## Mathematics 307—October 11, 1995

## Projections

The **projection** of a vector **u** onto a line  $\ell$  is the vector you get by dropping a perpendicular from the head of **u** onto  $\ell$ . If we are given a vector **v** pointing in the direction of that line, the projection will be a scalar multiple of **v**. The **signed length** of the projection is



It will be positive if the projection is on the same side as  $\mathbf{v}$ , zero if the projection vanishes, otherwise negative. In other words:

The projection of **u** onto the line through **v** is the same as the vector

$$\frac{\mathbf{u} \bullet \mathbf{v}}{\|\mathbf{v}\|} \frac{\mathbf{v}}{\|\mathbf{v}\|} = \frac{\mathbf{u} \bullet \mathbf{v}}{\mathbf{v} \bullet \mathbf{v}} \mathbf{v} \ .$$

Now let P be the plane perpendicular to the vector  $\mathbf{v}$ . Any vector  $\mathbf{u}$  can be expressed as the sum of its two components, one parallel to  $\mathbf{v}$  and one perpendicular to it. The perpendicular component is the perpendicular projection of  $\mathbf{u}$  onto the plane P. The formula for it is therefore

$$u - \frac{u \cdot v}{v \cdot v} v$$

Let T be the linear transformation taking a vector to its perpendicular projection along the line through  $\mathbf{u}$ . Its matrix has as its columns the images of  $\mathbf{i}$ ,  $\mathbf{j}$ ,  $\mathbf{k}$ . It is therefore

$$\frac{1}{\|\mathbf{v}\|^2} \begin{bmatrix} \mathbf{v}_x \mathbf{v}_x & \mathbf{v}_y \mathbf{v}_x & \mathbf{v}_z \mathbf{v}_x \\ \mathbf{v}_x \mathbf{v}_y & \mathbf{v}_y \mathbf{v}_y & \mathbf{v}_z \mathbf{v}_y \\ \mathbf{v}_x \mathbf{v}_z & \mathbf{v}_y \mathbf{v}_z & \mathbf{v}_z \mathbf{v}_z \end{bmatrix}$$

and the matrix of the complementary projection is

$$\begin{split} I &= \frac{1}{\|\mathbf{v}\|^2} \begin{bmatrix} \mathbf{v}_x \mathbf{v}_x & \mathbf{v}_y \mathbf{v}_x & \mathbf{v}_z \mathbf{v}_x \\ \mathbf{v}_x \mathbf{v}_y & \mathbf{v}_y \mathbf{v}_y & \mathbf{v}_z \mathbf{v}_y \\ \mathbf{v}_x \mathbf{v}_z & \mathbf{v}_y \mathbf{v}_z & \mathbf{v}_z \mathbf{v}_z \end{bmatrix} \\ &= \frac{1}{\|\mathbf{v}\|^2} \begin{bmatrix} \mathbf{v}_x \mathbf{v}_x + \mathbf{v}_y \mathbf{v}_y + \mathbf{v}_z \mathbf{v}_z & 0 & 0 \\ 0 & \mathbf{v}_x \mathbf{v}_x + \mathbf{v}_y \mathbf{v}_y + \mathbf{v}_z \mathbf{v}_z & 0 \\ 0 & 0 & \mathbf{v}_x \mathbf{v}_x + \mathbf{v}_y \mathbf{v}_y + \mathbf{v}_z \mathbf{v}_z \end{bmatrix} - \frac{1}{\|\mathbf{v}\|^2} \begin{bmatrix} \mathbf{v}_x \mathbf{v}_x & \mathbf{v}_y \mathbf{v}_x & \mathbf{v}_z \mathbf{v}_x \\ \mathbf{v}_x \mathbf{v}_y & \mathbf{v}_y \mathbf{v}_y & \mathbf{v}_z \mathbf{v}_y \\ \mathbf{v}_x \mathbf{v}_z & \mathbf{v}_y \mathbf{v}_z & \mathbf{v}_z \mathbf{v}_z \end{bmatrix} \\ &= \frac{1}{\|\mathbf{v}\|^2} \begin{bmatrix} \mathbf{v}_y \mathbf{v}_y + \mathbf{v}_z \mathbf{v}_z & -\mathbf{v}_y \mathbf{v}_x & -\mathbf{v}_z \mathbf{v}_x \\ -\mathbf{v}_x \mathbf{v}_y & \mathbf{v}_x \mathbf{v}_x + \mathbf{v}_z \mathbf{v}_z & -\mathbf{v}_z \mathbf{v}_y \\ -\mathbf{v}_x \mathbf{v}_z & -\mathbf{v}_y \mathbf{v}_z & \mathbf{v}_x \mathbf{v}_x + \mathbf{v}_y \mathbf{v}_y \end{bmatrix} \end{split}$$

There is one other formula involving projections which we shall need later.

**Proposition.** For any 3D vectors u and v

 $u \times (v \times u)$ 

is equal to  $||u||^2$  times the projection of v onto the plane perpendicular to u.

For the proof, we may as well divide by  $||u||^2$ , and can assume that ||u|| = 1. If v has the same direction as u then  $u \times (v \times u)$  vanishes, as does the projection. If v is perpendicular to u then  $v \times u$  is equal to v rotated by  $-90^\circ$  around u, and u crossed with this in turn rotates it back to v. Thus also agrees with the projection. Since both the expression  $u \times (v \times u)$  and the projection of v are linear in v, this proves the claim.

This also follows from the more general formula

$$u \times (v \times w) = (u \bullet w)v - (u \bullet v)w$$
.

The triple product is perpendicular to both u and to  $v \times w$ . Since it is perpendicular to  $v \times w$  it must lie in the plane containing v and w, hence will be a linear combination of v and w. The formula just finds the coefficients of this linear combination explicitly. To prove it, write v as a sum of two components  $v_0$ and  $v_{\perp}$ , the first parallel to w and the second perpendicular to it. It suffices to deal with each component separately. For  $v_0 = cw$  the formula asserts that 0 = 0. Thus we may as well assume v is perpendicular to w. We amy also divide both sides by ||v|| and ||w|| and hence may assume v and w to be of length 1 as well as perpendicular. In that case  $v \times w$  also has length 1 and makes up a rectangular frame together with vand w. We may choose these three vectors as basis. In this case the calculation is very simple.