

Lior Silberman's Math 223: Problem Set 3 (due 2/2/2022)**Practice problems (recommended, but do not submit)**

Section 1.6, Problems 1 (except (g)), 2-5, 7,8, 11,12, 22*, 24*.

M1. (§1.6 E8) Let $W = \{\underline{x} \in \mathbb{R}^5 \mid \sum_{i=1}^5 x_i = 0\}$ be the set of vectors in \mathbb{R}^5 whose co-ordinates sum to zero. It is a subspace (but you don't have to check this). The following 8 vectors span W (you don't have to check that either). Find a subset of them which forms a basis for W . $\underline{u}_1 = (2, -3, 4, -5, 2)$, $\underline{u}_2 = (-6, 9, -12, 15, -6)$, $\underline{u}_3 = (3, -2, 7, -9, 1)$, $\underline{u}_4 = (2, -8, 2, -2, 6)$, $\underline{u}_5 = (-1, 1, 2, 1, -3)$, $\underline{u}_6 = (0, -3, -18, 9, 12)$, $\underline{u}_7 = (1, 0, -2, 3, -2)$, $\underline{u}_8 = (2, -1, 1, -9, 7)$.

M2. Find a basis for the subspace $\{\underline{x} \in \mathbb{R}^4 \mid x_1 + 3x_2 - x_3 = 0\}$ of \mathbb{R}^4 . What is the dimension?

Basis and dimension

1. Recall the space $M_n(\mathbb{R})$ of $n \times n$ matrices: each element is a square $n \times n$ array of real numbers, with addition and scalar multiplication entrywise. For $A \in M_n(\mathbb{R})$ define its *transpose* A^T by reflecting along the main diagonal: $(A^T)_{ij} = A_{ji}$. For example $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}^T = \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$. Call a matrix A *symmetric* if $A^T = A$ (for example $\begin{pmatrix} 2 & 3 \\ 3 & 4 \end{pmatrix}$ is symmetric but $\begin{pmatrix} 1 & 2 \\ 3 & 1 \end{pmatrix}$ isn't). The set of symmetric matrices $S \subset M_n(\mathbb{R})$ is a subspace (we'll prove this later). Find a basis for this space and compute its dimension.

*2. Let $\mathbb{R}(x)$ be the space of functions of the form $\frac{f}{g}$ where $f, g \in \mathbb{R}[x]$ are polynomials such that $g \neq 0$. $\mathbb{R}(x)$ is called "the field of rational functions in one variable, and has the same relation to the ring of polynomials $\mathbb{R}[x]$ that the rational numbers \mathbb{Q} have to the ring of integers \mathbb{Z} . We will consider $\mathbb{R}(x)$ as a real vector space.

(a) Show that $\frac{1}{1-x} \in \mathbb{R}(x)$ is linearly independent of the set $\{x^k\}_{k=0}^\infty \subset \mathbb{R}(x)$.

RMK It's true that $\sum_{k=0}^\infty x^k = \frac{1}{1-x}$ holds on the interval $(-1, 1)$, but don't forget that the summation symbol on the left *does not stand* for repeated addition. Rather, it stands for a kind of limit.

(b) Show that the subset $\{\frac{1}{x-a}\}_{a \in \mathbb{R}} \subset \mathbb{R}(x)$ is linearly independent.

RMK The vector space $\mathbb{R}[x]$ has countable dimension, but by part (b) the dimension of $\mathbb{R}(x)$ as a real vector space is at least the cardinality of the continuum. In fact there is equality, because the cardinality of all of $\mathbb{R}(x)$ is that of the continuum.

Linear Functionals

Fix a vector space V . A *linear functional* on V is a map $\varphi: V \rightarrow \mathbb{R}$ such that for all $a, b \in \mathbb{R}$ and $\underline{u}, \underline{v} \in V$, $\varphi(a\underline{v} + b\underline{u}) = a\varphi(\underline{v}) + b\varphi(\underline{u})$. Let $V^* \stackrel{\text{def}}{=} \{\varphi: V \rightarrow \mathbb{R} \mid \varphi \text{ is a linear functional}\}$ be the set of linear functionals on V (V^* is the vector space *dual* to V , in short the *dual space*).

3. (The basic examples)

(a) Show that $\varphi \left(\begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = 5x - y - 4z$ defines a linear functional on \mathbb{R}^3 .

- (b) Let φ be a linear functional on \mathbb{R}^2 . Show that $\varphi\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = x \cdot \varphi\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) + y \cdot \varphi\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right)$, and conclude that every linear functional on \mathbb{R}^2 is of the form $\varphi\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = ax + by$ for some $a, b \in \mathbb{R}$.

SUPP Construct an identification of $(\mathbb{R}^n)^*$ with \mathbb{R}^n , generalizing part (b).

- (c) Fix a set X and a point $x \in X$. Define $e_x: \mathbb{R}^X \rightarrow \mathbb{R}$ by $e_x(f) = f(x)$ (this is called the “evaluation map”). Show that e_x is a linear functional.

4. Show that V^* is a subspace of \mathbb{R}^V , hence a vector space.

A Linear Transformation

In this problem our notation follows conventions from physics. Thus v will be a numerical parameter rather than a vector, and we write the coordinates of a vector in \mathbb{R}^2 as $\begin{pmatrix} x \\ t \end{pmatrix}$ rather than $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$.

5. In the course of his researches on electromagnetism, Henri Poincaré wrote down the following map $L_v: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which he called the “Lorentz transformation”:

$$L_v \begin{pmatrix} x \\ t \end{pmatrix} \stackrel{\text{def}}{=} \gamma_v \cdot \begin{pmatrix} x - vt \\ t - vx \end{pmatrix}.$$

Here v is a real parameter such that $|v| < 1$ and γ_v is also a number, defined by $\gamma_v = (1 - v^2)^{-1/2}$.

- (a) Suppose $v = 0.6$ so that $\gamma_v = (1 - 0.6^2)^{-1/2} = 1.25$. Calculate $L_v \begin{pmatrix} 3 \\ 2 \end{pmatrix}$, $L_v \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ and $L_v \begin{pmatrix} 2 \\ 3 \end{pmatrix}$. Check that $L_v \begin{pmatrix} 2 \\ 3 \end{pmatrix} = L_v \begin{pmatrix} 3 \\ 2 \end{pmatrix} + L_v \begin{pmatrix} -1 \\ 1 \end{pmatrix}$.

- (b) Show that L_v is a linear transformation.

- (c) (“Relativistic addition of velocities”) Let $v, v' \in (-1, 1)$ be two parameters. Show that $L_v \circ L_{v'} = L_u$ for $u = \frac{v+v'}{1+vv'}$. It is a fact that if $v, v' \in (-1, 1)$ then $\frac{v+v'}{1+vv'} \in (-1, 1)$ as well.

Hint: Start by showing $\gamma_v \gamma_{v'} = \frac{\gamma_u}{1+vv'}$.

RMK If $g: A \rightarrow B$ and $f: B \rightarrow C$ are functions then $f \circ g$ denotes their *composition*, the function $f \circ g: A \rightarrow C$ such that $(f \circ g)(a) = f(g(a))$ for all $a \in A$.

Extra credit

- C1. Let V be a vector space and let $W_1, W_2 \subset V$ be finite-dimensional subspaces.

- (a) Show that $\dim(W_1 + W_2) \leq \dim W_1 + \dim W_2$.

- (**b) Show that $\dim(W_1 + W_2) + \dim(W_1 \cap W_2) = \dim W_1 + \dim W_2$.

Hint Let A, B be finite sets. Then the “inclusion-exclusion” formula states $\#A + \#B = \#(A \cup B) + \#(A \cap B)$

- C2. For a vector space V and a set X endow V^X with the structure of a vector space (check the axioms!). When U, V are vector space show that the set of linear maps $\text{Hom}_{\mathbb{R}}(U, V) = \{f: U \rightarrow V \mid f \text{ is linear}\} \subset V^U$ is a subspace.

- C3. (a) Let V be a vector space of dimension r over the finite field \mathbb{F}_p . Show that $\#V = p^r$.
 (b) Combine problems C2, C3 from PS1 and part (a) to show that every finite field has p^r elements for some prime p and positive integer r .

Supplementary problems

- A. Let V be a vector space and let $\varphi \in V^*$ be non-zero.
- (a) Show that $\text{Ker } \varphi \stackrel{\text{def}}{=} \{\underline{v} \in V \mid \varphi(\underline{v}) = 0\}$ is a subspace.
 - (*b) Show that there is $\underline{v} \in V$ satisfying $\varphi(\underline{v}) = 1$.
 - (**c) Let B be a basis of $\text{Ker } \varphi$, and let $\underline{v} \in V$ be as in part (b). Show that $B \cup \{\underline{v}\}$ is a basis of V .
- RMK If V is finite-dimensional this shows: $\dim V = \dim \text{Ker } \varphi + 1$. In general we say that $\text{Ker } \varphi$ is of *codimension 1*.
- B. Let V be a vector space, W a subspace. Let $B \subset W$ be a basis for W and let $C \subset V$ be disjoint from B and such that $B \cup C$ is a basis for V (that is, we extend B until we get a basis for V).
- (a) Show that $\{\underline{v} + W\}_{\underline{v} \in C}$ is a basis for the quotient vector space V/W (V/W is defined in the supplement to PS2).
 - (b) Show that $\dim W + \dim(V/W) = \dim V$.

The following problem requires some background in set theory.

- C. Let V be a vector space, and let B, C be a bases of V .
- (a) Suppose one of B, C is finite, Show that the other is finite and that they have the same size.
 - We may therefore assume both B, C are infinite.
 - (b) For a finite subset $A \subset B$ show that $C \cap \text{Span}(A)$ is finite.
 - Let $\mathcal{F}_B, \mathcal{F}_C$ be the sets of finite subsets of B, C respectively, and let $f: \mathcal{F}_B \rightarrow \mathcal{F}_C$ be the function $f(A) = C \cap \text{Span}(A)$.
 - (c) Show that the image of f covers C (in symbols, $\bigcup f(\mathcal{F}_B) = C$).
 - (d) Show that the cardinality of the image of f is at least that of C .
 - (e) Show that $|B| \geq |C|$. Conclude that $|B| = |C|$, in other words that infinite-dimensional vector spaces also have well-defined dimensions.