z \end{array}$$

## Finding Eigenvectors, Given Eigenvalues

In equation form:

$$x + 2y + 4x = 7x$$

$$2x + 4y + z = 7y$$

$$4x + y + 2z = 7z$$

# Finding Eigenvectors, Given Eigenvalues

In equation form:

$$\begin{aligned} x + 2y + 4x &= 7x \\ 2x + 4y + z &= 7y \\ 4x + y + 2z &= 7z \end{aligned}$$

In better equation form:

$$\begin{aligned} -6x + 2y + 4x &= 0 \\ 2x - 3y + z &= 0 \\ 4x + y - 5z &= 0 \end{aligned}$$

$$\left[ \begin{array}{ccc|c} -6 & 2 & 4 & 0 \\ 2 & -3 & 1 & 0 \\ 4 & 1 & -5 & 0 \end{array} \right] \rightarrow \rightarrow \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

# Finding Eigenvectors, Given Eigenvalues

Gaussian elimination on augmented matrix:

$$\left[ \begin{array}{ccc|c} -6 & 2 & 4 & 0 \\ 2 & -3 & 1 & 0 \\ 4 & 1 & -5 & 0 \end{array} \right] \rightarrow \rightarrow \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$



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Solutions:

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So these are the solutions to:

$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 1 \\ 4 & 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 7 \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

## Finding Eigenvectors, Given Eigenvalues

The solutions to:

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## Finding Eigenvectors, Given Eigenvalues

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are precisely the vectors:

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So, we can choose  $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$  as an example of an eigenvector of

$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 1 \\ 4 & 1 & 2 \end{bmatrix} \text{ with eigenvalue } 7.$$

## Finding Eigenvectors from Eigenvalues

The matrix  $\begin{bmatrix} 3 & 6 \\ 6 & -2 \end{bmatrix}$  has eigenvalues  $-6$  and  $7$ .

Find an eigenvector associated to each eigenvalue.

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## From the 2015 final exam

The matrix below represents rotation in 3D about a line through the origin.

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In 2015 (as today!) we do not talk about computing 3D rotations in class. This is a computation you can do just by visualizing the matrix as a transformation and understanding the definition of an eigenvector.

## Generalized Eigenvector Finding

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Eigenvectors  $\mathbf{x}$  associated with eigenvalue  $\lambda$  are precisely the nonzero solutions to this homogeneous system.

So, we set up a homogeneous system of equations, where the coefficient matrix is formed by subtracting  $\lambda$  from every entry in the main diagonal of  $A$ .

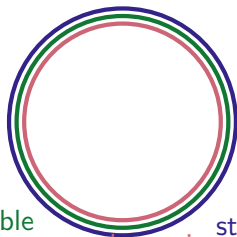
## How do we Find Eigenvalues, Though?

First, a reminder....

# Solutions to Systems of Equations

Let  $A$  be an  $n$ -by- $n$  matrix. The following statements are equivalent:

- 1)  $A\mathbf{x} = \mathbf{b}$  has exactly one solution for any  $\mathbf{b}$ .
- 2)  $A\mathbf{x} = \mathbf{0}$  has no nonzero solutions.
- 3) The rank of  $A$  is  $n$ .
- 4) The reduced form of  $A$  has no zeroes along the main diagonal.
- 5)  $A$  is invertible
- 6)  $\det(A) \neq 0$



invertible

nonzero determinant

statements 1-4

## How do we Find Eigenvalues, Though?

$A$  matrix;  $\lambda$  eigenvalue,  $\mathbf{x}$  eigenvector (so  $\mathbf{x} \neq \mathbf{0}$ )

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Note: we're not taking the determinant of  $A$ !

# Find Eigenvalues and Associated Eigenvectors

$$\lambda \text{ eigenvalue} \Leftrightarrow \det(A - \lambda I) = 0$$

$$A = \begin{bmatrix} 1 & 0 \\ 3 & -1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

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$$\left\{ \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis of } \mathbb{R}^2$$

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NOT a basis of  $\mathbb{R}^2$ !

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$$A = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 2 & 6 \\ 0 & 0 & 3 \end{bmatrix}$$

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# Using Eigenvalues to Compute Matrix Powers

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$$\mathbf{x} = \begin{bmatrix} 47 \\ 16 \\ 2 \end{bmatrix}$$

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$$A^{10}\mathbf{x} = A^{10}(2\mathbf{k}_1 + 4\mathbf{k}_2 + \mathbf{k}_3) = 2A^{10}\mathbf{k}_1 + 4A^{10}\mathbf{k}_2 + A^{10}\mathbf{k}_3 = 2\mathbf{k}_1 + 4(2^{10})\mathbf{k}_2 + 3^{10}\mathbf{k}_3$$

# Using Eigenvalues to Compute Matrix Powers

$$A = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 2 & 6 \\ 0 & 0 & 3 \end{bmatrix}$$

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$$4(2^{10})\mathbf{k}_2 + 3^{10}\mathbf{k}_3 = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 2^{14} \\ 2^{12} \\ 0 \end{bmatrix} + \begin{bmatrix} 29 \cdot 3^{10} \\ 12 \cdot 3^{10} \\ 2 \cdot 3^{10} \end{bmatrix}$$

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Find all solutions  $\lambda$  to the equation  $\det(A - \lambda I) = 0$ .

These are your eigenvalues.

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For eigenvectors  $k_1, k_2, \dots, k_n$ , solve the linear system of equations  $\mathbf{x} = a_1 k_1 + a_2 k_2 + \dots + a_n k_n$  for constants

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$$A\mathbf{x} = A(a_1 k_1 + a_2 k_2 + \dots + a_n k_n) = (a_1 \lambda_1^n k_1 + a_2 \lambda_2^n k_2 + \dots + a_n \lambda_n^n k_n)$$

Compute

$$\begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix}^{101} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

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1. Eigenvalues:
2. Eigenvectors:
3. Write  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  as a linear combination of eigenvectors:
4. Evaluate.

Your final answer should consist of **real, integer** entries.

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3. Write  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  as a linear combination of eigenvectors:  
 $\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1+8i}{10} \begin{bmatrix} -3-i \\ 5 \end{bmatrix} + \frac{1-8i}{10} \begin{bmatrix} -3+i \\ 5 \end{bmatrix}$
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$$\begin{aligned} \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix}^{101} \begin{bmatrix} 1 \\ 1 \end{bmatrix} &= \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix}^{101} \left( \frac{1+8i}{10} \begin{bmatrix} -3-i \\ 5 \end{bmatrix} + \frac{1-8i}{10} \begin{bmatrix} -3+i \\ 5 \end{bmatrix} \right) \\ &= (i^{101}) \frac{1+8i}{10} \begin{bmatrix} -3-i \\ 5 \end{bmatrix} + ((-i)^{101}) \frac{1-8i}{10} \begin{bmatrix} -3+i \\ 5 \end{bmatrix} \\ &= i \frac{1+8i}{10} \begin{bmatrix} -3-i \\ 5 \end{bmatrix} - i \frac{1-8i}{10} \begin{bmatrix} -3+i \\ 5 \end{bmatrix} = \begin{bmatrix} 5 \\ -8 \end{bmatrix} \end{aligned}$$

Your final answer should consist of **real, integer** entries.

There exists a 2-by-2 matrix  $A$  with the following eigenvalue-eigenvector pairs:

$$A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad A \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

What is  $A$ ? What is  $A^n$ ?

First, we note that for  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ ,  $A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ c \end{bmatrix}$ , and  $A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} b \\ d \end{bmatrix}$ . So, we can pick off the columns of  $A$  by finding its product with the standard basis vectors.

$$A \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = A \left( \frac{2}{3} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) = 0 + (3)(1/3) \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$A \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = A \left( \frac{-1}{3} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) = 0 + 3(1/3) \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\text{So, } A = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix} \quad \text{Similarly, } A^n = 3^{n-1} \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$$